

8. $\det(A - \lambda I) = \det \begin{bmatrix} 1-\lambda & 1 & 0 & 1 \\ 0 & 1-\lambda & 1 & 1 \\ 0 & 0 & 2-\lambda & 1 \\ 0 & 0 & 0 & 2-\lambda \end{bmatrix} = (1-\lambda)^2(2-\lambda)^2$

(5)

$\lambda=1$:

$$\begin{array}{cccc|c} 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ \hline 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

$v_4=0$
 $v_3=0$
 $v_2=0$
 $v_1=t$

$\vec{v} = t \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

$\lambda=1$ E-space = $\text{span}(\vec{e}_1)$

$\lambda=2$:

$$\begin{array}{cccc|c} -1 & 1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

$v_4=0$
 $v_3=t$
 $v_2=t$
 $v_1=t$

$\vec{v} = t \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}$

$\lambda=2$ E-space = $\text{span}\left\{\begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}\right\}$

only 2 lin. ind. eigenvectors - need 4!

A is NOT diagonalizable

7.1 3. $t^2 x'' + tx' + (t^2 - 1)x = 0$

$x_1 = x$
 $x_2 = x'$

$\begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} x_2 \\ -\frac{1}{t}x_2 + \frac{(1-t^2)}{t^2}x_1 \end{bmatrix}$

$x_2' = x'' = -\frac{1}{t}x' + \frac{(1-t^2)}{t^2}x$

8. $x'' + 3x' + 4x - 2y = 0$
 $y'' + 2y' - 3x + y = \cos t$



let $x_1 = x$
 $x_2 = x'$
 $y_1 = y$
 $y_2 = y'$

$\begin{bmatrix} x_1' \\ x_2' \\ y_1' \\ y_2' \end{bmatrix} = \begin{bmatrix} x_2 \\ -4x_1 - 3x_2 + 2y_1 \\ y_2 \\ 3x_1 - y_1 - 2y_2 + \cos t \end{bmatrix}$

18. $x' = -y$
 $y' = 10x - 7y$

$\begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 2 \\ -7 \end{bmatrix}$

this one can be converted into a 2nd order eqn:

$x' = -y$
so $x'' = -y' = -10x + 7y$

$x'' + 7x' + 10x = 0$

$x = e^{rt}$: $r^2 + 7r + 10 = 0$

$(r+5)(r+2) = 0$; $r = -2, -5$

$x = c_1 e^{-5t} + c_2 e^{-2t}$

$y = -x' = 5c_1 e^{-5t} + 2c_2 e^{-2t}$

$x(0) = 2 = c_1 + c_2$

$y(0) = -7 = 5c_1 + 2c_2$

$x_2' = x'' = -3x' - 4x + 2y$
 $y_2' = y'' = -2y' + 3x - y + \cos t$

$c_1 = \frac{\begin{vmatrix} 2 & 1 \\ -7 & 2 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 5 & 2 \end{vmatrix}} = \frac{-11}{-3} = \frac{11}{3}$

$c_2 = \frac{\begin{vmatrix} 1 & 2 \\ 5 & -7 \end{vmatrix}}{-3} = \frac{-17}{-3} = \frac{17}{3}$

$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \frac{11}{3} e^{-5t} \begin{bmatrix} 1 \\ 5 \end{bmatrix} + \frac{17}{3} e^{-2t} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

Note $\begin{cases} \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 10 & -7 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \\ \begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 2 \\ -7 \end{bmatrix} \end{cases}$

Could you do this using evals/evecs

97.1 21. a)

11: $\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} y \\ -x \end{bmatrix}$

is one we did in class:

$$x'' = y' = -x \quad x'' + x = 0$$

$$x = C \cos(t - \alpha)$$

$$y = x' = -C \sin(t - \alpha)$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = C \begin{bmatrix} \cos(t - \alpha) \\ -\sin(t - \alpha) \end{bmatrix}$$

$$\text{so } x^2 + y^2 = C^2 (\cos^2 + \sin^2) = C^2$$

so $\begin{bmatrix} x \\ y \end{bmatrix}$ lies on circle of radius C

shortcut:

