

Name: _____

Differential Equations 2280

Final Exam

Thursday, 28 April 2017, 12:45pm-3:15pm

Instructions: This in-class exam is 120 minutes. No calculators, notes, tables or books. No answer check is expected. Details count 75%. The answer counts 25%.

Chapters 1 and 2: Linear First Order Differential Equations

A (a) [60%] Solve $5v'(t) = 7 + \frac{4}{t+1}v(t)$, $v(0) = 7$. Show all integrating factor steps.

$$v'(t) = \frac{7}{5} + \frac{4/5}{t+1} v(t), \quad v(0) = 7$$

$$v'(t) - \frac{4/5}{t+1} v(t) = \frac{7}{5}$$

$w = \text{int. factor} = e^{\int -\frac{4/5}{t+1}} = e^{-\frac{4/5 \ln|t+1|}{t+1}} = |t+1|^{-4/5}$

$$\int -\frac{4/5}{t+1} = -\frac{4}{5} \int \frac{1}{t+1} = -\frac{4}{5} \ln|t+1| \quad (t+1)^{-4/5}$$
$$(w v(t))' = \frac{7}{5} w$$

quadrature \rightarrow

$$w v(t) = \frac{7}{5} \int w \quad \int w = \int (t+1)^{-4/5} = 5(t+1)^{1/5} + C$$

$$\rightarrow w v(t) = \frac{7}{5} (5(t+1)^{1/5} + C) = 7(t+1)^{1/5} + C$$

$$v(t) = \frac{7(t+1)^{1/5}}{(t+1)^{-4/5}} + \frac{C}{(t+1)^{-4/5}} = 7(t+1) + C(t+1)^{4/5} \Big|_{t=0}$$
$$= 7 \rightarrow C = 0$$

$v(t) = 7t + 7$

A (b) [20%] Solve the linear homogeneous equation $2\sqrt{x+2} \frac{dy}{dx} = 2xy$.

$$\frac{dy}{dx} - \frac{2x}{2\sqrt{x+2}}y = 0 \quad \xrightarrow{\text{shortcut const int fac.}} \quad y = \frac{\text{const}}{\int \frac{x}{\sqrt{x+2}} dx}$$

$$y' - \frac{x}{\sqrt{x+2}}y = 0 \quad \text{Int. fac.} = e^{-\int \frac{x}{\sqrt{x+2}} dx}$$

$$y = Ce^{\int \frac{x}{\sqrt{x+2}} dx}$$

$$\int \frac{x}{\sqrt{x+2}} dx \quad u = x+2 \quad \rightarrow \quad \int \frac{u-2}{\sqrt{u}} du$$

$$du = dx$$

$$= \int \sqrt{u} du - 2 \int u^{1/2} du$$

$$= \frac{2}{3}(x+2)^{3/2} - 4(x+2)^{1/2}$$

$$\boxed{y = Ce^{\frac{2}{3}(x+2)^{3/2} - 4(x+2)^{1/2}}}$$

A (c) [20%] The linear problem $2\sqrt{x+2}y' = 2xy - 3x$ can be solved using superposition
 $y = y_h + y_p$. Find y_h and y_p .

