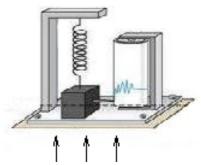
Sample Quiz 11, Problem 1. Vertical Motion Seismoscope

The 1875 **horizontal motion seismoscope** of F. Cecchi (1822-1887) reacted to an earthquake. It started a clock, and then it started motion of a recording surface, which ran at a speed of 1 cm per second for 20 seconds. The clock provided the observer with the earthquake hit time.



A Simplistic Vertical Motion Seismoscope

The apparently stationary heavy mass on a spring writes with the attached stylus onto a rotating drum, as the ground moves up. The generated trace is x(t).

The motion of the heavy mass m in the figure can be modeled initially by a forced spring-mass system with damping. The initial model has the form

$$mx'' + cx' + kx = f(t)$$

where f(t) is the vertical ground force due to the earthquake. In terms of the vertical ground motion u(t), we write via Newton's second law the force equation f(t) = -mu''(t) (compare to falling body -mg). The final model for the motion of the mass is then

1)
$$\begin{cases} x''(t) + 2\beta\Omega_0 x'(t) + \Omega_0^2 x(t) = -u''(t), \\ \frac{c}{m} = 2\beta\Omega_0, \quad \frac{k}{m} = \Omega_0^2, \\ x(t) = \text{center of mass position measured from equilibrium,} \\ u(t) = \text{vertical ground motion due to the earthquake.} \end{cases}$$

Terms **seismoscope**, **seismograph**, **seismometer** refer to the device in the figure. Some observations:

Slow ground movement means $x' \approx 0$ and $x'' \approx 0$, then (1) implies $\Omega_0^2 x(t) = -u''(t)$. The seismometer records ground acceleration.

Fast ground movement means $x \approx 0$ and $x' \approx 0$, then (1) implies x''(t) = -u''(t). The seismometer records ground displacement.

A release test begins by starting a vibration with u identically zero. Two successive maxima $(t_1, x_1), (t_2, x_2)$ are recorded. This experiment determines constants β, Ω_0 .

The objective of (1) is to determine u(t), by knowing x(t) from the seismograph.

The Problem.

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(a) Explain how a release test can find values for β , Ω_0 in the model $x'' + 2\beta \Omega_0 x' + \Omega_0^2 x = 0$.

(b) Assume the seismograph trace can be modeled at time t = 0 (a time after the earthquake struck) by $x(t) = Ce^{-at} \sin(bt)$ for some positive constants C, a, b. Assume a release test determined $2\beta\Omega_0 = 12$ and $\Omega_0^2 = 100$. Explain how to find a formula for the ground motion u(t), then provide a formula for u(t), using technology.

Solution.

(a) A release test is an experiment which provides initial data x(0) > 0, x'(0) = 0 to the seismoscope mass. The model is $x'' + 2\beta\Omega_0 x' + \Omega_0^2 x = 0$ (ground motion zero). The recorder graphs x(t) during the experiment, until two successive maxima $(t_1, x_1), (t_2, x_2)$ appear in the graph. This is enough information to find values for β, Ω_0 .

In an under-damped oscillation, the characteristic equation is $(r+p)^2 + \omega^2 = 0$ corresponding to complex conjugate roots $-p \pm \omega i$. The phase-amplitude form is $x(t) = Ce^{-pt} \cos(\omega t - \alpha)$, with period $2\pi/\omega$.

The equation $x'' + 2\beta\Omega_0 x' + \Omega_0^2 x = 0$ has characteristic equation $(r + \beta)^2 + \Omega_0^2 = 0$. Therefore $x(t) = Ce^{-\beta t}\cos(\Omega_0 t - \alpha)$.

The period is $t_2 - t_1 = 2\pi/\Omega_0$. Therefore, Ω_0 is known. The maxima occur when the cosine factor is 1, therefore

$$\frac{x_2}{x_1} = \frac{Ce^{-\beta t_2} \cdot 1}{Ce^{-\beta t_1} \cdot 1} = e^{-\beta(t_2 - t_1)}.$$

This equation determines β .

(b) The equation $-u''(t) = x''(t) + 2\beta\Omega_0 x'(t) + \Omega_0^2 x(t)$ (the model written backwards) determines u(t) in terms of x(t). If x(t) is known, then this is a quadrature equation for the ground motion u(t).

