## Chapter 5

## Second Order Linear Equations

Studied here are linear differential equations of the second order

$$
\begin{equation*}
a(x) y^{\prime \prime}+b(x) y^{\prime}+c(x) y=f(x) . \tag{1}
\end{equation*}
$$

Important to the theory is continuity of the coefficients $a(x), b(x), c(x)$ and the non-homogeneous term $f(x)$, also called the forcing term or the input.

### 5.1 Linear Constant Equations

Studied is the equation

$$
a y^{\prime \prime}+b y^{\prime}+c y=0
$$

where $a \neq 0, b$ and $c$ are constants. An explicit formula for the general solution is developed. Prerequisites are the quadratic formula, complex numbers, Cramer's rule for $2 \times 2$ linear systems and first order linear differential equations.

## Theorem 1 (Recipe for Constant Equations)

Let $a \neq 0, b$ and $c$ be real constants. Let $r_{1}, r_{2}$ be the two roots of $a r^{2}+b r+c=0$, real or complex. If complex, then let $r_{1}=\overline{r_{2}}=\alpha+i \beta$ with $\beta>0$. Consider the following three cases, organized by the sign of the discriminant $\mathcal{D}=b^{2}-4 a c$ :

$$
\begin{array}{ll}
\mathcal{D}>0 \text { (Real distinct roots) } & y_{1}=e^{r_{1} x}, \quad y_{2}=e^{r_{2} x} . \\
\mathcal{D}=0 \text { (Real equal roots) } & y_{1}=e^{r_{1} x}, \quad y_{2}=x e^{r_{1} x} . \\
\mathcal{D}<0 \text { (Conjugate roots) } & y_{1}=e^{\alpha x} \cos (\beta x), \quad y_{2}=e^{\alpha x} \sin (\beta x) .
\end{array}
$$

Then $y_{1}, y_{2}$ are two solutions of $a y^{\prime \prime}+b y^{\prime}+c y=0$ and all solutions are given by $y=c_{1} y_{1}+c_{2} y_{2}$, where $c_{1}, c_{2}$ are arbitrary constants.

The proof appears on page 193. Examples 1-3, page 191, cover the three cases.

A general solution is an expression that represents all solutions of the differential equation. Theorem 1 gives an expression of the form

$$
y=c_{1} y_{1}+c_{2} y_{2}
$$

where $c_{1}$ and $c_{2}$ are arbitrary constants and $y_{1}, y_{2}$ are special solutions of the differential equation, determined by the roots of the characteristic equation $a r^{2}+b r+c=0$. The terminology recipe means that the general solution can be written out at very high speed with no justification required.
The initial value problem for $a y^{\prime \prime}+b y^{\prime}+c y=0$ selects the constants $c_{1}, c_{2}$ in the general solution $y=c_{1} y_{2}+c_{2} y_{2}$ from initial conditions of the form $y\left(x_{0}\right)=d_{1}, y^{\prime}\left(x_{0}\right)=d_{2}$. In these conditions, $x_{0}$ is a given point in $-\infty<x<\infty$ and $d_{1}, d_{2}$ are two real numbers.

## Theorem 2 (Uniqueness)

Let $a \neq 0, b, c, x_{0}, d_{1}$ and $d_{2}$ be constants. The initial value problem $a y^{\prime \prime}+b y^{\prime}+c y=0, y\left(x_{0}\right)=d_{1}, y^{\prime}\left(x_{0}\right)=d_{2}$ has one and only one solution, found from the general solution $y=c_{1} y_{1}+c_{2} y_{2}$ by applying Cramer's rule or the method of elimination.

The proof appears on page 194. For Cramer's rule details, see Example 4, page 192.
The two theorems taken together give a working rule for solving a linear constant equation:

To solve $a y^{\prime \prime}+b y^{\prime}+c y=0$, find the roots of the characteristic equation $a r^{2}+b r+c=0$ and then apply the recipe to write down $y_{1}, y_{2}$. The general solution is then $y=c_{1} y_{1}+c_{2} y_{2}$. If initial conditions are given, then determine $c_{1}, c_{2}$ explicitly, otherwise $c_{1}, c_{2}$ remain arbitrary.