$$y_p = \text{equil. sol.} \rightarrow 2xy - 3x = x(2y - 3) = 0 \rightarrow$$

$$y_p = \frac{3}{2}$$

y_h from part b) \rightarrow

$$\boxed{y = Ce^{\frac{2}{3}(x+2)^{3/2} - 4(x+2)^{1/2}} + \frac{3}{2}}$$

Chapter 3: Linear Equations of Higher Order

- (a) [10%] Solve for the general solution: $y'' - 4y' + 20y = 0$

A

$$(r^2 - 4r + 4) + 16 = 0 \\ (r-2)^2 + 16 = 0$$

$$\text{char. eqn. } r^2 - 4r + 20 = 0$$

$$r = 2 \pm \frac{1}{2} \sqrt{16 - 4(1)(-20)}$$

$$= 2 \pm \frac{1}{2} \sqrt{-64} =$$

$$y = C_1 e^{2t} \cos 4t + C_2 e^{2t} \sin 4t$$

$$2 \pm 4i \rightarrow \\ \text{atoms} = e^{2t} \cos 4t, \\ e^{2t} \sin 4t$$

- (b) [20%] Solve for the general solution: $y^{(5)} + 289y^{(3)} = 0$

A

$$\text{char. eqn. } r^5 + 289r^3 = 0 \rightarrow$$

$$\begin{array}{r} 17 \\ 17 \\ \hline 114 \\ 114 \\ \hline 0 \end{array}$$

$$r^3(r^2 + 289) = 0$$

$$289$$

$$r = 0, 0, 0, \pm 17i$$

$$\text{atoms} = e^{0x}, xe^{0x}, x^2e^{0x}, \sin 17x, \cos 17x$$

$$y = C_1 + C_2 x + C_3 x^2 + C_4 \sin 17x + C_5 \cos 17x$$

$$r^2 - 4r + 20 = (r-2)^2 + 16$$

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(c) [20%] Solve for the general solution, given the characteristic equation is
 $r(r^3 - 4r)^2(r^2 - 4r + 20)^2 = 0$.

A

chr. eqn. $r^3 (r^2 - 4r)^2 ((r-2)^2 + 16)^2 = 0$

atoms = $1, \pi, x^2, e^{2x}, e^{-2x}$
 $x^2, x e^{2x}, x e^{-2x}, e^{2x} \cos 4x, e^{2x} \sin 4x, e^{-2x} \cos 4x, e^{-2x} \sin 4x$

$r = 0, 0, 0, \pm 2, \pm 2, 2 \pm 4i, 2 \pm 4i$

$y = C_1 + C_2 x + C_3 x^2 + C_4 e^{2x} + C_5 e^{-2x} + C_6 x e^{2x} + C_7 x e^{-2x}$

$+ C_8 e^{2x} \cos 4x + C_9 e^{2x} \sin 4x + C_{10} x e^{2x} \cos 4x + C_{11} x e^{2x} \sin 4x$

A (d) Given $\frac{1}{2}x''(t) + \frac{2}{5}x'(t) + \frac{2}{3}x(t) = 17 \cos(\omega t)$, which represents a damped forced spring-mass system with $m = \frac{1}{2}$, $c = \frac{2}{5}$, $k = \frac{2}{3}$, answer the following two questions.

(1) [10%] Compute the frequency ω for practical mechanical resonance.

(2) [10%] Classify the homogeneous problem as over-damped, critically-damped or under-damped.

(1) $\omega = \sqrt{\frac{k}{m} - \frac{c^2}{2m^2}} = \sqrt{\frac{4}{3} - \frac{(4/25)}{2(1/4)}} = \sqrt{\frac{4}{3} - \frac{(4/25)}{(1/2)}} = \sqrt{\frac{4}{3} - \frac{8}{25}}$

$= \sqrt{\frac{100}{75} - \frac{24}{75}} = \sqrt{\frac{76}{75}}$

(2) $\frac{1}{2}x'' + \frac{2}{5}x' + \frac{2}{3}x = 0 \rightarrow r^2 + \frac{4}{3}r + \frac{4}{3} = 0$

$e^{-...} \cos ... \rightarrow \text{oscillations}$

Underdamped

$r = -\frac{4}{10} \pm \frac{1}{2} \sqrt{\frac{16}{25} - \frac{16}{3}}$

$\uparrow \text{negative}, \frac{48}{75} - \frac{400}{75} \approx -\frac{350}{75} \approx 5$

$e^{-...} \sin ...$

- (e) [30%] Determine for $y^{(6)} - 4y^{(4)} = 5x^3 + x^2 e^{2x} + \sin(2x)$ the shortest trial solution for y_p according to the method of undetermined coefficients. Do not evaluate the undetermined coefficients!

A

homogeneous problem: $y^{(6)} - 4y^{(4)} = 0$

$$\text{char. eqn. } r^6 - 4r^4 = 0$$

$$r^4(r^2 - 4) = 0, \quad r = 0, 0, 0, 0, \pm 2$$

$$\text{atoms} = 1, x, x^2, x^3, e^{2x}, e^{-2x}$$

method of uc: first try $y_p = \underbrace{1+x+x^2+x^3}_{x^4} + \underbrace{e^{2x}+xe^{2x}+x^2e^{2x}}_x + \underbrace{\sin 2x + \cos 2x}_{\text{nothing okay}}$

no repeats - so must mult by:

$$\rightarrow y_p = d_1 x^4 + d_2 x^5 + d_3 x^6 + d_4 x^7 + d_5 x e^{2x} + d_6 x^2 e^{2x} + d_7 x^3 e^{2x} + d_8 \sin 2x + d_9 \cos 2x$$