For the example $x(t) = Ce^{-at}\sin(bt)$, $2\beta\Omega_0 = 12$, $\Omega_0^2 = 100$, then the quadrature equation is

$$-u''(t) = x''(t) + 12x'(t) + 100x(t).$$

After substitution of x(t), the equation becomes

$$-u''(t) = Ce^{-at} \left(\sin(bt) a^2 - \sin(bt) b^2 - 2\cos(bt) ab - 12\sin(bt) a + 12\cos(bt) b + 100\sin(bt) \right)$$

which can be integrated twice using Maple, for simplicity. All integration constants will be assumed zero. The answer:

$$u(t) = \frac{Ce^{-at} (12 a^{2}b + 12 b^{3} - 200 ab) \cos(bt)}{(a^{2} + b^{2})^{2}} - \frac{Ce^{-at} (a^{4} + 2 a^{2}b^{2} + b^{4} - 12 a^{3} - 12 ab^{2} + 100 a^{2} - 100 b^{2}) \sin(bt)}{(a^{2} + b^{2})^{2}}$$

The Maple session has this brief input:

de:=-diff(u(t),t,t) = diff(x(t),t,t) + 12*diff(x(t),t) + 100* x(t); x:=t->C*exp(-a*t)*sin(b*t); dsolve(de,u(t));subs(_C1=0,_C2=0,%); Laplace theory implements the *method of quadrature* for higher order differential equations, linear systems of differential equations, and certain partial differential equations.

Laplace's method solves differential equations.

The Problem. Solve by table methods or Laplace's method.

- (a) Forward table. Find $\mathcal{L}(f(t))$ for $f(t) = te^{2t} + 2t\sin(3t) + 3e^{-t}\cos(4t)$.
- (b) Backward table. Find f(t) for

$$\mathcal{L}(f(t)) = \frac{16}{s^2 + 4} + \frac{s + 1}{s^2 - 2s + 10} + \frac{2}{s^2 + 16}.$$

(c) Solve the initial value problem x''(t) + 256x(t) = 1, x(0) = 1, x'(0) = 0.

Solution (a).

$$\begin{split} \mathcal{L}(f(t)) &= \mathcal{L}(te^{2t} + 2t\sin(3t) + 3e^{-t}\cos(4t)) \\ &= \mathcal{L}(te^{2t}) + 2\mathcal{L}(t\sin(3t)) + 3\mathcal{L}(e^{-t}\cos(4t)) & \text{Linearity} \\ &= -\frac{d}{ds}\mathcal{L}(e^{2t}) - 2\frac{d}{ds}\mathcal{L}(\sin(3t)) + 3\mathcal{L}(e^{-t}\cos(4t)) & \text{Differentiation rule} \\ &= -\frac{d}{ds}\mathcal{L}(e^{2t}) - 2\frac{d}{ds}\mathcal{L}(\sin(3t)) + 3\mathcal{L}(\cos(4t))|_{s=s+1} & \text{Shift rule} \\ &= -\frac{d}{ds}\frac{1}{s-2} - 2\frac{d}{ds}\frac{3}{s^{2}+9} + 3\frac{s}{s^{2}+16}\Big|_{s=s+1} & \text{Forward table} \\ &= \frac{1}{(s-2)^{2}} + \frac{12s}{(s^{2}+9)^{2}} + 3\frac{s+1}{(s+1)^{2}+16} & \text{Calculus} \end{split}$$

Solution (b).

$$\begin{split} \mathcal{L}(f(t)) &= \frac{16}{s^2+4} + \frac{s+1}{s^2-2s+10} + \frac{2}{s^2+16} \\ &= 8\frac{2}{s^2+4} + \frac{s+1}{(s-1)^2+9} + \frac{1}{2}\frac{4}{s^2+16} \\ &= 8\mathcal{L}(\sin 2t) + \frac{s+1}{(s-1)^2+9} + \frac{1}{2}\mathcal{L}(\sin 4t) \\ &= 8\mathcal{L}(\sin 2t) + \frac{s+2}{s^2+9} \Big| s = s - 1 + \frac{1}{2}\mathcal{L}(\sin 4t) \\ &= 8\mathcal{L}(\sin 2t) + \mathcal{L}(\cos 3t + \frac{2}{3}\sin 3t) \Big| s = s - 1 + \frac{1}{2}\mathcal{L}(\sin 4t) \\ &= 8\mathcal{L}(\sin 2t) + \mathcal{L}(e^t \cos 3t + e^t \frac{2}{3}\sin 3t) + \frac{1}{2}\mathcal{L}(\sin 4t) \\ &= 8\mathcal{L}(\sin 2t) + \mathcal{L}(e^t \cos 3t + e^t \frac{2}{3}\sin 3t) + \frac{1}{2}\mathcal{L}(\sin 4t) \\ &= \mathcal{L}(8\sin 2t) + e^t \cos 3t + e^t \frac{2}{3}\sin 3t + \frac{1}{2}\sin 4t) \\ &= \mathcal{L}(8\sin 2t) + e^t \cos 3t + e^t \frac{2}{3}\sin 3t + \frac{1}{2}\sin 4t) \\ &= 8\sin 2t + e^t \cos 3t + e^t \frac{2}{3}\sin 3t + \frac{1}{2}\sin 4t \\ \end{split}$$

Solution (c).