## Theorem 3 (Superposition)

Let $a \neq 0, b$ and $c$ be constants. Assume $y_{1}, y_{2}$ are solutions of $a y^{\prime \prime}+b y^{\prime}+$ $c y=0$ and $c_{1}, c_{2}$ are constants. Then $y=c_{1} y_{1}+c_{2} y_{2}$ is a solution of $a y^{\prime \prime}+b y^{\prime}+c y=0$.

A proof appears on page 194. The result is implicitly used in Theorem 1, in order to show that a general solution satisfies the differential equation.

Recipe Speed. The time taken to write out the general solution varies among individuals and according to the algebraic complexity of the characteristic equation. Judge your understanding of the recipe by
these statistics: most persons can write out the general solution in under 60 seconds. Especially simple equations like $y^{\prime \prime}=0, y^{\prime \prime}+y=0, y^{\prime \prime}-y=0$, $y^{\prime \prime}+2 y^{\prime}+y=0, y^{\prime \prime}+3 y^{\prime}+2 y=0$ are finished in less than 30 seconds.

Graphics. Computer programs can produce plots for initial value problems. They cannot plot symbolic solutions containing the arbitrary variables $c_{1}, c_{2}$ that appear in the general solution.

Recipe Errors. Below in Table 1 are recorded some common but fatal errors made in writing out the general solution.

Table 1. Errors in Applying the Constant Equation Recipe.

| Bad equation | For $y^{\prime \prime}-y=0$, the correct characteristic equation is $r^{2}-1=0$. Commonly, $r^{2}-r=0$ is written, an error. |
| :---: | :---: |
| Sign reversal | For factored equation $(r+1)(r+2)=0$, the roots are $r=-1, r=-2$. A common error is to claim $r=1$ is a root. |
| Miscopy signs | The equation $r^{2}+2 r+2=0$ has complex conjugate roots $\alpha \pm \beta i$, where $\alpha=-1$ and $\beta=1(\beta>0$ is required). A common error is to miscopy signs on $\alpha$ and/or $\beta$. |
| Copying $\pm i$ | The equation $r^{2}+4=0$ has roots $\alpha \pm \beta i$ where $\alpha=0$ and $\beta=2$. A common mistake is to report "solutions" $\cos ( \pm 2 i x)$ and $\sin ( \pm 2 i x)$ - neither $\pm$ nor the complex unit $i$ should be copied. |

1 Example (Case 1) Solve $y^{\prime \prime}+y^{\prime}-2 y=0$.
Solution: The general solution is $y=c_{1} e^{x}+c_{2} e^{-2 x}$. Ordering is not important; an equivalent answer is $y=c_{1} e^{-2 x}+c_{2} e^{x}$. The answer will be justified below, by finding $y_{1}, y_{2}$ in the recipe.
The characteristic equation $r^{2}+r-2=0$ is found formally by replacements $y^{\prime \prime} \rightarrow r^{2}, y^{\prime} \rightarrow r$ and $y \rightarrow 1$ in the differential equation. Formal replacement reduces errors.
A college algebra method called inverse-FOIL applies to factor $r^{2}+r-2=0$ into $(r-1)(r+2)=0$. The roots are $r=1, r=-2$.
Applying case $\mathcal{D}>0$ of the recipe gives solutions $y_{1}=e^{x}$ and $y_{2}=e^{-2 x}$. If the roots are listed in reverse order, then the form of the answer will change to the equivalent one reported above.

2 Example (Case 2) Solve $4 y^{\prime \prime}+4 y^{\prime}+y=0$.

Solution: The general solution is $y=c_{1} e^{-x / 2}+c_{2} x e^{-x / 2}$. To justify this formula, find the characteristic equation $4 r^{2}+4 r+1=0$ and factor it by the inverse-FOIL method or square completion to obtain $(2 r+1)^{2}=0$. The roots are both $-1 / 2$.
Case $\mathcal{D}=0$ of the recipe gives $y_{1}=e^{-x / 2}, y_{2}=x e^{-x / 2}$. Then the general solution is $y=c_{1} y_{1}+c_{2} y_{2}$, which completes the verification.