Chapters 4 and 5: Systems of Differential Equations

(a) [20%] Matrix $A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & -5 \end{pmatrix}$ has eigenvalues $-1, 1, -5$. Find all eigenpairs of A and then write the solution of $\mathbf{x}(t)$ of $\mathbf{x}'(t) = A\mathbf{x}(t)$ according to the Eigenanalysis Method.

$$\lambda_1 = -1 \quad \begin{array}{c} A \\ \hline \vec{v}_1 \end{array}$$

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & -5 \end{pmatrix} \Rightarrow \begin{pmatrix} +1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & -4 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \vec{0}$$

$$\lambda_2 = 1 \quad \begin{array}{c} A \\ \hline \vec{v}_2 \end{array}$$

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & -5 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \vec{0}$$

$$\vec{v}_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\lambda_3 = -5 \quad \begin{array}{c} A \\ \hline \vec{v}_3 \end{array}$$

$$\begin{pmatrix} 5 & 1 & 1 \\ 1 & 5 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \vec{0}$$

$$\begin{pmatrix} 5 & 1 & 1 \\ 0 & 24 & 4 \\ 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 5 & 1 & 1 \\ 0 & 1 & \frac{1}{6} \\ 0 & 0 & 0 \end{pmatrix}$$

$$\vec{v}_3 = \begin{pmatrix} -1 \\ 1 \\ 6 \end{pmatrix}$$

check:

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & -5 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} = \lambda_1 \vec{v}_1$$

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & -5 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \lambda_2 \vec{v}_2$$

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & -5 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \\ 6 \end{pmatrix} = \begin{pmatrix} 1+6 \\ -1+6 \\ -30 \end{pmatrix} = \lambda_3 \vec{v}_3$$

$$\begin{pmatrix} 5 \\ 1 \\ 30 \end{pmatrix}$$

$$-5 \begin{pmatrix} -1 \\ 1 \\ 6 \end{pmatrix} = \begin{pmatrix} 5 \\ -5 \\ 30 \end{pmatrix}$$

$$x_1 = -\frac{1}{6}x_3$$

$$x_2 = -\frac{1}{6}x_3$$

$$x_3 = x_3$$

$$y_1 = -1$$

$$y_2 = -1$$

$$y_3 = 6$$

$$\boxed{\vec{x} = c_1 e^{-t} \begin{pmatrix} -1 \\ 1 \\ 6 \end{pmatrix} + c_2 e^t \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_3 e^{-5t} \begin{pmatrix} -1 \\ -1 \\ 6 \end{pmatrix}}$$

(b) [30%] Find the general solution of the 2×2 system

$$\frac{d}{dt} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} 5 & -1 \\ -1 & 5 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$

according to the Cayley-Hamilton-Ziebur Method, using the textbook's Chapter 4 shortcut.

$$\begin{aligned} x'(t) &= 5x(t) - y(t) \\ y'(t) &= -x(t) + 5y(t) \end{aligned}$$

$$\begin{pmatrix} 5 & -1 \\ -1 & 5 \end{pmatrix}, \det|A - \lambda I| = \begin{vmatrix} 5-\lambda & -1 \\ -1 & 5-\lambda \end{vmatrix} = (5-\lambda)(5-\lambda) - 1 = 0$$

$$\lambda^2 - 10\lambda + 25 - 1 = 0$$

$$(\lambda - 5)^2 = 1$$

$$\lambda = 5 \pm 1$$

$$\lambda = 6 \text{ or } 4$$

~~Atoms:~~ $y = e^{rx}$

Atoms: e^{6t}, e^{4t}

$$y(t) = C_1 e^{6t} + C_2 e^{4t}$$

$$x'(t) - 5x(t) = -y(t)$$

$$y(t) = 5x - x'$$

$$x' = 6C_1 e^{6t} + 4C_2 e^{4t}$$

$$y(t) = 5C_1 e^{6t} + 5C_2 e^{4t} - 6C_1 e^{6t} - 4C_2 e^{4t}$$

$$x(t) = C_1 e^{6t} + C_2 e^{4t}$$

$$y(t) = -C_1 e^{6t} + C_2 e^{4t}$$

(c) [20%] Assume a 2×2 system $\frac{d}{dt}\vec{u} = A\vec{u}$ has a scalar general solution

$$x(t) = c_1 e^{3t} + c_2 e^{4t}, \quad y(t) = 2c_2 e^{3t} + (c_1 + 3c_2) e^{4t}.$$

