

HW 2 Solution

Section 2.1.

#2. $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 2x_2 \\ 3x_3 \\ x_1 \end{bmatrix} = \begin{bmatrix} 0 & 2 & 0 \\ 0 & 0 & 3 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ Use Fact 2.1.2.

T can be represented by the matrix $\begin{bmatrix} 0 & 2 & 0 \\ 0 & 0 & 3 \\ 1 & 0 & 0 \end{bmatrix}$. So it is linear.

#4. $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} 9 & 3 & -3 \\ 2 & -9 & 1 \\ 4 & -9 & -2 \\ 5 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \Rightarrow A = \begin{bmatrix} 9 & 3 & -3 \\ 2 & -9 & 1 \\ 4 & -9 & -2 \\ 5 & 1 & 5 \end{bmatrix}$. Use Fact 2.1.2.

#6. $T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 + 4x_2 \\ 2x_1 + 5x_2 \\ 3x_1 + 6x_2 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$. So it is linear. & $T=A = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$.

#8. $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + 7x_2 \\ 3x_1 + 20x_2 \end{bmatrix} = \begin{bmatrix} 1 & 7 \\ 3 & 20 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \Rightarrow$ let $\begin{bmatrix} 1 & 7 & | & 1 & 0 \\ 3 & 20 & | & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 7 & | & 1 & 0 \\ 0 & -1 & | & -3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 7 & | & 1 & 0 \\ 0 & 1 & | & 3 & -1 \end{bmatrix}$
 $\rightarrow \begin{bmatrix} 1 & 0 & | & -20 & 7 \\ 0 & 1 & | & 3 & -1 \end{bmatrix}$ So the inverse $T^{-1} = \begin{bmatrix} -20 & 7 \\ 3 & -1 \end{bmatrix}$.

or $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -20 & 7 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} -20y_1 + 7y_2 \\ 3y_1 - y_2 \end{bmatrix}$.

(You can use the formulas of 2×2 inverse matrices).

#14. a. $\det = 2k - 15 \neq 0$ iff A is invertible. So if $k \neq \frac{15}{2}$, it is invertible.

b. By formula, $\det(A)$ must divide 2, 3, 5, & k. to have integer entries. So it must divide the greatest common divisor of 2, 3, 5 & k. First, since the greatest common divisor of 2, 3 & 5 is 1, $\det(A) = 2k - 15$ must divide 1 or -1. So it divides k. anyway.

So solve $2k - 15 = 1$ & $-1 \Rightarrow \boxed{k=8 \text{ or } k=7}$.

#10. $\begin{bmatrix} 1 & 2 \\ 4 & 9 \end{bmatrix}^{-1} = \frac{1}{9-8} \begin{bmatrix} 9 & -2 \\ -4 & 1 \end{bmatrix} = \begin{bmatrix} 9 & -2 \\ -4 & 1 \end{bmatrix}$ or you can try $\begin{bmatrix} 1 & 2 & | & 1 & 0 \\ 4 & 9 & | & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & | & 9 & -2 \\ 0 & 1 & | & -4 & 1 \end{bmatrix}$.

#20. $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \vec{e}_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \vec{e}_2$ & $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \vec{e}_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \vec{e}_1$, So it is a reflection about the

(line $y=x$, since $\vec{e}_1 \xrightarrow{T} \vec{e}_2$ & $\vec{e}_2 \xrightarrow{T} \vec{e}_1$).



#32. A is "scaling" $\Rightarrow A = \begin{bmatrix} 3 & 0 & 0 & \dots & 0 \\ 0 & 3 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & \dots & 3 \end{bmatrix}_{n \times n}$.

Section 2.2.

#2. $\begin{bmatrix} \cos 60^\circ & -\sin 60^\circ \\ \sin 60^\circ & \cos 60^\circ \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$.

#6. a unit vector in $L = \begin{bmatrix} \frac{2}{3} \\ \frac{1}{3} \\ \frac{2}{3} \end{bmatrix}$. Use $\text{Proj}_L(\vec{x}) = (\vec{x} \cdot \vec{u}) \vec{u}$ (Def. 2.2.1) Recall

So $\text{Proj}_L\left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}\right) = \left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} \frac{2}{3} \\ \frac{1}{3} \\ \frac{2}{3} \end{bmatrix}\right) \begin{bmatrix} \frac{2}{3} \\ \frac{1}{3} \\ \frac{2}{3} \end{bmatrix} = \frac{5}{3} \begin{bmatrix} \frac{2}{3} \\ \frac{1}{3} \\ \frac{2}{3} \end{bmatrix} = \begin{bmatrix} \frac{10}{9} \\ \frac{5}{9} \\ \frac{10}{9} \end{bmatrix}$.

#8. $\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \vec{e}_1 = \begin{bmatrix} 0 \\ -1 \end{bmatrix} = -\vec{e}_2$, $\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \vec{e}_2 = \begin{bmatrix} -1 \\ 0 \end{bmatrix} = -\vec{e}_1$.

So this is a reflection about the line $y = -x$.