3 Example (Case 3) Solve $4 y^{\prime \prime}+2 y^{\prime}+y=0$.
Solution: The solution is $y=c_{1} e^{-x / 4} \cos (\sqrt{3} x / 4)+c_{2} e^{-x / 4} \sin (\sqrt{3} x / 4)$. This formula is justified below, by showing that the solutions $y_{1}, y_{2}$ of the recipe are given by $y_{1}=e^{-x / 4} \cos (\sqrt{3} x / 4)$ and $y_{2}=e^{-x / 4} \sin (\sqrt{3} x / 4)$.
The characteristic equation is $4 r^{2}+2 r+1=0$. The roots by the quadratic formula are

$$
\begin{aligned}
r & =\frac{-b \pm \sqrt{b^{2}-4 a c}}{2 a} & & \begin{array}{l}
\text { College algebra formula for the roots of the } \\
\text { quadratic } a r^{2}+b r+c=0 .
\end{array} \\
& =\frac{-2 \pm \sqrt{2^{2}-(4)(4)(1)}}{(2)(4)} & & \text { Substitute } a=4, b=2, c=1 . \\
& =-\frac{1}{4} \pm \frac{\sqrt{-1} \sqrt{12}}{8} & & \text { Simplify. Used } \sqrt{(-1)(12)}=\sqrt{-1} \sqrt{12} . \\
& =-\frac{1}{4} \pm i \frac{\sqrt{3}}{4} & & \text { Convert to complex form, } i=\sqrt{-1} .
\end{aligned}
$$

The real part of the root is labeled $\alpha=-1 / 4$. The two imaginary parts are $\sqrt{3} / 4$ and $-\sqrt{3} / 4$. Only the positive one is labeled, the other being discarded: $\beta=\sqrt{3} / 4$.
The recipe case $\mathcal{D}<0$ applies to give solutions $y_{1}=e^{\alpha x} \cos (\beta x)$ and $y_{2}=$ $e^{\alpha x} \sin (\beta x)$. Substitution of $\alpha=-1 / 4$ and $\beta=\sqrt{3} / 4$ results in the formulas $y_{1}=e^{-x / 4} \cos (\sqrt{3} x / 4), y_{2}=e^{-x / 4} \sin (\sqrt{3} x / 4)$. The verification is complete.

4 Example (Initial Value Problem) Solve $y^{\prime \prime}+y^{\prime}-2 y=0, y(0)=1$, $y^{\prime}(0)=-2$ and graph the solution on $0 \leq x \leq 2$.

Solution: The solution to the initial value problem is $y=e^{-2 x}$. The graph appears in Figure 1. Justification and graph construction appear below.
The general solution is $y=c_{1} e^{x}+c_{2} e^{-2 x}$, from Example 1. The problem of finding $c_{1}, c_{2}$ uses the two equations $y(0)=1, y^{\prime}(0)=-2$ and the general solution to obtain expanded equations for $c_{1}, c_{2}$ :

$$
\begin{aligned}
e^{0} c_{1} & +e^{0} c_{2} \\
e^{0} c_{1}-2 e^{0} c_{2} & =-2
\end{aligned}
$$

The equations will be solved by the method of elimination. Since $e^{0}=1$, the equations are subject to simplification. Subtracting them eliminates the variable $c_{1}$ to give $3 c_{2}=3$. Therefore, $c_{2}=1$ and back-substitution finds $c_{1}=0$. Then $y=c_{1} e^{x}+c_{2} e^{-2 x}$ reduces to $y=e^{-2 x}$.
To graph the solution is a routine application of curve library methods, so no hand-graphing methods will be discussed. To produce a computer graphic of the solution, the following code is offered.

```
plot(exp(-2*x),x=0..2); Maple V
Plot[{exp(-2 x)},{x,0,2}]; Mathematica
plot [0:2] exp(-2*x) Gnuplot
x=0:0.05:2; plot(x,exp(-2*x)) Matlab and Scilab
```