$$\frac{d}{dt} (x^2 + y^2)$$

$$= 2xx' + 2yy'$$

$$= 2x(y) + 2y(-x) \quad (\text{from sys})$$

$$= 0! \quad \text{so } x^2 + y^2 \text{ is const.}$$

21b). 12. $x' = y$
 $y' = x$

$$x'' = y' = x$$

$$x'' - x = 0$$

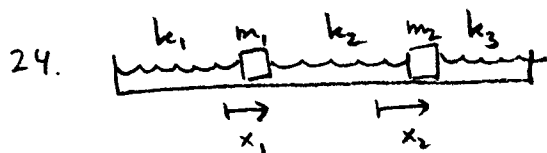
$$x = e^{rt} \quad r^2 - 1 = 0; \quad r = \pm 1$$

$$x = c_1 e^t + c_2 e^{-t}$$

$$y = x' = c_1 e^t - c_2 e^{-t}$$

$$\begin{aligned} x^2 - y^2 &= [c_1 e^t + c_2 e^{-t}]^2 - [c_1 e^t - c_2 e^{-t}]^2 \\ &= e^{2t} (c_1^2 - c_2^2) + e^{-2t} (c_2^2 - c_1^2) \\ &\quad + 1 (2c_1 c_2 + 2c_1 c_2) \end{aligned} \quad \left. \vphantom{\begin{aligned} x^2 - y^2 &= [c_1 e^t + c_2 e^{-t}]^2 - [c_1 e^t - c_2 e^{-t}]^2 \\ &= e^{2t} (c_1^2 - c_2^2) + e^{-2t} (c_2^2 - c_1^2) \\ &\quad + 1 (2c_1 c_2 + 2c_1 c_2) \end{aligned}} \right\} = 4c_1 c_2 = \text{const!}$$

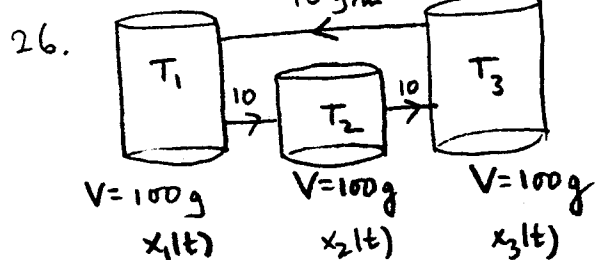
shortcut: $\frac{d}{dt} (x^2 - y^2) = 2xx' - 2yy'$
 $= 2x(y) - 2y(x)$,
from D.E.
 $= 0$.
so $x^2 - y^2 = \text{const.}$



$$m_1 x_1'' = k_2 (x_2 - x_1) - k_1 x_1 = x_1 (-k_1 - k_2) + x_2 k_2$$

$$m_2 x_2'' = -k_2 (x_2 - x_1) - k_3 x_2 = x_1 k_2 + x_2 (-k_2 - k_3)$$

why?



each rate is 10 g/min

$$\frac{dx_1}{dt} = 10 \left(\frac{x_3}{100} \right) - 10 \left(\frac{x_1}{100} \right)$$

Similarly: $\frac{dx_2}{dt} = 10 \frac{x_1}{100} - 10 \frac{x_2}{100}$

$$\frac{dx_3}{dt} = 10 \frac{x_2}{100} - 10 \frac{x_3}{100}$$

if you multiply each eqn by 10 you get the system in the book.

Math 2250-4

HW due Weds 11/21

7.2 5, 9, 10, 13, 14, 16, 21, 23, 25

7.3 3, 4, 6, 13, 14, 25, 30, 32

$$9. \begin{aligned} x' &= 3x - 4y + z + t \\ y' &= x - 3z + t^2 \\ z' &= 6y - 7z + t^3 \end{aligned}$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix}' = \begin{bmatrix} 3 & -4 & 1 \\ 1 & 0 & -3 \\ 0 & 6 & -7 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} + \begin{bmatrix} t \\ t^2 \\ t^3 \end{bmatrix}$$

