

KEY

Draft 1

Differential Equations and Linear Algebra 2250

Midterm Exam 2

Exam Date: 17 April 2015 at 7:25am

Instructions: This in-class exam is designed to be completed in 80 minutes. No calculators, notes, tables or books. No answer check is expected. Details count 3/4, answers count 1/4.

Chapter 4

Problem 1 (Linear Algebra) Do all parts.

1(a) [10%] For any matrix A , $\text{nullity}(A)$ equals the number of free variables for the problem $A\vec{x} = \vec{0}$. How many pivot columns in a 1000×54 matrix A with $\text{nullity}(A) = 21$? Answer: 33

$= \text{rank}(A)$ $\text{rank} + \text{nullity} = 54$

1(b) [40%] Consider the following matrix and its reduced row echelon form:

$$A = \begin{pmatrix} 1 & -2 & -2 & 0 & 1 \\ 3 & -6 & -5 & 1 & 4 \\ -2 & 4 & 3 & -1 & -3 \end{pmatrix}, \quad \text{rref}(A) = \begin{pmatrix} 1 & -2 & 0 & 2 & 3 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

(b₁) Show all linear algebra steps used to solve $A\vec{x} = \vec{0}$ for $\vec{x}$.

(b₂) Report a basis for the solution space S of $A\vec{x} = \vec{0}$.

(b₃) Report the dimension of S .

$$(b_1) \begin{pmatrix} 1 & -2 & -2 & 0 & 1 \\ 3 & -6 & -5 & 1 & 4 \\ -2 & 4 & 3 & -1 & -3 \end{pmatrix} \xrightarrow{\text{Combo}(1,2,-3)} \begin{pmatrix} 1 & -2 & -2 & 0 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ -2 & 4 & 3 & -1 & -3 \end{pmatrix} \xrightarrow{\text{Combo}(1,3,2)} \begin{pmatrix} 1 & -2 & -2 & 0 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & -1 & -1 & -1 \end{pmatrix} \xrightarrow{\text{Combo}(2,3,1)} \begin{pmatrix} 1 & -2 & -2 & 0 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & -2 & 0 & 2 & 3 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} = \text{last frame, or rref.} \quad \begin{cases} x_1 - 2x_2 + 2x_4 + 3x_5 = 0 \\ x_3 + x_4 + x_5 = 0 \\ 0 = 0 \end{cases}$$

$\text{Combo}(3,1,2)$

Free vars = x_2, x_4, x_5 Lead = x_1, x_3

$$\text{Vector sol} = \vec{x} = \begin{pmatrix} 2t_1 - 2t_2 - 3t_3 \\ t_1 \\ -t_2 - t_3 \\ t_2 \\ t_3 \end{pmatrix}$$

$$\begin{cases} x_1 = 2t_1 - 2t_2 - 3t_3 \\ x_2 = t_1 \\ x_3 = -t_2 - t_3 \\ x_4 = t_2 \\ x_5 = t_3 \end{cases} \quad \text{Scalar Sol.}$$

(b₂) partials on $t_1, t_2, t_3 = \text{Strang's special} =$

$S = \text{Span}(\text{special sols})$

(b₃) $\text{Dim}(S) = 3$ # of basis vectors.

$$\left(\begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 0 \\ -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} \right)$$

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Chapter 4

Problem 1 (Linear Algebra) Continued.

1(c) [20%] Check the independence tests which apply to prove that vectors

$$\begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 3 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 3 \\ 0 \end{pmatrix}$$

are independent in the vector space $\mathcal{R}^4$. Demerits are given for missing a box and also for checking the box for an inapplicable test.

- | | | |
|-------------------------------------|-------------------------|---|
| ☐ | Wronskian test | Wronskian of functions f, g, h nonzero at $x = x_0$ implies independence of f, g, h . |
| ☒ | Rank test | Vectors $\vec{v}_1, \vec{v}_2, \vec{v}_3$ are independent if their augmented matrix has rank 3. |
| ☐ | Determinant test | Vectors $\vec{v}_1, \vec{v}_2, \vec{v}_3$ are independent if their square augmented matrix has nonzero determinant. |
| ☐ | Atom test | Any finite set of distinct Euler solution atoms is independent. |
| ☒ | Pivot test | Vectors $\vec{v}_1, \vec{v}_2, \vec{v}_3$ are independent if their augmented matrix A has 3 pivot columns. |
| ☐ | Sampling test | Let samples a, b, c be given and for functions f, g, h define |

$$A = \begin{pmatrix} f(a) & g(a) & h(a) \\ f(b) & g(b) & h(b) \\ f(c) & g(c) & h(c) \end{pmatrix}.$$

Then $\det(A) \neq 0$ implies independence of f, g, h .