Figure 1. Exponential solution $y=e^{-2 x}$.
Proof of Theorem 1: To show that $y_{1}$ and $y_{2}$ are solutions is left to the exercises. For the remainder of the proof, assume $y$ is a solution of $a y^{\prime \prime}+b y^{\prime}+$ $c y=0$. It has to be shown that $y=c_{1} y_{1}+c_{2} y_{2}$ for some real constants $c_{1}, c_{2}$.
Algebra background. In college algebra it is shown that the polynomial $a r^{2}+b r+c$ can be written in terms of its roots $r_{1}, r_{2}$ as $a\left(r-r_{1}\right)\left(r-r_{2}\right)$. In particular, the sum and product of the roots satisfy the relations $b / a=-r_{1}-r_{2}$ and $c / a=r_{1} r_{2}$.
Case $\mathcal{D}>0$. The equation $a y^{\prime \prime}+b y^{\prime}+c y=0$ can be re-written in the form $y^{\prime \prime}-\left(r_{1}+r_{2}\right) y^{\prime}+r_{1} r_{2} y=0$ due to the college algebra relations for the sum and product of the roots of a quadratic equation. The equation "factors" into $\left(y^{\prime}-r_{2} y\right)^{\prime}-r_{1}\left(y^{\prime}-r_{2} y\right)=0$ which suggests the substitution $u=y^{\prime}-r_{2} y$. Then $a y^{\prime \prime}+b y^{\prime}+c y=0$ is equivalent to the first order system

$$
\begin{gathered}
u^{\prime}-r_{1} u=0 \\
y^{\prime}-r_{2} y=u
\end{gathered}
$$

Growth-decay theory, page 3, applied to the first equation gives $u=u_{0} e^{r_{1} x}$. The second equation $y^{\prime}-r_{2} y=u$ is then solved by the integrating factor method, as in Example 11, page 75. This gives $y=y_{0} e^{r_{2} x}+u_{0} e^{r_{1} x} /\left(r_{1}-r_{2}\right)$. Therefore, any possible solution $y$ has the form $c_{1} e^{r_{1} x}+c_{2} e^{r_{2} x}$ for some $c_{1}, c_{2}$. This completes the proof of the case $\mathcal{D}>0$.
Case $\mathcal{D}=0$. The details follow the case $\mathcal{D}>0$, except that $y^{\prime}-r_{2} y=u$ has a different solution, $y=y_{0} e^{r_{1} x}+u_{0} x e^{r_{1} x}$ (exponential factors $e^{r_{1} x}$ and $e^{r_{2} x}$ cancel because $r_{1}=r_{2}$ ). Therefore, any possible solution $y$ has the form $c_{1} e^{r_{1} x}+c_{2} x e^{r_{1} x}$ for some $c_{1}, c_{2}$. This completes the proof of the case $\mathcal{D}=0$.
Case $\mathcal{D}<0$. The equation $a y^{\prime \prime}+b y^{\prime}+c y=0$ can be re-written in the form $y^{\prime \prime}-\left(r_{1}+r_{2}\right) y^{\prime}+r_{1} r_{2} y=0$ as in the case $\mathcal{D}>0$, even though $y$ is real and the roots are complex. The substitution $u=y^{\prime}-r_{2} y$ gives the same equivalent system as in the case $\mathcal{D}>0$. The solutions are symbolically the same, $u=$ $u_{0} e^{r_{1} x}$ and $y=y_{0} e^{r_{1} x}+u_{0} e^{r_{1} x} /\left(r_{1}-r_{2}\right)$. Therefore, any possible real solution $y$ has the form $C_{1} e^{r_{1} x}+C_{2} e^{r_{2} x}$ for some possibly complex $C_{1}, C_{2}$. Taking the real part of both sides of this equation gives $y=c_{1} e^{\alpha x} \cos (\beta x)+c_{2} e^{\alpha x} \sin (\beta x)$ for some real constants $c_{1}, c_{2}$, as follows:

$$
\begin{aligned}
y & =\operatorname{Re}(y) \\
& =\mathcal{R e}\left(C_{1} e^{r_{1} x}+C_{2} e^{r_{2} x}\right) \\
& =e^{\alpha x} \operatorname{Re}\left(C_{1} e^{i \beta x}+C_{2} e^{-i \beta x}\right) \\
& =e^{\alpha x}\left(c_{1} \cos (\beta x)+c_{2} \sin (\beta x)\right)
\end{aligned}
$$

Because $y$ is real.

