

## Electrical Circuits

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- Voltage drop formulas of Faraday, Ohm, Coulomb.
- Kirchhoff's laws.
- LRC Circuit equation.
- Electrical-Mechanical Analogy.
- Transient and Steady-state Currents.
- Reactance and Impedance.
- Time lag.
- Electrical Resonance.

## Voltage Drop Formulas

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|----------------------|-----------------------------------------------------------------------------------------------------------------|
| <b>Faraday's Law</b> | $V_L = L \frac{dI}{dt}$ <p><math>L</math> = inductance in henries,<br/><math>I</math> = current in amperes.</p> |
| <b>Ohm's Law</b>     | $V_R = RI$ <p><math>R</math> = resistance in ohms.</p>                                                          |
| <b>Coulomb's Law</b> | $V_C = \frac{Q}{C}$ <p><math>Q</math> = charge in coulombs,<br/><math>C</math> = capacitance in farads.</p>     |

## Kirchhoff's Laws

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The **charge**  $Q$  and **current**  $I$  are related by the equation

$$\frac{dQ}{dt} = I.$$

- **Loop Law:** *The algebraic sum of the voltage drops around a closed loop is zero.*
- **Junction Law:** *The algebraic sum of the currents at a node is zero.*

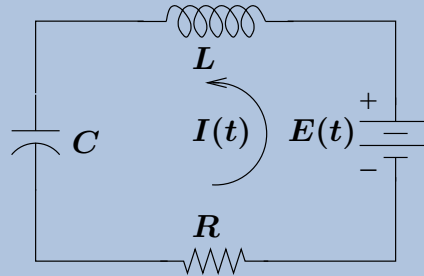
## LRC Circuit Equation in Charge form

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The first law of Kirchhoff implies the RLC circuit equation

$$LQ'' + RQ' + \frac{1}{C}Q = E(t)$$

where inductor  $L$ , resistor  $R$  and capacitor  $C$  are in a single loop having electromotive force  $E(t)$ .



**Figure 1.** An LRC Circuit.

The components are a resistor  $R$ , inductor  $L$ , capacitor  $C$  and emf  $E(t)$ . Current  $I(t)$  is assigned counterclockwise direction, from minus to plus on the emf terminals.

## LRC Circuit Equation in Current Form

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Differentiation of the charge form of the LRC circuit equation

$$LQ'' + RQ' + \frac{1}{C}Q = E(t)$$

gives the current form of the LRC circuit equation

$$LI'' + RI' + \frac{1}{C}I = \frac{dE}{dt}.$$

## Electrical–Mechanical Analogy

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$$\begin{aligned} mx'' + cx' + kx &= F(t), \\ LQ'' + RQ + C^{-1}Q &= E(t). \end{aligned}$$

**Table 1. Electrical–Mechanical Analogy**

| <b>Mechanical System</b> | <b>Electrical System</b>              |
|--------------------------|---------------------------------------|
| Mass $m$                 | Inductance $L$                        |
| Dashpot constant $c$     | Resistance $R$                        |
| Hooke's constant $k$     | Reciprocal capacitance $1/C$          |
| Position $x$             | Charge $Q$ [or Current $I$ ]          |
| External force $F$       | Electromotive force $E$ [or $dE/dt$ ] |

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## Transient and Steady-state Currents

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The theory of mechanical systems leads to electrical results by applying the electrical-mechanical analogy to the LRC circuit equation in current form with  $E(t) = E_0 \sin \omega t$ . We assume  $L$ ,  $R$  and  $C$  positive.

- The solution  $I_h$  of the homogeneous equation  $LI'' + RI' + \frac{1}{C}I = 0$  is a **transient current**, satisfying

$$\lim_{t \rightarrow \infty} I_h(t) = 0.$$

- The non-homogeneous equation  $LI'' + RI' + \frac{1}{C}I = E_0 \omega \cos \omega t$  has a unique periodic solution [**steady-state current**]

$$I_{ss}(t) = \frac{E_0 \cos(\omega t - \alpha)}{\sqrt{R^2 + S^2}}, \quad S \equiv \omega L - \frac{1}{\omega C}, \quad \tan \alpha = \frac{\omega RC}{1 - LC\omega^2}.$$

It is found by the method of undetermined coefficients.

## Reactance and Impedance

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Write

$$I_{ss}(t) = \frac{E_0 \cos(\omega t - \alpha)}{\sqrt{R^2 + S^2}}$$

as

$$I_{ss}(t) = \frac{E_0}{Z} \cos(\omega t - \alpha)$$

where

$Z = \sqrt{R^2 + S^2}$  is called the **impedance**

$S = \omega L - \frac{1}{\omega C}$  is called the **reactance**.



## Time Lag

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The steady-state current  $I_{\text{ss}}(t) \frac{E_0}{Z} \cos(\omega t - \alpha)$  can be written as a sine function using trigonometric identity  $\cos(x - \pi/2) = \sin(x)$  with  $\alpha = \delta + \pi/2$ :

$$I_{\text{ss}}(t) = \frac{E_0}{Z} \sin(\omega t - \delta), \quad \tan \delta = \frac{LC\omega^2 - 1}{\omega RC} = \frac{S}{R}.$$

Because the input is

$$E(t) = E_0 \omega \sin(\omega t),$$

then the **time lag** between the input voltage and the steady-state current is

$$\frac{\delta}{\omega} = \frac{\arctan(S/R)}{\omega} \quad \text{seconds.}$$

## Electrical Resonance

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**Resonance** in an LRC circuit is defined only for sinusoidal inputs  $E(t) = E_0 \sin(\omega t)$ . Then the differential equation in current form is

$$I'' + \frac{R}{L}I' + \frac{1}{LC}I = \frac{E_0\omega}{L} \cos(\omega t).$$

Resonance happens if there is a frequency  $\omega$  which maximizes the steady-state solution amplitude  $I_0 = E_0/Z$ ,  $Z = \sqrt{R^2 + S^2}$ ,  $S = \omega L - \frac{1}{C\omega}$ . By calculus, this happens exactly when  $dZ/d\omega = 0$ , which gives the **resonant frequency**

$$\omega = \frac{1}{\sqrt{LC}}.$$

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**Details:**  $dI_0/d\omega = 0$  if and only if  $-E_0Z^{-2} \frac{dZ}{d\omega} = 0$ , which is equivalent to  $\frac{dZ}{d\omega} = 0$ . Then  $2S \frac{dS}{d\omega} = 0$  and finally  $S = 0$ , because  $\frac{dS}{d\omega} > 0$ . The equation  $S = 0$  is equivalent to  $\omega = 1/\sqrt{LC}$ .