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Chapter 4

Problem 1 (Linear Algebra) Continued.

1(d) [30%] Let v_1, v_2, v_3, v_4 denote the rows of the matrix

$$A = \begin{pmatrix} -2 & 0 & -6 & 0 \\ 2 & 0 & 5 & 1 \\ 1 & 0 & 3 & 0 \\ 1 & 0 & 2 & 1 \end{pmatrix}.$$

Extract from the list v_1, v_2, v_3, v_4 a largest set of independent vectors.

$$\begin{pmatrix} -2 & 2 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ -6 & 5 & 3 & 2 \\ 0 & 1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & 2 & 1 & 1 \\ 0 & -1 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & 2 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Combo(1,3,-3)
Swap rows

rank = 2 = # pivots
pivots = 1, 2

 $\vec{v}_1, \vec{v}_2$ is a largest independent set

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Chapter 5

Problem 2 (Linear Differential Equations of Order n) Do all parts.

2(a) [20%] Mark with **X** the functions which **cannot** be a solution of a linear homogeneous differential equation with constant coefficients. Before marking, apply all algebraic simplifications. Test your choices against this theorem:

The general solution of a linear homogeneous n th order differential equation with constant coefficients is a linear combination of Euler solution atoms.

$1+x^2 \rightarrow$

$e^{\ln(1+x^2)}$	$e^{-x/2}$	$\ln(2) + x^2$	$\cos(x)$
$\sin(\pi x)$	$\frac{x}{1+x}$ X	$e^{ix} + x^3$	$\tan(x)$ X

$\cos(x)$ and $\cos(-x)$, both = $\cos(x)$

2(b) [20%] Determine a **basis of solutions** for a homogeneous constant-coefficient linear differential equation, given the characteristic equation has roots $0, 0, 0; -1, -1; 1 + 2i, 1 - 2i, 1 + 2i, 1 - 2i$.

Basis = $1, x, x^2; e^{-x}, x e^{-x}; e^x \cos 2x, e^x \sin 2x, x e^x \cos 2x, x e^x \sin 2x$

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Chapter 5

Problem 2 (Linear Differential Equations of Order n) Continued.2(c) [40%] Find the steady-state periodic solution for the forced spring-mass system $x'' + 2x' + 5x = 10 \sin(t)$.

Und. Coeff. trial $x(t) = x = d_1 \cos t + d_2 \sin t$ by Rule I
 Rule II does not apply. Substitute trial solution into DE above.

$$(-d_1 \cos t - d_2 \sin t) + 2(-d_1 \sin t + d_2 \cos t) + 5(d_1 \cos t + d_2 \sin t) = 10 \sin t$$

$$(-d_1 + 2d_2 + 5d_1) \cos t + (-d_2 - 2d_1 + 5d_2) \sin t = 10 \sin t$$

$$\begin{cases} 4d_1 + 2d_2 = 0 \\ -2d_1 + 4d_2 = 10 \end{cases}$$

$$d_1 = \frac{\begin{vmatrix} 0 & 2 \\ 10 & 4 \end{vmatrix}}{\begin{vmatrix} 4 & 2 \\ -2 & 4 \end{vmatrix}} = \frac{-20}{20} = -1$$

$$d_2 = \frac{\begin{vmatrix} 4 & 0 \\ -2 & 10 \end{vmatrix}}{20} = \frac{40}{20} = 2$$

$$x_p = d_1 \cos t + d_2 \sin t$$

$$x_p = -\cos t + 2 \sin t$$

→ Because $\lim_{t \rightarrow \infty} x_h = 0$, then $x_p = 2 \sin t - \cos t$ is

The steady-state periodic solution.

Must supply the reason for the steady-state answer.

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Chapter 5

Problem 2 (Linear Differential Equations of Order n) Continued.

2(d) [30%] A homogeneous linear differential equation with constant coefficients has characteristic equation of order 6 with roots 0, 0, 0, 1, $1 + 2i$, $1 - 2i$, listed according to multiplicity. The corresponding non-homogeneous equation for unknown $y(x)$ has right side $f(x) = 3e^{-x} + 4x^2 + 5xe^{-x} \cos 2x + 10e^x \sin 2x$. Determine the undetermined coefficients **shortest** trial solution for y_p .