## Substitute.

Use $e^{\alpha x+i \beta x}=e^{\alpha x} e^{i \beta x}$.
Where $c_{1}=\mathcal{R e}\left(C_{1}+C_{2}\right)$ and $c_{2}=$ $\operatorname{Im}\left(C_{2}-C_{1}\right)$ are real. Applied $e^{i \beta}=$ $\cos \beta+i \sin \beta$.

This completes the proof of the case $\mathcal{D}<0$.
Proof of Theorem 2: The left sides of the two requirements $y\left(x_{0}\right)=d_{1}$, $y^{\prime}\left(x_{0}\right)=d_{2}$ are expanded using the relation $y=c_{1} y_{1}+c_{2} y_{2}$ to obtain the following system of equations for the unknowns $c_{1}, c_{2}$ :

$$
\begin{aligned}
& y_{1}\left(x_{0}\right) c_{1}+y_{2}\left(x_{0}\right) c_{2}=d_{1}, \\
& y_{1}^{\prime}\left(x_{0}\right) c_{1}+y_{2}^{\prime}\left(x_{0}\right) c_{2}=d_{2} .
\end{aligned}
$$

If the determinant of coefficients

$$
\Delta=y_{1}\left(x_{0}\right) y_{2}^{\prime}\left(x_{0}\right)-y_{1}^{\prime}\left(x_{0}\right) y_{2}\left(x_{0}\right)
$$

is nonzero, then Cramer's rule says that the solutions $c_{1}, c_{2}$ are given as quotients

$$
c_{1}=\frac{d_{1} y_{2}^{\prime}\left(x_{0}\right)-d_{2} y_{2}\left(x_{0}\right)}{\Delta}, \quad c_{2}=\frac{y_{1}\left(x_{0}\right) d_{2}-y_{1}^{\prime}\left(x_{0}\right) d_{1}}{\Delta} .
$$

The organization of the proof is made from the three cases of the recipe, using $x$ instead of $x_{0}$, to simplify notation. The issue of a unique solution has now reduced to verification of $\Delta \neq 0$, in the three cases.
Case $\mathcal{D}>0$. Then

$$
\begin{aligned}
\Delta & =e^{r_{1} x} r_{2} e^{r_{2} x}-r_{1} e^{r_{1} x} e^{r_{2} x} & & \text { Substitute for } y_{1}, y_{2} . \\
& =\left(r_{2}-r_{1}\right) e^{r_{1} x+r_{2} x} & & \text { Simplify. } \\
& \neq 0 & & \text { Because } r_{1} \neq r_{2} .
\end{aligned}
$$

Case $\mathcal{D}=0$. Then

$$
\begin{aligned}
\Delta & =e^{r_{1} x}\left(e^{r_{1} x}+r_{1} x e^{r_{1} x}\right)-r_{1} e^{r_{1} x} x e^{r_{1} x} & & \text { Substitute for } y_{1}, y_{2} . \\
& =e^{2 r_{1} x} & & \text { Simplify. } \\
& \neq 0 & &
\end{aligned}
$$

Case $\mathcal{D}<0$. Then $r_{1}=\overline{r_{2}}=\alpha+i \beta$ and

$$
\begin{aligned}
\Delta & =\beta e^{2 \alpha x}\left(\cos ^{2} \beta x+\sin ^{2} \beta x\right) & & \text { Cancel } \alpha e^{2 \alpha x} \sin (\beta x) \cos (\beta x) . \\
& =\beta e^{2 \alpha x} & & \text { Trigonometric identity. } \\
& \neq 0 & & \text { Because } \beta>0 .
\end{aligned}
$$

In applications, the more efficient method of elimination is used to find $c_{1}, c_{2}$. In some references, it is called Gaussian elimination.

