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## Math 2250 Extra Credit Problems Chapter 9 S2015

Submitted work. Please submit one stapled package with this sheet on top. Kindly check-mark the problems submitted and label the paper Extra Credit. Label each solved problem with its corresponding problem number, e.g., Xc10.3-20.

## Problem Xc9.1-4. (Phase Portraits)

Find the equilibrium points for the system. Plot a phase diagram using technology.

$$
\left\{\begin{aligned}
\frac{d x}{d t} & =x-2 y+3 \\
\frac{d y}{d t} & =x-y+2
\end{aligned}\right.
$$

Maple Example: Plot the phase diagram of $\mathbf{u}^{\prime}=\left(\begin{array}{ll}1 & 2 \\ 0 & 3\end{array}\right) \mathbf{u}+\binom{4}{5}$ using maple.

```
with(DEtools):
equilEQ:=[0=x+2*y+4,0=3*y+5];
solve(equilEQ,{x,y});# find diagram center (a,b)
a:=-2/3;b:=-5/3;
de:=[diff(x(t),t)=x(t)+2*y(t)+4, diff(y(t),t)=3*y(t)+5];
ic:=[[x(0)=0,y(0)=-1],[x(0)=-1,y(0)=-1.5],[x(0)=0.5,y(0)=-2],
[x(0)=0.5,y(0)=-1.5],[x(0)=-0.7,y(0)=-1.7]];
DEplot(de,[x(t),y(t)],t=-10..10,ic,x=a-2..a+2,y=b-2..b+2,stepsize=0.05);
```

The plot can also be done in maple version $12+$ with the Phase Portrait tool. Start at the TOOLS menu, then TASKS $\longrightarrow$ BROWSE $\longrightarrow$ DIFFERENTIAL EQUATIONS. See the problem notes at the course web site for Chapter 9.

## Problem Xc9.1-8. (Equilibrium Points)

Find the equilibrium points for the system. Plot a phase diagram. The graph window should include the three equilibrium points.

$$
\left\{\begin{array}{l}
\frac{d x}{d t}=x-2 y \\
\frac{d y}{d t}=4 x-x^{3}
\end{array}\right.
$$

## Problem Xc9.1-18. (Stability)

Determine if the equilibrium point $(0,0)$ is stable, asymptotically stable, or unstable. Identify the equilibrium point as a node, saddle, center or spiral by examination of its computer-generated direction field.
(a) $x^{\prime}=y, y^{\prime}=-x$
(b) $x^{\prime}=y, y^{\prime}=-5 x-4 y$
(c) $x^{\prime}=-2 x, y^{\prime}=-2 y$
(d) $x^{\prime}=y, y^{\prime}=x$

## Problem Xc9.2-2. (Classification by Eigenvalues)

Compute the eigenvalues of $A$. Determine stability of equilibrium $(0,0)$ and classify as node (proper/improper), saddle, spiral, center.
(a) $A\left(\begin{array}{rr}0 & 1 \\ -1 & 0\end{array}\right)$
(b) $A\left(\begin{array}{ll}1 & 2 \\ 2 & 1\end{array}\right)$
(c) $A\left(\begin{array}{ll}3 & -2 \\ 4 & -1\end{array}\right)$
(c) $A\left(\begin{array}{ll}1 & -2 \\ 2 & -3\end{array}\right)$

## Problem Xc9.2-12. (Phase Portrait)

Find the equilibrium point (it is unique) and plot by computer a phase diagram.

$$
\left\{\begin{array}{l}
\frac{d x}{d t}=x+y-7 \\
\frac{d y}{d t}=3 x-y-5
\end{array}\right.
$$

## Problem Xc9.2-22. (Almost Linear System)

Linearize the system at its equilibria and determine the stability and type of each. Plot a phase diagram by computer to verify the claims made.

$$
\left\{\begin{array}{l}
\frac{d x}{d t}=2 x-5 y+x^{3} \\
\frac{d y}{d t}=4 x-6 y+y^{4}
\end{array}\right.
$$

## Problem Xc9.3-8. (Predator-Prey System)

Linearize the system at equilibrium point $(0,0)$. Verify that the phase diagram of the nonlinear system at $(0,0)$ is a saddle.

$$
\left\{\begin{aligned}
\frac{d x}{d t} & =x(5-x-y) \\
\frac{d y}{d t} & =y(-2+x)
\end{aligned}\right.
$$

## Problem Xc9.3-9. (Predator-Prey System)

Linearize the system at equilibrium point $(5,0)$. Verify that the phase diagram of the nonlinear system at $(5,0)$ is a saddle.

$$
\left\{\begin{aligned}
\frac{d x}{d t} & =x(5-x-y) \\
\frac{d y}{d t} & =y(-2+x)
\end{aligned}\right.
$$

## Problem Xc9.3-10. (Predator-Prey System)

Linearize the system at equilibrium point $(2,3)$. Verify that the phase diagram of the nonlinear system at $(2,3)$ is an asymptotically stable spiral.

$$
\left\{\begin{aligned}
\frac{d x}{d t} & =x(5-x-y) \\
\frac{d y}{d t} & =y(-2+x)
\end{aligned}\right.
$$

## Problem Xc9.4-4. (Almost Linear System)

Linearize at $(0,0)$ and classify the equilibrium point $(0,0)$ of the nonlinear system, using a phase diagram to verify the conclusion.

$$
\left\{\begin{array}{l}
\frac{d x}{d t}=2 \sin x+\sin y \\
\frac{d y}{d t}=\sin x+2 \sin y
\end{array}\right.
$$

## Problem Xc9.4-8. (Almost Linear System)

Linearize at all equilibria and classify the equilibrium points of the nonlinear system. Use a phase diagram to verify the conclusions.

$$
\left\{\begin{aligned}
\frac{d x}{d t} & =y \\
\frac{d y}{d t} & =\sin \pi x-y
\end{aligned}\right.
$$

End of extra credit problems chapter 9.