Compute the exponential matrix e^{At} .

$$\begin{aligned} X(t) &= c_1 e^{3t} + c_2 e^{4t} \\ Y(t) &= c_1 e^{3t} + c_2 (2e^{3t} + 3e^{4t}) \\ \text{if } \Phi(t) &= \begin{pmatrix} e^{3t} & e^{4t} \\ e^{4t} & 2e^{3t} + 3e^{4t} \end{pmatrix} \end{aligned}$$

$$\Phi(0) = \begin{pmatrix} 1 & 1 \\ 1 & 5 \end{pmatrix}$$

$$\Phi(0)^{-1} = \frac{1}{5-1} \begin{pmatrix} 5 & -1 \\ -1 & 1 \end{pmatrix}$$

$$= \frac{1}{4} \begin{pmatrix} 5 & -1 \\ -1 & 1 \end{pmatrix}$$

$$e^{At} = \Phi(t)\Phi(0)^{-1} = \begin{pmatrix} e^{3t} & e^{4t} \\ e^{4t} & 2e^{3t} + 3e^{4t} \end{pmatrix} \begin{pmatrix} 5 & -1 \\ -1 & 1 \end{pmatrix} \left(\frac{1}{4}\right)$$

$$= \left(\begin{array}{cc} 5e^{3t} - e^{4t} & -e^{3t} + e^{4t} \\ 5e^{4t} - (2e^{3t} + 3e^{4t}) & -e^{4t} + (2e^{3t} + 3e^{4t}) \end{array} \right) \frac{1}{4}$$

$$e^{At} = \left(\begin{array}{cc} \frac{5e^{3t} - e^{4t}}{4} & \frac{-e^{3t} + e^{4t}}{4} \\ \frac{5e^{4t} - (2e^{3t} + 3e^{4t})}{4} & \frac{-e^{4t} + (2e^{3t} + 3e^{4t})}{4} \end{array} \right)$$

e^{At}

(d) [30%] Consider the scalar system

$$\begin{cases} x' = x \\ y' = 3x + y, \\ z' = x + z \end{cases}$$

Solve the system by the most efficient method.

$$x' - x = 0 \quad \boxed{\omega}$$

$$w_1 = 1, r = e^{-t}$$

$$\boxed{x = C_1 e^{-t}}$$

$$y' = 3C_1 e^{-t} + y$$

$$y' - y = 3C_1 e^{-t}$$

$$w_2 = e^{-t}$$

$$(y w_2)' = 3C_1$$

$$yw_2 = 3tC_1 + C_2$$

$$\boxed{y = 3t e^{-t} C_1 + C_2 e^{-t}}$$

$$z' = C_1 e^{-t} + t$$

$$z' - z = C_1 e^{-t}$$

$$\frac{(w_3 z)'}{\omega} = C_1 e^{-t}$$

$$(w_3 z)' = C_1$$

$$w_3 = e^{-t}$$

$$(w_3 z)' = 5C_1$$

$$w_3 z = C_1 t + C_3$$

$$\boxed{z = C_1 t e^{-t} + C_3 e^{-t}}$$

Chapter 6: Dynamical Systems

- (a) [10%] Which of the four types *center*, *spiral*, *node*, *saddle* can be asymptotically stable at $t = \infty$? Explain your answer.

Spiral or node
 Saddle is never stable, center is always stable so no such thing as asymptotically stable w/ centers, and spirals or nodes can thus only be the ones which can be asymptotically spiral or node,
 which can be stable.
 Thus by elimination only the spiral or node one concludes

- (b) [20%] The origin is an equilibrium point of the linear system $\mathbf{u}' = \begin{pmatrix} 1 & 1 \\ -1 & 2 \end{pmatrix} \mathbf{u}$. Classify $(0, 0)$ as *center*, *spiral*, *node*, *saddle*.

$$(1-\lambda)(2-\lambda) + 1 = 0$$

$$2 - \lambda - 2\lambda + \lambda^2 + 1 = 0$$

$$\lambda^2 - 3\lambda + 3 = 0$$

$$\lambda = \frac{3 \pm \sqrt{9 - 4(0)(3)}}{2}$$

$$= \frac{3}{2} \pm \frac{\sqrt{3}i}{2}$$

$$= \frac{3}{2} \pm \frac{\sqrt{3}i}{2} / e$$

Unstable spiral

involves exponentials and sines, cosines,

Ans: $e^{\frac{3}{2}t} \left(\cos \frac{\sqrt{3}}{2}t, \sin \frac{\sqrt{3}}{2}t \right)$

(c) [20%] Consider the nonlinear dynamical system

$$x' = 14x - \frac{1}{2}x^2 - xy, \quad y' = 16y - \frac{1}{2}y^2 - xy.$$

Find the equilibrium points.