$$10. \begin{aligned} x' &= tx - y + e^t z \\ y' &= 2x + t^2 y - z \\ z' &= e^{-t} x + 3ty + t^3 z \end{aligned}$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix}' = \begin{bmatrix} t & -1 & e^t \\ 2 & t^2 & -1 \\ e^{-t} & 3t & t^3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$14. \vec{x}' = \begin{bmatrix} -3 & 2 \\ -3 & 4 \end{bmatrix} \vec{x} \quad \vec{x}_1 = \begin{bmatrix} e^{3t} \\ 3e^{3t} \end{bmatrix} \quad \vec{x}_1' = \begin{bmatrix} 3e^{3t} \\ 9e^{3t} \end{bmatrix}$$

$$A\vec{x}_1 = \begin{bmatrix} -3 & 2 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} e^{3t} \\ 3e^{3t} \end{bmatrix} = \begin{bmatrix} (-3+6)e^{3t} \\ (-3+12)e^{3t} \end{bmatrix} = \begin{bmatrix} 3e^{3t} \\ 9e^{3t} \end{bmatrix} \checkmark$$

$$\vec{x}_2 = \begin{bmatrix} 2e^{-2t} \\ e^{-2t} \end{bmatrix} \quad \vec{x}_2' = \begin{bmatrix} -4e^{-2t} \\ -2e^{-2t} \end{bmatrix}$$

$$A\vec{x}_2 = \begin{bmatrix} -3 & 2 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} 2e^{-2t} \\ e^{-2t} \end{bmatrix} = \begin{bmatrix} e^{-2t}(-6+2) \\ e^{-2t}(-6+4) \end{bmatrix} = \begin{bmatrix} -4e^{-2t} \\ -2e^{-2t} \end{bmatrix} \checkmark$$

$$W = \left| \vec{x}_1 \quad \vec{x}_2 \right| = \begin{vmatrix} e^{3t} & 2e^{-2t} \\ 3e^{3t} & e^{-2t} \end{vmatrix}$$

$$= e^{3t} e^{-2t} \begin{vmatrix} 1 & 2 \\ 3 & 1 \end{vmatrix} = e^t (-5) \neq 0 \text{ so solns are lin ind.}$$

↑ from 1st col
↑ from 2nd col

$$\text{so } \vec{x}_H(t) = c_1 e^{3t} \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$16. \vec{x}' = \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} \vec{x}$$

$$\vec{x}_1 = e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad \vec{x}_2 = e^{2t} \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad ; \quad \vec{x}_2' = 2e^{2t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$\vec{x}_1' = 3e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$A\vec{x}_2 = \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} e^{2t} \begin{bmatrix} 1 \\ -2 \end{bmatrix} = e^{2t} \begin{bmatrix} 2 \\ -4 \end{bmatrix} = 2e^{2t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$A\vec{x}_1 = \begin{bmatrix} 4 & 1 \\ -2 & 1 \end{bmatrix} e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = e^{3t} \begin{bmatrix} 3 \\ -3 \end{bmatrix} = 3e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$W = \det \left[e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}, e^{2t} \begin{bmatrix} 1 \\ -2 \end{bmatrix} \right] = e^{3t} e^{2t} \begin{vmatrix} 1 & 1 \\ -1 & -2 \end{vmatrix} = e^{5t} (-1) \neq 0 \text{ so l.i.v.}$$

$$\vec{x}_H(t) = c_1 e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

(2)

$$\vec{x}' = \begin{bmatrix} -8 & -11 & -2 \\ 6 & 9 & 2 \\ -6 & -6 & 1 \end{bmatrix} \vec{x}$$

$$\vec{x}_1 = e^{-2t} \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix}$$

$$\vec{x}_1' = -2e^{-2t} \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix}$$

$$A\vec{x}_1 = \begin{bmatrix} -8 & -11 & -2 \\ 6 & 9 & 2 \\ -6 & -6 & 1 \end{bmatrix} e^{-2t} \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix} = e^{-2t} \begin{bmatrix} -24 + 22 - 4 \\ 18 - 18 + 4 \\ -18 + 12 + 2 \end{bmatrix} = e^{-2t} \begin{bmatrix} -6 \\ 4 \\ -4 \end{bmatrix}$$

$$\vec{x}_2 = e^t \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$\vec{x}_2' = e^t \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$A\vec{x}_2 = \begin{bmatrix} -8 & -11 & -2 \\ 6 & 9 & 2 \\ -6 & -6 & 1 \end{bmatrix} e^t \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} = e^t \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$\vec{x}_3 = e^{3t} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