To save time, do not evaluate the undetermined coefficients and do not find $y_p(x)$!

atoms for f : e^{-x} ; $1, x, x^2$; $e^x \cos 2x, xe^x \cos 2x$; $e^x \sin 2x, xe^x \sin 2x$
 $\uparrow$ $\uparrow$ $\uparrow$ $\uparrow$
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Rule II: atoms = e^{-x} ; x^3, x^4, x^5 ; $xe^x \cos 2x, x^2 e^x \cos 2x$; $xe^x \sin 2x, x^2 e^x \sin 2x$

$y = \text{shortest trial sol} = \text{linear combination of 14 above Euler atoms}$

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Chapter 10

Problem 3. (Laplace Theory) Complete all parts.

It is assumed that you have memorized the basic 4-item Laplace integral table and know the 6 basic rules for Laplace integrals. No other tables or theory are required to solve the problems below. If you don't know a table entry, then leave the expression unevaluated for partial credit.

3(a)[20%] Display the s -fractions for $\mathcal{L}(x(t))$ and $\mathcal{L}(y(t))$ according to Laplace's Method.

$$\begin{cases} x' = 3x + 4y, \\ y' = -2y, \\ x(0) = 1, \quad y(0) = 2. \end{cases}$$

To save time, don't solve for $x(t)$ or $y(t)$!

$$\begin{cases} \mathcal{L}(x') = 3\mathcal{L}(x) + 4\mathcal{L}(y) \\ \mathcal{L}(y') = -2\mathcal{L}(y) \end{cases}$$

$$\begin{cases} s\mathcal{L}(x) - 1 = 3\mathcal{L}(x) + 4\mathcal{L}(y) \\ s\mathcal{L}(y) - 2 = -2\mathcal{L}(y) \end{cases}$$

$$\begin{cases} (s-3)\mathcal{L}(x) + (-4)\mathcal{L}(y) = 1 \\ (0)\mathcal{L}(x) + (s+2)\mathcal{L}(y) = 2 \end{cases}$$

$$\mathcal{L}(x) = \frac{\begin{vmatrix} 1 & -4 \\ s-3 & s+2 \end{vmatrix}}{\begin{vmatrix} s-3 & -4 \\ 0 & s+2 \end{vmatrix}} = \frac{s+2+8}{(s-3)(s+2)} = \boxed{\frac{s+10}{(s-3)(s+2)}}$$

$$\mathcal{L}(y) = \frac{\begin{vmatrix} s-3 & 1 \\ 0 & 2 \end{vmatrix}}{(s-3)(s+2)} = \frac{2(s-3)}{(s-3)(s+2)} = \boxed{\frac{2}{s+2}}$$

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Chapter 10

Problem 3. (Laplace Theory) Continued.

3(b) [30%] Solve for $f(t)$, given

$$\mathcal{L}(f(t))|_{s \rightarrow s-2} + 2 \frac{d}{ds} \mathcal{L}(tf(t)) = \frac{s+1}{(s+2)^2}.$$

$$\mathcal{L}(e^{2t} f(t)) + \mathcal{L}(-2t^2 f(t)) = \frac{s+2}{(s+2)^2} + \frac{-1}{(s+2)^2}$$

$$\mathcal{L}((e^{2t} - 2t^2) f(t)) = \frac{1}{s+2} + \frac{-1}{(s+2)^2}$$

$$'' = \mathcal{L}(e^{-2t}) + \frac{-1}{s^2} \Big|_{s \rightarrow s+2}$$

$$'' = \mathcal{L}(e^{-2t}) + \mathcal{L}(-t) \Big|_{s \rightarrow s+2}$$

$$= \mathcal{L}(e^{-2t}) + \mathcal{L}(-t e^{-2t})$$

$$= \mathcal{L}((1-t)e^{-2t})$$

$$\text{Levick's Thm} \Rightarrow (e^{2t} - 2t^2) f(t) = (1-t)e^{-2t}$$

$$f(t) = \frac{(1-t)e^{-2t}}{e^{2t} - 2t^2}$$

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Chapter 10

Problem 3. (Laplace Theory) Continued.

