

1. (Chapter 1: 60 points) Consider the system $A\vec{u} = \vec{b}$ with $\vec{u} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$ defined by

$$\begin{aligned} 2x_1 + 3x_2 + 4x_3 + x_4 &= 2 \\ 4x_1 + 3x_2 + 8x_3 + x_4 &= 4 \\ 6x_1 + 3x_2 + 8x_3 + x_4 &= 2 \end{aligned} \Rightarrow \left[\begin{array}{cccc|c} 2 & 3 & 4 & 1 & 2 \\ 4 & 3 & 8 & 1 & 4 \\ 6 & 3 & 8 & 1 & 2 \end{array} \right]$$

Solve the following parts:

A (a) [10%] Find the reduced row echelon form of the augmented matrix.

A (b) [10%] Identify the free variables and the lead variables.

A (c) [10%] Display a vector formula for a particular solution $\vec{u}_p \Rightarrow \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

A (d) [10%] Display a vector formula for the homogeneous solution $\vec{u}_h \Rightarrow t_1 \begin{bmatrix} 0 \\ -\frac{1}{3} \\ 0 \\ 1 \end{bmatrix}$

A (e) [10%] Identify each of Strang's Special Solutions. $\Rightarrow \begin{bmatrix} 0 \\ -\frac{1}{3} \\ 0 \\ 1 \end{bmatrix}$

A (f) [10%] Display the vector general solution \vec{u} , using superposition. $\Rightarrow \vec{u} = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + t_1 \begin{bmatrix} 0 \\ -\frac{1}{3} \\ 0 \\ 1 \end{bmatrix}$

$$a) \left[\begin{array}{cccc|c} 2 & 3 & 4 & 1 & 2 \\ 4 & 3 & 8 & 1 & 4 \\ 6 & 3 & 8 & 1 & 2 \end{array} \right] \xrightarrow[r_3 - 3r_1]{r_2 - 2r_1} \left[\begin{array}{cccc|c} 2 & 3 & 4 & 1 & 2 \\ 0 & -3 & 0 & -1 & 0 \\ 0 & -6 & -4 & -2 & -4 \end{array} \right] \xrightarrow[r_3 - 2r_2]{r_1 + r_2, -\frac{1}{3}r_2} \left[\begin{array}{cccc|c} 2 & 0 & 4 & 0 & 2 \\ 0 & 1 & 0 & \frac{1}{3} & 0 \\ 0 & 0 & -4 & 0 & -4 \end{array} \right]$$

$$\begin{aligned} r_1 + r_3 \cdot \frac{1}{2} & \rightarrow \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & \frac{1}{3} & 0 \\ 0 & 0 & 1 & 0 & 1 \end{array} \right] \\ \frac{1}{4} r_3 & \end{aligned}$$

b) lead var. - x_1, x_2, x_3 ; free var. - x_4

$$\begin{aligned} x_1 &= -1 \\ x_2 &= -\frac{1}{3}x_4 = -\frac{1}{3}t_1 \\ x_3 &= 1 \\ x_4 &= t_1 \end{aligned} \Rightarrow \vec{x}_h = t_1 \begin{bmatrix} 0 \\ -\frac{1}{3} \\ 0 \\ 1 \end{bmatrix}, \vec{x}_p = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \vec{u}_p$$

$$c) \vec{u}_h = t_1 \begin{bmatrix} 0 \\ -\frac{1}{3} \\ 0 \\ 1 \end{bmatrix}$$