$$\vec{x}_3' = 3e^{3t} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

$$A\vec{x}_3 = \begin{bmatrix} -8 & -11 & -2 \\ 6 & 9 & 2 \\ -6 & -6 & 1 \end{bmatrix} e^{3t} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} = e^{3t} \begin{bmatrix} 3 \\ -3 \\ 0 \end{bmatrix}$$

$$W = \begin{vmatrix} e^{-2t} \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix} & e^t \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} & e^{3t} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \end{vmatrix} = e^{-2t} e^t e^{3t} \begin{vmatrix} 3 & 1 & 1 \\ -2 & -1 & -1 \\ 2 & 1 & 0 \end{vmatrix} = e^{2t} (-2 - 2 + 2 + 3) = e^{2t} \neq 0$$

$$\text{so } \vec{x}_H(t) = c_1 e^{-2t} \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix} + c_2 e^t \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_3 e^{3t} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

23. refer to #14:

$$c_1 \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 5 \end{bmatrix}$$

$$\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \frac{1}{-5} \begin{bmatrix} 1 & -2 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 5 \end{bmatrix}$$

$$\text{so } \vec{x}_H(t) = 2e^{3t} \begin{bmatrix} 1 \\ 3 \end{bmatrix} - e^{2t} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = -\frac{1}{5} \begin{bmatrix} -10 \\ 5 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

25. refer to 16

$$\begin{bmatrix} 11 \\ -7 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 11 \\ -7 \end{bmatrix}$$

$$\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \frac{1}{-1} \begin{bmatrix} -2 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 11 \\ -7 \end{bmatrix} = \begin{bmatrix} 15 \\ -4 \end{bmatrix}$$

$$\text{so } \vec{x}_H(t) = 15e^{3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix} - 4e^{2t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

3

3 #4) $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} 4 & 1 \\ 6 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

$$|A - \lambda I| = \begin{vmatrix} 4-\lambda & 1 \\ 6 & -1-\lambda \end{vmatrix} = \lambda^2 - 3\lambda - 10 = (\lambda - 5)(\lambda + 2)$$

$$\lambda = 5, -2$$

$\lambda = 5:$

$$\begin{array}{cc|c} -1 & 1 & 0 \\ 6 & -6 & 0 \\ \hline 1 & -1 & 0 \\ 0 & 0 & 0 \end{array}$$

$\vec{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$\vec{z}_1 = e^{5t} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$\lambda = -2$

$$\begin{array}{cc|c} 6 & 1 & 0 \\ 6 & 1 & 0 \\ \hline 6 & 1 & 0 \\ 0 & 0 & 0 \end{array}$$

$\vec{v} = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$

$\vec{z}_2 = e^{-2t} \begin{bmatrix} -1 \\ 6 \end{bmatrix}$

$$\vec{x}_H(t) = c_1 e^{5t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

6) $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} 9 & 5 \\ -6 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

$$|A - \lambda I| = \begin{vmatrix} 9-\lambda & 5 \\ -6 & -2-\lambda \end{vmatrix} = \lambda^2 - 7\lambda + 12 = (\lambda - 4)(\lambda - 3)$$

$$\lambda = 3, 4$$

$\lambda = 3$

$$\begin{array}{cc|c} 6 & 5 & 0 \\ -6 & -5 & 0 \\ \hline 6 & 5 & 0 \\ 0 & 0 & 0 \end{array}$$

$\vec{v} = \begin{bmatrix} -5 \\ 6 \end{bmatrix}$

$\lambda = 4$

$$\begin{array}{cc|c} 5 & 5 & 0 \\ -6 & -6 & 0 \\ \hline 1 & 1 & 0 \\ 0 & 0 & 0 \end{array}$$

$\vec{v} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$$\vec{x}_H(t) = c_1 e^{3t} \begin{bmatrix} -5 \\ 6 \end{bmatrix} + c_2 e^{4t} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\vec{x}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -5 & -1 \\ 6 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \frac{1}{1} \begin{bmatrix} 1 & 1 \\ -6 & -5 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -6 \end{bmatrix}$$

$$\vec{x}(t) = e^{3t} \begin{bmatrix} -5 \\ 6 \end{bmatrix} - 6e^{4t} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

