## Autonomous Differential Equations

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## Autonomous Differential Equation

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The first order differential equation

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\begin{equation*}
y^{\prime}(x)=f(y(x)) \tag{1}
\end{equation*}
$$

has right side independent of $\boldsymbol{x}$. It is called an autonomous differential equation.

- We usually assume $\boldsymbol{f}$ is continuously differentiable. Then Picard's theorem applies, which implies that solution curves to an autonomous equation don't cross.
- There are no external control terms, that is, no terms that depend on $\boldsymbol{x}$. Due to the lack of external controls, the equation is said to be self-governing or autonomous.


## Phase Line Diagram

A phase line diagram for the autonomous equation $\boldsymbol{y}^{\prime}=\boldsymbol{f}(\boldsymbol{y})$ is a line segment with labels sink, source or node, one for each root of $\boldsymbol{f}(\boldsymbol{y})=0$, i.e., each equilibrium; see Figure 1. It summarizes the contents of a direction field and threaded curves, including all equilibrium solutions.


Figure 1. A phase line diagram for an autonomous equation $\boldsymbol{y}^{\prime}=\boldsymbol{f}(\boldsymbol{y})$.

## Phase Diagram

A phase line diagram is used to draw a phase diagram of threaded solutions and equilibrium solutions by using the three rules below.

1. Equilibrium solutions are horizontal lines in the phase diagram.
2. Threaded solutions of $\boldsymbol{y}^{\prime}=\boldsymbol{f}(\boldsymbol{y})$ don't cross. In particular, they don't cross equilibrium solutions.
3. A threaded non-equilibrium solution that starts at $\boldsymbol{x}=\mathbf{0}$ at a point $\boldsymbol{y}_{0}$ must be increasing if $\boldsymbol{f}\left(\boldsymbol{y}_{0}\right)>0$, and decreasing if $\boldsymbol{f}\left(\boldsymbol{y}_{0}\right)<\mathbf{0}$.


Figure 2. A phase diagram for an autonomous equation $\boldsymbol{y}^{\prime}=\boldsymbol{f}(\boldsymbol{y})$. The graphic is drawn directly from phase line diagram Figure 1, using rules 1, 2, 3.

## Justification of Rule 3

To justify 3 , let $\boldsymbol{y}_{1}(\boldsymbol{x})$ be a solution with $\boldsymbol{y}_{1}^{\prime}(\boldsymbol{x})=\boldsymbol{f}\left(\boldsymbol{y}_{1}(\boldsymbol{x})\right)$ either positive or negative at $\boldsymbol{x}=\mathbf{0}$.
If $\boldsymbol{y}_{1}^{\prime}\left(\boldsymbol{x}_{1}\right)=0$ for some $\boldsymbol{x}_{1}>0$, then let $\boldsymbol{c}=\boldsymbol{y}_{1}\left(\boldsymbol{x}_{1}\right)$ and define equilibrium solution $y_{2}(x)=c$.
Then solution $\boldsymbol{y}_{1}$ crosses equilibrium solution $\boldsymbol{y}_{2}$ at $\boldsymbol{x}=\boldsymbol{x}_{1}$, violating rule 2 .

## Direction Field Plots

A direction field for $\boldsymbol{y}^{\prime}=\boldsymbol{f}(\boldsymbol{y})$ can be constructed in two steps. First, draw it along the $\boldsymbol{y}$-axis. Secondly, duplicate the $\boldsymbol{y}$-axis field at even divisions along the $\boldsymbol{x}$-axis.

Fact 1. An equilibrium is a horizontal line. It is stable if all solutions starting near the line remain nearby as $\boldsymbol{x} \rightarrow \infty$.
Fact 2. Solutions don't cross. In particular, any solution that starts above or below an equilibrium solution must remain above or below.
Fact 3. A solution curve of $\boldsymbol{y}^{\prime}=\boldsymbol{f}(\boldsymbol{y})$ rigidly moved to the left or right will remain a solution, i.e., the translate $\boldsymbol{y}\left(\boldsymbol{x}-\boldsymbol{x}_{0}\right)$ of a solution to $\boldsymbol{y}^{\prime}=\boldsymbol{f}(\boldsymbol{y})$ is also a solution.

A phase line diagram is merely a summary of the solution behavior in a direction field. Conversely, an independently made phase line diagram can be used to enrich the detail in a direction field.
Fact 3 is used to make additional threaded solutions from an initial threaded solution, by translation. Threaded solutions with turning points are observed to have their turning points march monotonically to the left, or to the right.