3(c) [20%] Fill in the blank spaces in the Laplace table:

Forward Table

$f(t)$	$\mathcal{L}(f(t))$
t^3	$\frac{6}{s^4}$
$\cos(4t)$	$\frac{s}{s^2 + 16}$
$(2t + 1)^2$	$\frac{8}{s^3} + \frac{4}{s^2} + \frac{1}{s}$
$t^2 e^{2t}$	$\frac{2}{(s-2)^3}$

Backward Table

$\mathcal{L}(f(t))$	$f(t)$
$\frac{3}{s^2 + 9}$	$\sin 3t$
$\frac{s-2}{s^2 - 4s + 5}$	$e^{2t} \cos(t)$
$\frac{1}{s^3} + \frac{1}{s+1}$	$\frac{t^2}{2} + e^{-t}$
$\frac{s+1}{(s-1)^2}$	$(1+2t)e^t$

$$(2t+1)^2 = 4t^2 + 4t + 1 \rightarrow \frac{4 \cdot 2}{s^3} + \frac{4}{s^2} + \frac{1}{s}$$

$$\mathcal{L}(t^2 e^{2t}) = \mathcal{L}(t^2) \big|_{s \rightarrow s-2} = \frac{2}{s^3} \big|_{s \rightarrow s-2} = \frac{2}{(s-2)^3}$$

$$\begin{aligned} \frac{s-2}{s^2-4s+5} &= \frac{s-2}{(s-2)^2+1} = \frac{s}{s^2+1} \big|_{s \rightarrow s-2} = \mathcal{L}(\cos t) \big|_{s \rightarrow s-2} \\ &= \mathcal{L}(e^{2t} \cos t) \end{aligned}$$

$$\begin{aligned} \frac{s+1}{(s-1)^2} &= \frac{s-1}{(s-1)^2} + \frac{2}{(s-1)^2} = \frac{1}{s-1} + \frac{2}{(s-1)^2} = \left(\frac{1}{s} + \frac{2}{s^2} \right) \big|_{s \rightarrow s-1} \\ &= \mathcal{L}(1+2t) \big|_{s \rightarrow s-1} = \mathcal{L}((1+2t)e^t) \end{aligned}$$

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Chapter 10

Problem 3. (Laplace Theory) Continued.

3(d) [30%] Laplace's method is applied to the problem

$$\begin{cases} x'' + 2x' + x = e^t, \\ x(0) = 0, \quad x'(0) = 1, \end{cases}$$

finding the answer $x(t) = \frac{1}{2} \sinh(t) + \frac{1}{2} t e^{-t}$. Display the Laplace solution steps used to obtain the answer $x(t)$. Check the correctness of your answer with identity $\sinh(u) = \frac{1}{2} e^u - \frac{1}{2} e^{-u}$.

$$\mathcal{L}(x'') + 2\mathcal{L}(x') + \mathcal{L}(x) = \mathcal{L}(e^t)$$

$$s\mathcal{L}(x') - x'(0) + 2(s\mathcal{L}(x) - x(0)) + \mathcal{L}(x) = \frac{1}{s-1}$$

$$s(s\mathcal{L}(x) - x(0)) - 1 + 2s\mathcal{L}(x) + \mathcal{L}(x) = \frac{1}{s-1}$$

$$(s^2 + 2s + 1)\mathcal{L}(x) = 1 + \frac{1}{s-1} = \frac{s-1+1}{s-1}$$

$$\mathcal{L}(x) = \frac{s-1+1}{(s-1)(s^2+2s+1)}$$

$$\mathcal{L}(x) = \frac{s}{(s-1)(s+1)^2}$$

$$\mathcal{L}(x) = \frac{A}{s-1} + \frac{B}{s+1} + \frac{C}{(s+1)^2}$$

$$\mathcal{L}(x) = \mathcal{L}(Ae^t + Be^{-t} + Cte^{-t})$$

$$x(t) = Ae^t + Be^{-t} + Cte^{-t}$$

clear fractions: $s = A(s+1)^2 + B(s-1)(s+1) + C(s-1)$

Sampling method

$$\begin{aligned} s=1 &: 1 = 4A \\ s=-1 &: -1 = -2C \\ s=0 &: 0 = A + B(-1) + C(-1) \end{aligned}$$

$$\begin{aligned} A &= \frac{1}{4} \\ C &= \frac{1}{2} \\ B &= -\frac{1}{4} \end{aligned}$$

Use this page to start your solution.