14) $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}' = \begin{bmatrix} 3 & -4 \\ 4 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

$$|A - \lambda I| = \begin{vmatrix} 3-\lambda & -4 \\ 4 & 3-\lambda \end{vmatrix} = (3-\lambda)^2 + 16 = (3-\lambda-4i)(3-\lambda+4i) = 0$$

$$\lambda = 3 \pm 4i$$

$\lambda = 3+4i$

$$\begin{array}{cc|c} -4i & -4 & 0 \\ 4 & -4i & 0 \\ \hline i & 1 & 0 \\ 1 & -i & 0 \\ \hline R_2 & -1 & -i & 0 \\ R_1 & i & 1 & 0 \\ \hline 1 & -i & 0 \\ -iR_1 + R_2 & 0 & 0 & 0 \end{array}$$

$\vec{v} = \begin{bmatrix} i \\ 1 \end{bmatrix}$

$$e^{\lambda t} \vec{v} = e^{(3+4i)t} \begin{bmatrix} i \\ 1 \end{bmatrix}$$

real part is e^{3t}

$$= e^{3t} (\cos 4t + i \sin 4t) \begin{bmatrix} i \\ 1 \end{bmatrix}$$

Im part is another one!

$$= e^{3t} \begin{bmatrix} -\sin 4t \\ \cos 4t \end{bmatrix} + i e^{3t} \begin{bmatrix} \cos 4t \\ \sin 4t \end{bmatrix}$$

$$\vec{x}_H(t) = e^{3t} \left[c_1 \begin{bmatrix} -\sin 4t \\ \cos 4t \end{bmatrix} + c_2 \begin{bmatrix} \cos 4t \\ \sin 4t \end{bmatrix} \right]$$

3 #30

$$\frac{dx_1}{dt} = -10 \frac{x_1}{25} + 10 \frac{x_2}{40}$$

$$\frac{dx_2}{dt} = 10 \frac{x_1}{25} - 10 \frac{x_2}{40}$$

$$\begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} -.4 & .25 \\ .4 & -.25 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 15 \\ 0 \end{bmatrix}$$

$$|A - \lambda I| = \begin{vmatrix} -.4 - \lambda & .25 \\ .4 & -.25 - \lambda \end{vmatrix} = \lambda^2 + .65\lambda + .4(.25) - .4(.25)$$

$$= \lambda(\lambda + .65)$$

$$\lambda = 0: \begin{array}{cc|c} -.4 & .25 & 0 \\ .4 & -.25 & 0 \\ \hline -.40 & .25 & 0 \\ 0 & 0 & 0 \\ \hline -.8 & .5 & 0 \\ 0 & 0 & 0 \end{array}$$

$$\vec{v} = \begin{bmatrix} 5 \\ 8 \end{bmatrix}$$

$$\lambda = -.65$$

$$\begin{array}{cc|c} .25 & .25 & 0 \\ .4 & .4 & 0 \\ \hline 1 & 1 & 0 \\ 0 & 0 & 0 \end{array}$$

$$\vec{v} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

limiting values make sense!

$$\vec{x}(t) = \frac{15}{13} \begin{bmatrix} 5 \\ 8 \end{bmatrix} + \frac{120}{13} e^{-.65t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\vec{x}(t) = c_1 \begin{bmatrix} 5 \\ 8 \end{bmatrix} + c_2 e^{-.65t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\vec{x}(0) = \begin{bmatrix} 15 \\ 0 \end{bmatrix} = \begin{bmatrix} 5 & 1 \\ 8 & -1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix};$$

$$\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = -\frac{1}{13} \begin{bmatrix} -1 & -1 \\ -8 & 5 \end{bmatrix} \begin{bmatrix} 15 \\ 0 \end{bmatrix} = \begin{bmatrix} 15/13 \\ 120/13 \end{bmatrix}$$