Answer check: One of the points is $(0, 32)$. See part (d) below.

$$\begin{aligned} x(14 - \frac{1}{2}x - y) &= 0 \\ y(16 - \frac{1}{2}y - x) &= 0 \end{aligned}$$

$$(0, 32)$$

$$y(16 - \frac{1}{2}y) = 0$$

$$(28, 0)$$

$$x(14 - \frac{1}{2}x) = 0$$

$$(0, 0)$$

$$14 - \frac{1}{2}x - y = 0$$

$$16 - \frac{1}{2}y - x = 0$$

$$\frac{1}{2}x + y = 14$$

$$\frac{1}{2}y + x = 16$$

$$x + 2y = 28$$

$$2x + y = 32$$

$$x = 28 - 2y$$

$$2(28 - 2y) + y = 32$$

$$56 - 3y = 32$$

$$-3y = -24$$

$$y = 8, x = 12$$

$$\boxed{(0, 32), (0, 0), (28, 0)} \\ (12, 8)$$

equil.

$$(12, 8)$$

(d) [30%] Consider again the nonlinear dynamical system

$$x' = 14x - \frac{1}{2}x^2 - xy, \quad y' = 16y - \frac{1}{2}y^2 - xy.$$

- (1) Compute the linearization at equilibrium point $(0, 32)$ of this system, which is the linear system $\frac{d}{dt}\vec{u}(t) = J(0, 32)\vec{u}(t)$.
- (2) Classify the unique equilibrium $(0, 0)$ of the linear system as a **node**, **spiral**, **center**, **saddle**.
- (3) Report the equilibrium $(0, 0)$ as **unstable** or **stable** at $t = \infty$. Classify further the equilibrium as a **repeller** or **attractor**, if the term applies.

d. (1) $J(X/Y) = \begin{pmatrix} 14 - X - Y & -X \\ -Y & 16 - Y - X \end{pmatrix}$

$$J(0, 32) = \begin{pmatrix} -18 & 0 \\ -32 & -16 \end{pmatrix}$$

(2) $(-18 - r)(-16 - r) = 0$ $y_1(t) = e^{-16t} = 0$
 $r = -16, -18$ $y_2(t) = e^{-18t} = 0$
 Columns: e^{-16t}, e^{-18t} $\lim_{t \rightarrow \infty}$

(3) Node
Stable, attractor.

- (e) [20%] Consider again the nonlinear dynamical system

$$x' = 14x - \frac{1}{2}x^2 - xy, \quad y' = 16y - \frac{1}{2}y^2 - xy.$$

What classification can be deduced for equilibrium $(0, 32)$ of this nonlinear system, according to the Pasting Theorem (Theorem 2 in 6.2)? It is not enough to give a one-word classification. Please explain your answer fully and cite the applicability of the exceptions in the Pasting Theorem.

A

since it is a node in the linear system with distinct roots it will also be a node in the nonlinear system
 Pasting says! node \rightarrow spiral if $r_1 = r_2$
 for nodes from the linear system
 nonlinear system from the classification using pasting theorem.

Chapter 7: Laplace Theory

(a) [20%] Solve for $f(t)$ in the equation $\mathcal{L}(f(t)) = \frac{s+1}{s(s+2)^2}$.