Answer check: $\frac{1}{2} \sinh(t) + \frac{1}{2} t e^{-t} = \frac{1}{4} e^t - \frac{1}{4} e^{-t} + \frac{1}{2} t e^{-t}$
 $= Ae^t + Be^{-t} + Cte^{-t}$
 $= x(t) \quad \checkmark$

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Chapter 6

Problem 4. (Eigenanalysis) Complete all parts.

4(a) [30%] Let $A = \begin{pmatrix} 6 & -4 & 4 \\ 8 & -6 & 11 \\ 0 & 0 & 5 \end{pmatrix}$. The eigenpairs are reported to be

$$\left(-2, \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}\right), \left(2, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}\right), \left(5, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}\right).$$

Circle any incorrect eigenpairs.

$$\begin{pmatrix} 6 & -4 & 4 \\ 8 & -6 & 11 \\ 0 & 0 & 5 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 6-8 \\ 8-12 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 \\ -4 \\ 0 \end{pmatrix} = -2 \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \quad \text{Eigenpair } \checkmark$$

$$\begin{pmatrix} 6 & -4 & 4 \\ 8 & -6 & 11 \\ 0 & 0 & 5 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 6 \\ 13 \\ 5 \end{pmatrix} \neq \lambda \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \text{Not an eigenpair}$$

$$\begin{pmatrix} 6 & -4 & 4 \\ 8 & -6 & 11 \\ 0 & 0 & 5 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -6+11 \\ 5 \end{pmatrix} = \begin{pmatrix} 0 \\ +5 \\ 5 \end{pmatrix} = 5 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \quad \text{Eigenpair } \checkmark$$

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Chapter 6

Problem 4. (Eigenanalysis) Continued.

4(b) [40%] Find the eigenpairs of the matrix $A = \begin{pmatrix} -0.9 & 0.3 \\ 0.3 & -0.1 \end{pmatrix}$.

$$\begin{vmatrix} -0.9 - \lambda & 0.3 \\ 0.3 & -0.1 - \lambda \end{vmatrix} = 0 \rightarrow \begin{aligned} &(-0.9 - \lambda)(-0.1 - \lambda) - (0.3)^2 = 0 \\ &.09 + .1\lambda + .9\lambda + \lambda^2 - .09 = 0 \\ &\lambda^2 + \lambda = 0 \\ &\lambda(\lambda + 1) = 0 \\ &\boxed{\lambda = 0, \lambda = -1} \end{aligned}$$

$$\begin{pmatrix} -9/10 & 3/10 & | & 0 \\ 3/10 & -1/10 & | & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 0 & | & 0 \\ 3/10 & -1/10 & | & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 3 & -1 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix}$$

$$\begin{cases} 3x_1 - x_2 = 0 \\ 0 = 0 \end{cases} \quad \begin{cases} x_1 = \frac{1}{3}t_1 \\ x_2 = t_1 \end{cases} \quad \boxed{\left(0, \begin{pmatrix} 1/3 \\ 1 \end{pmatrix}\right) = \text{Eigenpair}}$$

$$\begin{pmatrix} -9/10 + 1 & 3/10 & | & 0 \\ 3/10 & -1/10 + 1 & | & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1/10 & 3/10 & | & 0 \\ 3/10 & 9/10 & | & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 3 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix}$$

$$\begin{cases} x_1 + 3x_2 = 0 \\ 0 = 0 \end{cases} \quad \begin{cases} x_1 = -3t_1 \\ x_2 = t_1 \end{cases} \quad \boxed{\left(-1, \begin{pmatrix} -3 \\ 1 \end{pmatrix}\right) = \text{Eigenpair}}$$

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Chapter 6

Problem 4. (Eigenanalysis) Continued.

4(c) [30%] The vector general solution $\vec{u}(t)$ of a linear differential system $\frac{d}{dt}\vec{u} = A\vec{u}$ is given by a formula involving the eigenpairs of $n \times n$ diagonalizable matrix A .

Assume $A = \begin{pmatrix} -0.9 & 0.3 \\ 0.3 & -0.1 \end{pmatrix}$. Find the general solution $\vec{u}$ of the system $\frac{d}{dt}\vec{u} = A\vec{u}$.

$$\vec{u} = c_1 e^{0t} \begin{pmatrix} 1/3 \\ 1 \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} -3 \\ 1 \end{pmatrix}$$

use eigenpairs from 4(b)

Use this page to start your solution.