#32 r=60

$$\begin{bmatrix} x_1(0) \\ x_2(0) \\ x_3(0) \end{bmatrix} = \begin{bmatrix} 45 \\ 0 \\ 0 \end{bmatrix}$$

$$V_1 = 20, V_2 = 30, V_3 = 60$$

$$\frac{dx_1}{dt} = -60 \frac{x_1}{20}$$

$$\frac{dx_2}{dt} = 60 \frac{x_1}{20} - 60 \frac{x_2}{30}$$

$$\frac{dx_3}{dt} = 60 \frac{x_2}{30} - 60 \frac{x_3}{60}$$

$$\begin{bmatrix} x_1' \\ x_2' \\ x_3' \end{bmatrix} = \begin{bmatrix} -3 & 0 & 0 \\ 3 & -2 & 0 \\ 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

matrix is triangular so evals are -3, -2, -1

$$\lambda = -1$$

$$\lambda = -2$$

$$\vec{v} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$A - \lambda I: \begin{array}{ccc|c} -1 & 0 & 0 & 0 \\ 3 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ \hline 1 & 0 & 0 & 0 \\ 0 & 1 & 1/2 & 0 \\ 0 & 0 & 0 & 0 \end{array}$$

$$\begin{aligned} v_3 &= t \\ v_2 &= -\frac{1}{2}t \\ v_1 &= 0 \end{aligned}$$

$$\vec{v} = \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix}$$

$$\lambda = -3: \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 3 & 1 & 0 & 0 \\ 0 & 2 & 2 & 0 \\ \hline 3 & 0 & -1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ \hline 0 & 0 & -1/3 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array}$$

$$\begin{aligned} v_3 &= t \\ v_2 &= -t \\ v_1 &= \frac{1}{3}t \end{aligned}$$

$$\vec{v} = t \begin{bmatrix} 1/3 \\ -1 \\ 1 \end{bmatrix}$$

$$\vec{v} = \begin{bmatrix} 1/3 \\ -1 \\ 1 \end{bmatrix} \checkmark$$

(6)

$$\text{so } \vec{x}(t) = c_1 e^{-t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix} + c_3 e^{-3t} \begin{bmatrix} 1 \\ -3 \\ 3 \end{bmatrix}$$

$$\vec{x}(0) = \begin{bmatrix} 45 \\ 0 \\ 0 \end{bmatrix} = c_1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ -3 \\ 3 \end{bmatrix}$$

$$\Rightarrow c_3 = 45$$

$$-c_2 - 135 = 0 \quad c_2 = -135$$

$$c_1 - 270 + 35 = 0 \quad c_1 = 135$$

$$\vec{x}(t) = 135 e^{-t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - 135 e^{-2t} \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix} + 45 e^{-3t} \begin{bmatrix} 1 \\ -3 \\ 3 \end{bmatrix}$$

in tank 3, $x_3(t) = 135 e^{-t} - 270 e^{-2t} + 135 e^{-3t}$

Max when $\left(\frac{x_3}{135}\right)'(t) = 0$:

$$-e^{-t} + 4e^{-2t} - 3e^{-3t} = 0$$

$$-1 + 4e^{-t} - 3e^{-2t} = 0$$

$$3e^{-2t} - 4e^{-t} + 1 = 0$$

$$3z^2 - 4z + 1 = 0$$

$$(3z-1)(z-1) = 0$$

$$\uparrow$$

$$t=0$$

$$z = \frac{1}{3}; \quad e^{-t} = \frac{1}{3}$$

$$\text{so } x_3(t) = \frac{135}{3} - \frac{270}{9} + \frac{135}{27} = 45 - 30 + 5$$

$$= 20 \text{ lbs}$$

$$= \underline{\underline{20}} \text{ lbs}$$

> A:=matrix(3,3,[-3,0,0,3,-2,0,0,2,-1]);

$$A := \begin{bmatrix} -3 & 0 & 0 \\ 3 & -2 & 0 \\ 0 & 2 & -1 \end{bmatrix}$$

> eigenvects(A);

[-3, 1, {[1, -3, 1]}], [-1, 1, {[0, 0, 1]}], [-2, 1, {[0, 1, -2]}]

it would
be fine to
use Maple!
"solve"

:=t->135*(exp(-t)-2*exp(-2*t)+exp(-3*t));

x3:=t->135 e^(-t)-270 e^(-2t)+135 e^(-3t)

solve(diff(x3(t),t)=0,t);