Proof of Theorem 3: The three terms of the differential equation are computed using the expression $y=c_{1} y_{1}+c_{2} y_{2}$ :

$$
\begin{array}{rlrl}
\text { Term 1: } & & c y & =c c_{1} y_{1}+c c_{2} y_{2} \\
\text { Term 2: } & & b y^{\prime} & =b\left(c_{1} y_{1}+c_{2} y_{2}\right)^{\prime} \\
& & =b c_{1} y_{1}^{\prime}+b c_{2} y_{2}^{\prime} \\
\text { Term 3: } & & a y^{\prime \prime} & =a\left(c_{1} y_{1}+c_{2} y_{2}\right)^{\prime \prime} \\
& =a c_{1} y_{1}^{\prime \prime}+a c_{2} y_{2}^{\prime \prime}
\end{array}
$$

The left side LHS of the differential equation is the sum of the three terms. It is simplified as follows:

$$
\begin{aligned}
\mathrm{LHS}= & c_{1}\left[a y_{1}^{\prime \prime}+b y_{1}^{\prime}+c y_{1}\right] & & \text { Add terms } 1,2 \text { and } 3, \\
& +c_{2}\left[a y_{2}^{\prime \prime}+b y_{2}^{\prime}+c y_{2}\right] & & \text { then collect on } c_{1}, c_{2} . \\
= & c_{1}[0]+c_{2}[0] & & \text { Both } y_{1}, y_{2} \text { satisfy } a y^{\prime \prime}+b y^{\prime}+c y=0 . \\
= & \mathrm{RHS} & & \text { The left and right sides match. }
\end{aligned}
$$

## Exercises 5.1

Recipe General Solution. Apply the recipe for constant equations, Theorem 1, page 189 , to write out the general solution. Model the solution after Examples 1-3, page 191.

1. $y^{\prime \prime}=0$
2. $3 y^{\prime \prime}=0$
3. $y^{\prime \prime}+y^{\prime}=0$
4. $3 y^{\prime \prime}+y^{\prime}=0$
5. $y^{\prime \prime}+3 y^{\prime}+2 y=0$
6. $y^{\prime \prime}-3 y^{\prime}+2 y=0$
7. $y^{\prime \prime}-y^{\prime}-2 y=0$
8. $y^{\prime \prime}-2 y^{\prime}-3 y=0$
9. $y^{\prime \prime}+y=0$
10. $y^{\prime \prime}+4 y=0$
11. $y^{\prime \prime}+16 y=0$
12. $y^{\prime \prime}+8 y=0$
13. $y^{\prime \prime}+y^{\prime}+y=0$
14. $y^{\prime \prime}+y^{\prime}+2 y=0$
15. $y^{\prime \prime}+2 y^{\prime}+y=0$
16. $y^{\prime \prime}+4 y^{\prime}+4 y=0$
17. $3 y^{\prime \prime}+y^{\prime}+y=0$
18. $9 y^{\prime \prime}+y^{\prime}+y=0$
19. $5 y^{\prime \prime}+25 y^{\prime}=0$
20. $25 y^{\prime \prime}+y^{\prime}=0$
21. (Recipe case 1) Let $y_{1}=e^{r_{1} x}$, $y_{2}=e^{r_{2} x}$. Assume factorization $a r^{2}+b r+c=a\left(r-r_{1}\right)\left(r-r_{2}\right)$. Show that $y_{1}, y_{2}$ are solutions of $a y^{\prime \prime}+b y^{\prime}+c y=0$.
22. (Recipe case 2) Let $y_{1}=e^{r_{1} x}$, $y_{2}=x e^{r_{1} x}$. Assume factorization $a r^{2}+b r+c=a\left(r-r_{1}\right)\left(r-r_{1}\right)$. Show that $y_{1}, y_{2}$ are solutions of $a y^{\prime \prime}+b y^{\prime}+c y=0$.
23. (Recipe case 3) Let $y_{1}=$ $e^{\alpha x} \cos \beta x, y_{2}=e^{\alpha x} \sin \beta x$, with $\beta>0$. Assume factorization $a r^{2}+$ $b r+c=a(r-\alpha-i \beta)(r-\alpha+i \beta)$. Show that $y_{1}, y_{2}$ are solutions of $a y^{\prime \prime}+b y^{\prime}+c y=0$.
