# The Corrected Trial Solution in the Method of Undetermined Coefficients

- Definition of Related Atoms
- The Basic Trial Solution Method
- Symbols
- Superposition
- The Trial Solution with Fewest Atoms
- Two Correction Rules
  - Correction Rule I
  - Correction rule II
- Illustrations
- Observations
- A Shortcut for Correction Rule II

#### **Definition of Related Atoms**

A base atom is one of the terms 1,  $\cos bx$ ,  $\sin bx$ ,  $e^{ax}$ ,  $e^{ax} \cos bx$ ,  $e^{ax} \sin bx$ . An atom equals  $x^n$  times a base atom, for  $n = 0, 1, 2, 3 \dots$ Atoms A and B are **related** if and only if their successive derivatives  $A, A', A'', \dots, B$ ,  $B', B'', \dots$  share a common atom.

Then  $x^3$  is related to x and  $x^{101}$ , while x is unrelated to  $e^x$ ,  $xe^x$  and  $x \sin x$ . Atoms  $x \sin x$  and  $x^3 \cos x$  are related, but the atoms  $\cos 2x$  and  $\sin x$  are unrelated.

An easy way to detect related atoms:

Atom A is related to atom B if and only if their base atoms are identical or else they would become identical by changing a sine to a cosine.

### **The Basic Trial Solution Method**

The method is outlined here for an nth order linear differential equation.

# **Undetermined Coefficients Trial Solution Method**

**Step 1**. Let  $g(x) = x^n f(x)$ , where n is the order of the differential equation. Extract all distinct atoms that appear in the derivatives g(x), g'(x), g''(x),..., then collect the distinct atoms so found into a list of k atoms. Multiply these atoms by **undetermined coefficients**  $d_1, \ldots, d_k$ , then add to define a **trial solution** y

- **Step 2**. Substitute y into the differential equation.
- **Step 3**. Match coefficients of atoms left and right to write out linear algebraic equations for unknowns  $d_1, d_2, \ldots, d_k$ . Solve the equations. Any variables not appearing are set to zero.
- **Step 4**. The trial solution y with evaluated coefficients  $d_1, d_2, \ldots, d_k$  becomes the particular solution  $y_p$ .

#### Symbols .

The symbols  $c_1$ ,  $c_2$  are reserved for use as arbitrary constants in the general solution  $y_h$  of the homogeneous equation.

Symbols  $d_1, d_2, d_3, \ldots$  are reserved for use in the trial solution y of the non-homogeneous equation. Abbreviations: c = constant, d = determined.

#### **Superposition**

The relation  $y = y_h + y_p$  suggests solving ay'' + by' + cy = f(x) in two stages:

- (a) Find  $y_h$  as a linear combination of atoms computed by applying Euler's theorem to factors of the characteristic polynomial  $ar^2 + br + c$ .
- (b) Apply the basic trial solution method to find  $y_p$ .
  - We expect to find two arbitrary constants  $c_1$ ,  $c_2$  in the solution  $y_h$ , but in contrast, no arbitrary constants appear in  $y_p$ .
  - Calling  $d_1, d_2, d_3, \dots$  undetermined coefficients is misleading, because in fact they are eventually *determined*.

#### The Trial Solution with Fewest Atoms

Undetermined coefficient theory computes a trial solution with **fewest atoms**, thereby eliminating superfluous symbols, which effects a reduction in the size of the algebra problem. In the case of the example  $y'' + y = x^2$ , the theory computes a trial solution  $y = d_1 + d_2x + d_3x^2$ , reducing the number of symbols from 5 to 3.

In a general equation ay'' + by' + cy = f(x), the atoms in the trial solution y are the atoms that appear in  $g(x) = x^2 f(x)$  plus all lower-power related atoms. Equivalently, the atoms are those extracted from the successive derivatives g(x), g'(x), g''(x), .... For example, if  $f(x) = x^2$ , then  $g(x) = x^2(x^2) = x^4$  and the *list of derivatives* is  $x^4$ ,  $4x^3$ ,  $12x^2$ , 24x, 24. Strip coefficients to identify *the list of related atoms* 1, x,  $x^2$ ,  $x^3$ ,  $x^4$ . Alternatively, begin with the atoms in g(x), namely  $x^4$ , and append all lower powered related atoms. Briefly, atom  $x^4$  causes an append of related atoms  $1, x, x^2, x^3$ .

#### Two Correction Rules

The *initial* trial solution y obtained by constructing atoms from  $g(x) = x^n f(x)$  is not the trial solution with fewest atoms. It is a sum of terms which can be organized into groups of related atoms, and it is known that each group contains n superfluous terms. The correction rules describe how to remove the superfluous terms, which produces the desired corrected trial solution with **fewest possible atoms**.