$$\begin{aligned}\mathcal{L}\{y(t)\} &= \frac{s+1}{s(s+2)^2} = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{(s+2)^2} \\ &= A + B e^{-2t} + C t e^{-2t}\end{aligned}$$

$$\begin{aligned}s+1 &= A(s^2 + 4s + 4) + Bs(s+2) + Cs \\ &\quad + B(s^2 + 2s)\end{aligned}$$

$$\begin{aligned}A + B &= 0 & 4A + 2B + C &= 1 & 4A &= 1 \\ \frac{1}{4} &= -B & 1 - \frac{1}{2} + C &= 1 & A &= 1/4 \\ B &= -\frac{1}{4} & -\frac{1}{2} + C &= 0 & \\ C &= \frac{1}{2}\end{aligned}$$

$$f(t) = \frac{1}{4} - \frac{1}{4}e^{-2t} + \frac{1}{2}te^{-2t}$$

(b) [20%] Find $\mathcal{L}(f)$ given $f(t) = (-t)e^t \sin(2t)$.

$$\begin{aligned}
 f(t) &= (-t)e^t \sin 2t \\
 \mathcal{L}\{f\} &= \mathcal{L}\{-t e^t \sin 2t\} \\
 &= \frac{d}{ds} \mathcal{L}\{\sin 2t\} \Big|_{s \rightarrow s-1} \\
 &= \frac{d}{ds} \left(\frac{2}{s^2 + 4} \right) \Big|_{s \rightarrow s-1} \\
 &= \frac{d}{ds} \left(\frac{2}{(s-1)^2 + 4} \right) \\
 &= -\frac{2(2(s-1))}{((s-1)^2 + 4)^2} \\
 &= \boxed{\frac{-4(s-1)}{((s-1)^2 + 4)^2}}
 \end{aligned}$$

(c) [30%] Solve by Laplace's Method the forced linear dynamical system

$$\begin{cases} x' = x - y, \\ y' = x + y + 3, \end{cases}$$

subject to initial states $x(0) = 0, y(0) = 0$.

$$\begin{aligned} x' &= x - y & x(0) &= 0 & y' &= x + y + 3 & y(0) &= 0 \\ s x(s) - x(0) &= x(s) - y(s) & s y(s) - y(0) &= x(s) + y(s) + \frac{3}{s} \\ (s-1)x(s) + y(s) &= 0 & -x(s) + (s-1)y(s) &= \frac{3}{s} \end{aligned}$$

use cramer's rule:

$$D = \begin{bmatrix} s-1 & 1 \\ -1 & s-1 \end{bmatrix} \quad x = \begin{bmatrix} 0 & 1 \\ 3/s & s-1 \end{bmatrix} \quad y = \begin{bmatrix} s-1 & 0 \\ -1 & 3/s \end{bmatrix}$$

$$\begin{aligned} D &= (s-1)^2 + 1 \\ &= (s-1)^2 + 1 \quad (s^2 - 2s + 2) \\ x(s) &= \frac{-3}{s((s-1)^2 + 1)} \quad y(s) = \frac{3(s-1)}{s((s-1)^2 + 1)} \end{aligned}$$

$$\frac{-3}{s((s-1)^2 + 1)} = \left. \frac{A}{s} + \frac{BS}{s^2 + 1} \right|_{s \rightarrow s-1} + \left. \frac{C}{s^2 + 1} \right|_{s \rightarrow s-1} \quad \begin{array}{l} y(s) \text{ partial fractions} \\ \text{are same} \end{array}$$

$$x(s) = A + B e^t \cos t + C e^t \sin t \quad y(s) = A + B e^t \cos t + C e^t \sin t$$

$$-3 = A(s^2 - 2s + 2) + Bs^2 + Cs$$

$$\begin{aligned} A + B &= 0 & -2A + C &= 0 & 2A &= -3 \\ B &= 3/2 & 2\left(\frac{3}{2}\right) + C &= 0 & A &= -\frac{3}{2} \\ 3 + C &= 0 & C &= -3 & B &= 3/2 \\ C &= -3 & & & & C = 0 \end{aligned}$$

$$3/2 - 3 = A(s^2 - 2s + 2) + B s^2 + Cs$$

$$\begin{aligned} A + B &= 0 & -2A + C &= 3 & 2A &= -3 \\ -\frac{3}{2} + B &= 0 & -3 + C &= 3 & B &= \frac{3}{2} \\ B &= 3/2 & C &= 3 & & \end{aligned}$$

$$x(s) = -\frac{3}{2} + \frac{3}{2} e^t \cos t - 3 e^t \sin t$$

$$y(s) = -\frac{3}{2} + \frac{3}{2} e^t \cos t$$

(d) [20%] Solve for $f(t)$ in the equation $\mathcal{L}(f(t)) = \frac{s}{s^2 - 4s + 20}$.

