

Sec 7.3.

#4. $A = \begin{bmatrix} 0 & -1 \\ 1 & 2 \end{bmatrix}$ $f_A(\lambda) = \lambda^2 - 2\lambda + 1 = (\lambda - 1)^2 \Rightarrow \lambda = 1$ with a.m. = 2.

$E_1 = \ker \begin{bmatrix} 0-1 & -1 \\ 1 & 2-1 \end{bmatrix} = \ker \begin{bmatrix} -1 & -1 \\ 1 & 1 \end{bmatrix} = \ker \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} = \text{Span} \left(\begin{bmatrix} 1 \\ -1 \end{bmatrix} \right)$ ← basis.

& g.m. ($\lambda=1$) = 1 \Rightarrow So A has No eigenbasis.

#8. $f_A(\lambda) = \det \begin{bmatrix} 1-\lambda & 1 & 0 \\ 0 & 2-\lambda & 2 \\ 0 & 0 & 3-\lambda \end{bmatrix} = (1-\lambda)(2-\lambda)(3-\lambda) \Rightarrow \lambda = 1, 2, 3$ with each a.m. = 1.

$E_1 = \ker \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{bmatrix} = \ker \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 2 \end{bmatrix} = \ker \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \text{Span} \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right)$ ← basis for $\lambda=1$.

$E_2 = \ker \begin{bmatrix} -1 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 1 \end{bmatrix} = \ker \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \text{Span} \left(\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right)$ ← basis for $\lambda=2$.

$E_3 = \ker \begin{bmatrix} -2 & 1 & 0 \\ 0 & -1 & 2 \\ 0 & 0 & 0 \end{bmatrix} = \ker \begin{bmatrix} 1 & -\frac{1}{2} & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} = \ker \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix} = \text{Span} \left(\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right)$ ← basis for $\lambda=3$.

Since A has 3 distinct eigenvalues, A has an eigenbasis $\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right)$.

#14. $f_A(\lambda) = \det \begin{bmatrix} 1-\lambda & 0 & 0 \\ -5 & -\lambda & 2 \\ 0 & 0 & 1-\lambda \end{bmatrix} = (1-\lambda) \det \begin{bmatrix} -\lambda & 2 \\ 0 & 1-\lambda \end{bmatrix} = (1-\lambda)(-\lambda)(1-\lambda) = -\lambda(1-\lambda)^2$

$\Rightarrow \lambda = 0$ with a.m. = 1 & $\lambda = 1$ with a.m. = 2.

$E_0 = \det \begin{bmatrix} 1 & 0 & 0 \\ -5 & 0 & 2 \\ 0 & 0 & 1 \end{bmatrix} = \det \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 1 \end{bmatrix} = \det \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \text{Span} \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right)$ ← basis for $\lambda=0$. \Rightarrow g.m.(0) = 1

$E_1 = \det \begin{bmatrix} 0 & 0 & 0 \\ -5 & -1 & 2 \\ 0 & 0 & 0 \end{bmatrix} = \text{Span} \left(\begin{bmatrix} 1 \\ -5 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} \right)$ ← basis for $\lambda=1$. \Rightarrow g.m.(1) = 2

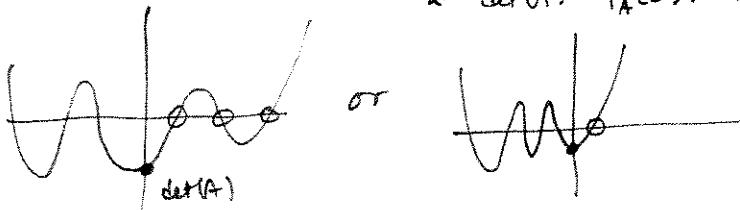
$1 + 2 = 3 = \dim(\mathbb{R}^3)$. \Rightarrow A has an eigenbasis $\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -5 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} \right)$.

#21. $\begin{bmatrix} 1 \\ 2 \end{bmatrix} \in \ker \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} - 1 \cdot I_2 \right)$ & $\begin{bmatrix} 2 \\ 3 \end{bmatrix} \in \ker \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} - 2 \cdot I_2 \right)$

$\Rightarrow \begin{pmatrix} a-1 & b \\ c & d-1 \end{pmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ & $\begin{pmatrix} a-2 & b \\ c & d-2 \end{pmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow a=5, b=-2, c=b, d=-2.$

So $A = \begin{bmatrix} 5 & -2 \\ 6 & -2 \end{bmatrix}$

#26. $f_A(\lambda) = (-\lambda)^6 + \text{tr}(A)(-\lambda)^5 + \dots + \det(A) = \lambda^6 - \text{tr}(A)\lambda^5 + \dots + \det(A)$ ← negative.
& $\det(A) = f_A(0)$. i.e. this is the y-intercept of $y = f_A(\lambda)$.



So $f_A(\lambda)$ has a root on the positive x-axis.
So A has at least one positive eigenvalue.

See 7.3 (continued)

$$\#27. \quad f_A(\lambda) = (-\lambda)^2 + \text{tr}(A)(-\lambda) + \det(A) = \lambda^2 - 5\lambda + 6 = (\lambda - 2)(\lambda - 3).$$

So $\lambda = 2$ & 3 , with a.m. = 1 each.

$$\#28. \quad f_{J_n(k)}(\lambda) = \det \begin{bmatrix} k-\lambda & 1 & 0 & \dots & 0 \\ 0 & k-\lambda & 1 & \dots & 0 \\ \vdots & & & & \\ 0 & \dots & \dots & \dots & k-\lambda \end{bmatrix} = (k-\lambda)^n.$$

$\Rightarrow \lambda = k$ with a.m. = n .

$$E_k = \ker(J_n(k) - kI_n) = \ker \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & & & & \\ 0 & \dots & \dots & \dots & 0 \end{bmatrix} = \text{Span} \left(\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right) = \text{Span}(\vec{e}_1).$$

So $\lambda = k$ has g.m. = 1. (So $J_n(k)$ has no eigenbasis.)

#36. No! since they have different traces.