#### **Correction Rule I**

If some variable  $d_p$  is missing after substitution **Step 2**, then the system of linear equations for  $d_1, \ldots, d_k$  fails to have a unique solution. In the language of linear algebra, a missing variable  $d_p$  in the system of linear equations is a *free variable*, which implies the linear system in the unknowns  $d_1, \ldots, d_k$  has, among the *three possibilities*, infinitely many solutions.

A symbol  $d_p$  appearing in a trial solution will be missing in **Step 2** if and only if it multiplies an atom A(x) that is a solution of the homogeneous equation. Because  $d_p$  will be a free variable [any missing variable is a free variable], to which we will assign value zero in **Step 3**, the term  $d_pA(x)$  can be removed from the trial solution. We can do this in advance, to **decrease the number of symbols** in the trial solution.

**Rule I**. Remove all terms  $d_p A(x)$  in the trial solution of Step 1 for which atom A(x) is a solution of the homogeneous differential equation.

#### **Correction Rule II**

The trial solution always contains superfluous atoms, introduced by using  $x^n f(x)$  to construct the trial solution instead of f(x). For example, the equation  $y'' + y = x^2$  would have trial solution  $y = d_1 + d_2x + d_3x^2 + d_4x^3 + d_5x^4$ , with atoms  $x^3$  and  $x^4$  superfluous, because  $y_p = x^2 - 2$ . We could have replaced the 5-term trial solution by 3-termed trial solution  $y = d_1 + d_2x + d_3x^2$ . There is a rule for how to remove superfluous terms, which combines easily with Rule I:

Rule II. Terms removed from Rule I appear in groups of related atoms

$$B(x), \quad xB(x), \quad \ldots, \quad x^mB(x),$$

where B(x) is a base atom, that is, an atom not containing a power of x. Rule I removes the first k of these atoms from the trial solution. Rule II removes the last n - k of these atoms. The ones removed are called **superfluous atoms**.

### An Illustration \_

Assume the differential equation has order n=2 and the trial solution contains a sub-list of related atoms

$$e^{2x},\,xe^{2x},\,x^2e^{2x},\,x^3e^{ex}.$$

#### Example 1

Assume  $e^{2x}$  is **not** a solution of the homogeneous equation.

Then Rule I removes no atoms (k = 0) and Rule II removes the last 2 atoms (n - k = 2 - 0 = 2), resulting in the revised **shorter** atom sub-list

$$e^{2x}, xe^{2x}.$$

#### Example 2

Assume  $e^{2x}$  is a solution of the homogeneous equation.

Then Rule I removes atom  $e^{2x}$  (k = 1) from the start of the list and Rule II removes  $x^3e^{2x}$  from the end of list (n - k = 2 - 1 = 1), resulting in the revised sub-list

$$xe^{2x}, x^2e^{2x}.$$

## Observations

- Rule I and Rule II together imply that exactly *n* atoms are removed from every complete sub-list of related atoms in the original trial solution.
- The n atoms are removed from *the two ends*, killing k from the *beginning* of the list and n k from the *end* of the list.
- Substitution of the trial solution into the differential equation creates a the system of linear algebraic equations for the undetermined coefficients  $d_1, d_2, d_3, \ldots$ , in which every symbol  $d_j$  appears! There are no free variables and the total number of atoms used in y cannot be reduced.
- The system of equations has the least possible dimension and a unique solution for the undetermined coefficients.

## A Shortcut

Building the atom list from  $g(x) = x^n f(x)$  requires subsequent **removal of** n atoms from each sub-list of related atoms. Building a short atom list from f(x) requires a subsequent **append of atoms** to each sub-list of related atoms. The second method, which requires less writing, is a **shortcut** recommended after learning the basic method of removing atoms.

The idea for appending the atoms is the realization that the factor  $x^n$  used in  $g(x) = x^n f(x)$  causes n extra atoms to appear in a sub-list of related atoms. Here are the facts:

- If the first atom in the sublist, base atom *B*, is a solution of the homogeneous differential equation, then it is removed. This causes the first of the *n* appended atoms to be kept.
- If the first two atoms *B*, *xB* are solutions of the homogeneous differential equation, then both are removed. This causes the first two of the *n* appended atoms to be kept.
- If the first three atoms B, xB,  $x^2B$  are solutions of the homogeneous differential equation, then all three are removed. This causes the first three of the n appended atoms to be kept.

#### A Shortcut for Correction Rule II

Let a sub-list of related atoms be constructed from f(x) instead of  $g(x) = x^n f(x)$ .

Each removal of an atom from the left causes an append of a related atom on the right.

An Example for 
$$f(x)=11.578x^3e^x+22.1\cos 2x$$

Consider the sub-list constructed from atom  $x^3e^x$ . The other atom  $\cos 2x$  is treated similarly. Assume n = 3 and  $e^x$ ,  $xe^x$  are homogeneous DE solutions.

Long sub-list from  $x^n f(x)$ Short sub-list from f(x)Remove one on the left Append one on the right Remove one more from the left Append one more on the right Corrected list