## Phase Portraits for Autonomous Systems

Plot an autonomous system of two ODEs, including the direction field, critical point(s), and phase portraits as desired.

## **Instructions**

- To begin, enter the necessary information into the fields below:
  - the bounds for the plot window
  - F(x, y) and G(x, y), the right-hand sides of the autonomous ODEs  $\dot{x} = F(x, y)$  and  $\dot{y} = G(x, y)$
  - one equilibrium (critical) point as a list [a, b], and multiple such points in a sequence [a, b], [c, d]
  - bounds for *t*, the independent variable of the ODEs, and hence, the parameter along orbits (trajectories or paths)
- Click the **Enter Data** button to obtain a direction field and all entered equilibrium (critical) points.
- ullet Click on the plot area and select the Click and Drag Manipulator (  $\bullet$  ) from the Plot menu

or plotting toolbar. Then click anywhere in the direction field to create a phase portrait through that point.

• The **Erase Phase Portrait** button erases all orbits and field arrows. The **Clear All** button clears every field in the template.

## Plot Window $\begin{array}{c} -10 \\ \hline -5 \\ \le y \le 5 \end{array}$ Differential Equations $\dot{x} = F(x, y) = y$ $\dot{y} = G(x, y) = y$ $-\sin(x) - y$ Equilibrium (Critical) Points $\begin{array}{c} \text{Equilibrium (Critical) Points} \end{array}$

[0, 0], [-Pi, 0], [Pi, 0]	
Parameter $-5$ $\leq t \leq$	
Enter Data	