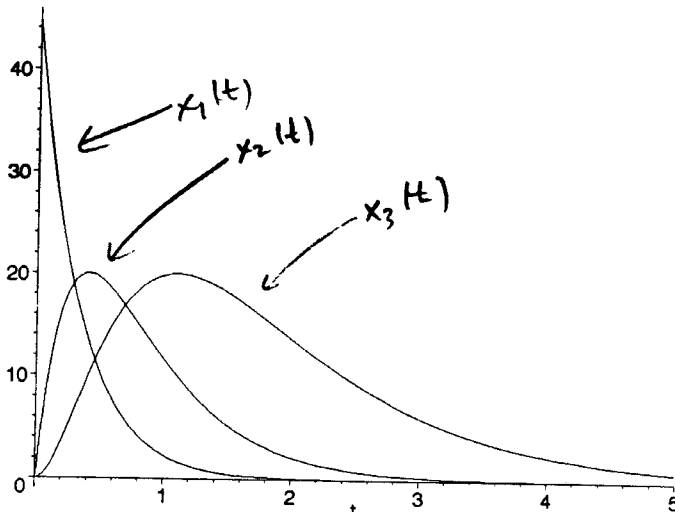
ln(3), 0

3(ln(3));

20

> plot({x1(t),x2(t),x3(t)},t=0..5,color=black,title=
"tank solutes vs time");

tank solutes vs time



(6)

$$\text{so } \vec{x}(t) = c_1 e^{-t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix} + c_3 e^{-3t} \begin{bmatrix} 1 \\ -3 \\ 3 \end{bmatrix}$$

$$\vec{x}(0) = \begin{bmatrix} 45 \\ 0 \\ 0 \end{bmatrix} = c_1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ -3 \\ 3 \end{bmatrix} \Rightarrow \begin{aligned} c_3 &= 45 \\ -c_2 - 135 &= 0 \quad c_2 = -135 \\ c_1 - 270 + 35 &= 0 \quad c_1 = 135 \end{aligned}$$

$$\vec{x}(t) = 135e^{-t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - 135e^{-2t} \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix} + 45e^{-3t} \begin{bmatrix} 1 \\ -3 \\ 3 \end{bmatrix}$$

in tank 3, $x_3(t) = 135e^{-t} - 270e^{-2t} + 135e^{-3t}$

Max when $\left(\frac{x_3}{135}\right)'(t) = 0$:

$$-e^{-t} + 4e^{-2t} - 3e^{-3t} = 0$$

$$-1 + 4e^{-t} - 3e^{-2t} = 0$$

$$3e^{-2t} - 4e^{-t} + 1 = 0$$

$$3z^2 - 4z + 1 = 0$$

$$(3z-1)(z-1) = 0$$

$$\uparrow$$

$$t=0$$

$$z = \frac{1}{3}; \quad e^{-t} = \frac{1}{3}$$

$$\text{so } x_3(t) = \frac{135}{3} - \frac{270}{9} + \frac{135}{27} = 45 - 30 + 5$$

$$= 20 \text{ lbs.}$$

$$\underline{\underline{20 \text{ lbs.}}}$$

$$\begin{aligned} &> A := \text{matrix}(3, 3, [-3, 0, 0, 3, -2, 0, 0, 2, -1]); \\ &A := \begin{bmatrix} -3 & 0 & 0 \\ 3 & -2 & 0 \\ 0 & 2 & -1 \end{bmatrix} \end{aligned}$$

$$> \text{eigenvecs}(A);$$

$$\begin{bmatrix} -3 & 1 & 1 \\ 3 & -1 & -3 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 10 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 1 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

it would
be fine to
use Maple!
"solve"

```
:=t->135*(exp(-t)-2*exp(-2*t)+exp(-3*t));
```

```
x3:=t->135*exp(-t)-270*exp(-2*t)+135*exp(-3*t);
```

```
solve(diff(x3(t),t)=0,t);
```

```
ln(3), 0
```

```
20
```

```
> plot({x1(t), x2(t), x3(t)}, t=0..5, color=black, title=
```

```
  tank solutes vs time);
```