$$\begin{aligned} \mathcal{L}\{f(t)\} &= \frac{s}{s^2 - 4s + 20} = \frac{s}{(s-2)^2 + 16} \quad ((-2)(s-2)) \\ &= \frac{s}{u^2 + 16} \Big|_{u=s-2} = \frac{u+2}{u^2 + 16} \Big|_{u=s-2} = \frac{s+2}{s^2 + 16} \Big|_{s=s-2} \\ &= \frac{s}{s^2 + 16} \Big|_{s \rightarrow s-2} + \frac{2}{s^2 + 16} \Big|_{s \rightarrow s-2} \\ &= e^{2t} \cos 4t + \frac{1}{2} e^{2t} \sin 4t \end{aligned}$$

(e) [10%] Solve for $f(t)$ in the relation

$$\mathcal{L}(f) = \frac{d}{ds} (\mathcal{L}(t^2 e^{4t} \cos t))|_{s \rightarrow s+1}.$$

$$\mathcal{L}\{\sqrt{t}\} = \mathcal{L}\{-t^2 e^{-4t} \cos t\}|_{s \rightarrow s+1}$$

$$= \mathcal{L}\{-t^3 e^{-4t} e^{-t} \cos t\}$$

$$f = -t^3 e^{-3t} \cos t$$

Chapter 9: Fourier Series and Partial Differential Equations

In parts (a) and (b), let $f_0(x) = 1$ on the interval $-2 < x < 0$, $f_0(x) = 0$ on the interval $0 < x < 2$, $f_0(x) = 0$ for $x = 0$ and $x = \pm 2$. Let $f(x)$ be the periodic extension of f_0 to the whole real line, of period 4.

- (a) [10%] Compute the Fourier coefficients of $f(x)$ on $[-2, 2]$.

$$f_0(x) = \begin{cases} 1 & -2 < x < 0 \\ 0 & 0 < x < 2 \\ 0 & x = 0, \pm 2 \end{cases}$$



$$a_0 = \frac{1}{L} \int_{-L}^L f(t) dt = \frac{1}{2} \int_{-2}^0 1 dt = \frac{1}{2} \left[t \right]_{-2}^0 = \frac{1}{2} (0 - (-2)) = \frac{1}{2} \cdot 2 = 1$$

for series $\frac{a_0}{2} + \sum \dots$

$$a_n = \frac{1}{L} \int_{-L}^L f(t) \cos\left(\frac{n\pi t}{L}\right) dt = \frac{1}{2} \int_{-2}^0 \cos\left(\frac{n\pi t}{2}\right) dt$$

$$= \frac{1}{2} \left(\frac{2}{n\pi} \sin\left(\frac{n\pi t}{2}\right) \right) \Big|_{-2}^0 = \frac{1}{2} (0 - (0)) = \boxed{0}$$

$$b_n = \frac{1}{L} \int_{-L}^L f(t) \sin\left(\frac{n\pi t}{L}\right) dt = \frac{1}{2} \int_{-2}^0 \sin\left(\frac{n\pi t}{2}\right) dt$$

$$= \frac{1}{2} \left[-\frac{2}{n\pi} \cos\left(\frac{n\pi t}{2}\right) \right] \Big|_{-2}^0 = \frac{1}{2} \left[-\frac{2}{n\pi} - \left(-\frac{2}{n\pi} (-1)^n \right) \right]$$

$\cos(-\pi t)$

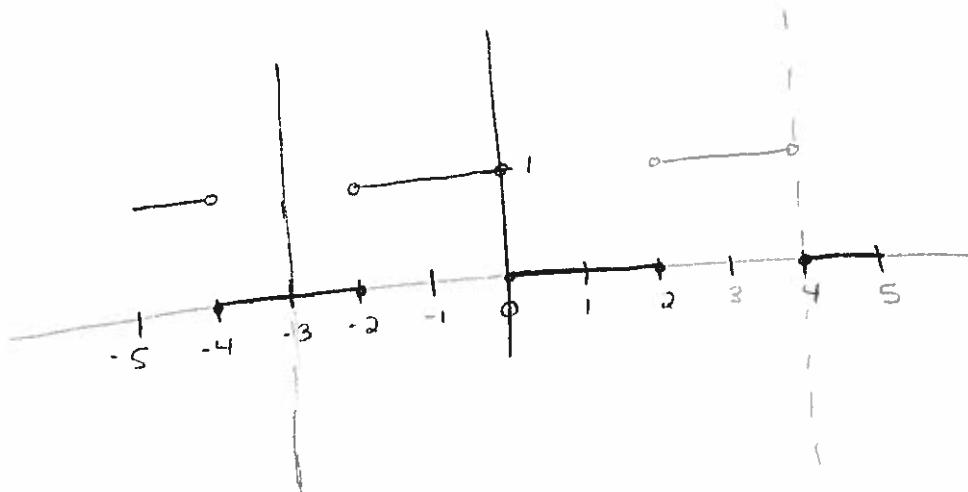
$$= \frac{1}{2} \left[-\frac{2}{n\pi} + \frac{2}{n\pi} (-1)^n \right] = -\frac{1}{\pi} \left(\frac{2}{n} \right) \left[(-1)^n - 1 \right]$$