$$\begin{split} \mathcal{L}(x''(t) + 256x(t)) &= \mathcal{L}(1) & \mathcal{L} \text{ acts like matrix mult} \\ s \mathcal{L}(x') - x'(0) + 256 \mathcal{L}(x) &= \mathcal{L}(1) & \text{Parts rule} \\ s(s \mathcal{L}(x) - x(0)) - x'(0) + 256 \mathcal{L}(x) &= \mathcal{L}(1) & \text{Parts rule} \\ s^2 \mathcal{L}(x) - s + 256 \mathcal{L}(x) &= \mathcal{L}(1) & \text{Use } x(0) = 1, x'(0) = 0 \\ (s^2 + 256) \mathcal{L}(x) &= s + \mathcal{L}(1) & \text{Collect } \mathcal{L}(x) \text{ left} \\ \\ \mathcal{L}(x) &= \frac{s + \mathcal{L}(1)}{(s^2 + 256)} & \text{Isolate } \mathcal{L}(x) \text{ left} \\ \\ \mathcal{L}(x) &= \frac{s + 1/s}{(s^2 + 256)} & \text{Forward table} \\ \\ \mathcal{L}(x) &= \frac{s^2 + 1}{s(s^2 + 256)} & \text{Algebra} \\ \\ \mathcal{L}(x) &= \frac{A}{s} + \frac{Bs + C}{s^2 + 256} & \text{Partial fractions} \\ \\ \mathcal{L}(x) &= A \mathcal{L}(1) + B \mathcal{L}(\cos 16t) + \frac{C}{16} \mathcal{L}(\sin 16t) & \text{Backward table} \\ \\ \\ \mathcal{L}(x) &= \mathcal{L}(A + B \cos 16t + \frac{C}{16} \sin 16t) & \text{Linearity} \\ \\ x(t) &= A + B \cos 16t + \frac{C}{16} \sin 16t & \text{Lerch's rule} \\ \end{split}$$

The partial fraction problem remains:

$$\frac{s^2 + 1}{s(s^2 + 256)} = \frac{A}{s} + \frac{Bs + C}{s^2 + 256}$$

This problem is solved by clearing the fractions, then swapping sides of the equation, to obtain

$$A(s^{2} + 256) + (Bs + C)(s) = s^{2} + 1.$$

Substitute three values for s to find 3 equations in 3 unknowns A, B, C:

Then A = 1/256, B = 255/256, C = 0 and finally

$$x(t) = A + B\cos 16t + \frac{C}{16}\sin 16t = \frac{1 + 255\cos 16t}{256}$$

Answer Checks

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# Sample quiz 11
# answer check problem 2(a)
f:=t*exp(2*t)+2*t*sin(3*t)+3*exp(-t)*cos(4*t);
with(inttrans): # load laplace package
laplace(f,t,s);
# The last two fractions simplify to 3(s+1)/((s+1)^2+16).
# answer check problem 2(b)
F:=16/(s^2+4)+(s+1)/(s^2-2*s+10)+2/(s^2+16);
invlaplace(F,s,t);
# answer check problem 2(c)
de:=diff(x(t),t,t)+256*x(t)=1;ic:=x(0)=1,D(x)(0)=0;
dsolve([de,ic],x(t));
# answer check problem 2(c), partial fractions
convert((s^2+1)/(s*(s^2+256)),parfrac,s);
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The output appears on the next page

Sample quiz 11 + answer check problem 2(a) > $f:=t^{exp(2^{t}t)+2^{t}t^{s}}sin(3^{t}t)+3^{t}exp(-t)^{t}cos(4^{t}t);$ $f:=te^{2^{t}t}+2tsin(3t)+3e^{-t}cos(4t)$ (1) with(inttrans): # load laplace package > laplace(f,t,s) assuming s::real; $\frac{1}{(s-2)^2} + \frac{12s}{(s^2+9)^2} + \frac{3}{2(s+1-4I)} + \frac{3}{2(s+1+4I)}$ (2) # The last two fractions simplify to 3(s+1)/((s+1)^2+16). # answer check problem 2(b) > F:=16/(s^2+4)+(s+1)/(s^2-2*s+10)+2/(s^2+16); F:= $\frac{16}{s^2+4} + \frac{s+1}{s^2-2s+10} + \frac{2}{s^2+16}$ (3) > invlaplace(F,s,t); $8\sin(2t) + \frac{1}{2}\sin(4t) + \frac{1}{3}e^{t}(3\cos(3t) + 2\sin(3t))$ (4) # answer check problem 2(c) > de:=diff(x(t),t,t)+256*x(t)=1;ic:=x(0)=1,D(x)(0)=0; $de := \frac{d^2}{dt^2} x(t) + 256 x(t) = 1$ ic := x(0) = 1, D(x)(0) = 0(5) > dsolve([de,ic],x(t)); $x(t) = \frac{1}{256} + \frac{255}{256}\cos(16t)$ (6) # answer check problem 2(c), partial fractions > convert((s^2+1)/(s*(s^2+256)), parfrac, s); $\frac{1}{256 s} + \frac{255}{256} \frac{s}{s^2 + 256}$ (7)