#10. a unit vector on $L = \begin{bmatrix} \frac{4}{5} \\ \frac{3}{5} \end{bmatrix}$.

$\text{Proj}_L(\vec{x}) = (\vec{x} \cdot \vec{u}) \vec{u} = \begin{bmatrix} u_1^2 & u_1 u_2 \\ u_1 u_2 & u_2^2 \end{bmatrix} \vec{x} = \begin{bmatrix} \frac{16}{25} & \frac{12}{25} \\ \frac{12}{25} & \frac{9}{25} \end{bmatrix} \vec{x}$. ← the answer.

#11. $\text{Ref}_L(\vec{x}) = 2(\vec{x} \cdot \vec{u}) \vec{u} - \vec{x} = \begin{bmatrix} 2u_1^2 - 1 & 2u_1 u_2 \\ 2u_1 u_2 & 1 - 2u_2^2 \end{bmatrix} \vec{x} = \begin{bmatrix} \frac{7}{25} & \frac{24}{25} \\ \frac{24}{25} & -\frac{7}{25} \end{bmatrix} \vec{x}$

#27, #37 Look at the back of the textbook.

#49. \vec{x} is in the unit circle. So $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ satisfies $x_1^2 + x_2^2 = 1$.

Then $T(\vec{x}) = \begin{bmatrix} 5 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5x_1 \\ 2x_2 \end{bmatrix} \stackrel{\text{let}}{=} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$.

Look at $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$ satisfies "which equation". $y_1 = 5x_1$ & $y_2 = 2x_2$.

$\Rightarrow x_1 = \frac{y_1}{5}$, $x_2 = \frac{y_2}{2}$. $\Rightarrow \left(\frac{y_1}{5}\right)^2 + \left(\frac{y_2}{2}\right)^2 = 1$

So $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$ is on the ellipse centered at $(0,0)$, $\frac{y_1^2}{25} + \frac{y_2^2}{4} = 1$.

Section 2.3

#4. $\begin{bmatrix} 1 & 2 & 1 \\ 1 & 3 & 2 \\ 1 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & -2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \text{ref}(A)$. & Square A^{-1} .
 \Rightarrow invertible.

#16. $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 3 & 5 \\ 5 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$, $\det(A) = 3 \cdot 8 - 5 \cdot 5 = 24 - 25 = -1 \neq 0$.
 So it is invertible, & inverse = $-1 \begin{bmatrix} 8 & -5 \\ -5 & 3 \end{bmatrix} = \begin{bmatrix} -8 & 5 \\ 5 & -3 \end{bmatrix}$.

#30. $\begin{bmatrix} 0 & 1 & b \\ -1 & 0 & c \\ -b & -c & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -c \\ 0 & 1 & b \\ 0 & -c & -bc \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -c \\ 0 & 1 & b \\ 0 & 0 & 0 \end{bmatrix}$
 \Downarrow never invertible.

#34. (a) if $a=0$ or $b=0$ or $c=0$, then $\text{ref}(A)$ can't be I_3 .
 So for any nonzero a, b, c , it is invertible, since its ref is I_3 .

& its inverse is $\begin{bmatrix} a & 0 & 0 & | & 1 & 0 & 0 \\ 0 & b & 0 & | & 0 & 1 & 0 \\ 0 & 0 & c & | & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & | & \frac{1}{a} & 0 & 0 \\ 0 & 1 & 0 & | & 0 & \frac{1}{b} & 0 \\ 0 & 0 & 1 & | & 0 & 0 & \frac{1}{c} \end{bmatrix}$ inverse.

(b). Similarly, any nonzero diagonal entries make $n \times n$ diagonal matrices invertible.

#38. $\det = -1 \Rightarrow A^{-1} = \begin{bmatrix} -1 & -k \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & k \\ 0 & -1 \end{bmatrix} = A$. ("interesting")

Section 2.4

#2. $\begin{bmatrix} 1 & -1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 7 & 5 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 4 \\ -8 & -8 \end{bmatrix}$. #4. $\begin{bmatrix} 1 & -1 \\ 0 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 0 \\ 7 & 4 \end{bmatrix}$.

#13. $\begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & k \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \vec{e}_3 \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & k \end{bmatrix} \vec{e}_2 = \vec{e}_3 \begin{bmatrix} b \\ e \\ h \end{bmatrix} = \begin{bmatrix} b \\ e \\ h \end{bmatrix}$

may not be the same

#20. False: since $(A-B)(A+B) = AA + AB - BA - BB = A^2 + AB - BA - B^2 \neq A^2 - B^2$.

Any matrices A & B such that $AB \neq BA$ show a counterexample to this statement.

#22. False: cause this implies $AB = BA$ which may not be true.

#23. True: prove it: $(ABA^{-1})^3 = \underbrace{(ABA^{-1})(ABA^{-1})(ABA^{-1})}_{I_n} = AB \underbrace{I_n}_B I_n BA^{-1} = ABBA^{-1} = \underbrace{(ABA^{-1})^3}$.

#28. $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \neq O_2 \Rightarrow A^2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$.