$b_n = \frac{-2}{n\pi}$ for n odd, and $b_n = 0$ for n even

In parts (a) and (b), let $f_0(x) = 1$ on the interval $-2 < x < 0$, $f_0(x) = 0$ on the interval $0 < x < 2$, $f_0(x) = 0$ for $x = 0$ and $x = \pm 2$. Let $f(x)$ be the periodic extension of f_0 to the whole real line, of period 4.

- (b) [10%] Graph $f(x)$ on $-5 < x < 5$. Find all values of x in $-3 \leq x < 4$ which will exhibit Gibb's over-shoot.

$$f_0(x) = \begin{cases} 1 & -2 < x < 0 \\ 0 & 0 < x < 2 \\ 0 & x = 0, \pm 2 \end{cases}$$



Gibb's over-shoot whenever there is a jump discontinuity, so at $x = -2, 0, 2$ for the interval $[-3, 4]$

(c) [30%] Heat Conduction in a Rod. Solve the rod problem on $0 \leq x \leq 2, t \geq 0$:

$$\begin{cases} u_t &= 10u_{xx}, \\ u(0, t) &= 0, \\ u(2, t) &= 0, \\ u(x, 0) &= 4\sin(6\pi x) + 15\sin(14\pi x) \end{cases}$$

$k = \sqrt{10}$ $n=6$ $L=1$ add on $e^{-(\frac{n\pi}{L})^2 kt}$ to each component

$$u(x, t) = 4\sin(6\pi x)e^{-(6\pi)^2 \sqrt{10}t} + 15\sin(14\pi x)e^{-(14\pi)^2 \sqrt{10}t}$$

(d) [40%] **Vibration of a Finite String.** The normal modes for the string equation $u_{tt} = c^2 u_{xx}$ on $0 < x < L, t > 0$ are given by the functions

$$\sin\left(\frac{n\pi x}{L}\right) \cos\left(\frac{n\pi ct}{L}\right), \quad \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{n\pi ct}{L}\right).$$

It is known that each normal mode is a solution of the string equation and that the problem below has solution $u(x,t)$ equal to an infinite series of constants times normal modes (the superposition of the normal modes). For a problem with shape $u(x,0) = 0$ and speed $u_t(x,0) = g(x)$, only the second normal modes $\sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{n\pi ct}{L}\right)$ appear in the series solution.

Solve the finite string vibration problem on $0 \leq x \leq 5, t > 0$:

$$\begin{cases} u_{tt}(x,t) = 100u_{xx}(x,t), \\ u(0,t) = 0, & \text{clamped at } x=0 \\ u(4,t) = 0, & \text{clamped at } x=4 \\ u(x,0) = 0, & \text{shape zero} \\ u_t(x,0) = \sin(5\pi x) + 2\sin(7\pi x) & \text{speed nonzero} \end{cases}$$

For $u_L(x,0)$, use $\sin\left(\frac{n\pi x}{L}\right)$. Here $c = 10$

$$u_L(x,0) = \sin(5\pi x) + 2\sin(7\pi x)$$

$$u_L(x,t) = \sin(5\pi x) \frac{\sin(5\pi 10t)}{50\pi} + 2\sin(7\pi x) \frac{\sin(7\pi 10t)}{70\pi}$$

$$u_t(x,t) = \sin(5\pi x) \frac{\sin(50\pi t)}{50\pi} + 2\sin(7\pi x) \frac{\sin(70\pi t)}{70\pi}$$

(over 50π and 70π because $u_t(x,t)$
is a derivative.)

