

KEY

Differential Equations and Linear Algebra 2250-2

Midterm Exam 3, Spring 2007

Version 2: 10:45

Calculators, books, notes and computers are not allowed. Answer checks are not expected or required. First drafts are expected, not complete presentations. The midterm exam has 5 problems, some with multiple parts, suitable for 50 minutes.

1. (ch4) Complete enough of the following to add to 100%.

(a) [100%] Let V be the vector space of all continuous functions defined on $0 \leq x \leq 1$. Define S to be the set of all continuously differentiable functions $f(x)$ in V such that $f'(1) = f(0) + \int_0^1 x f(x^2) dx$. Prove that S is a subspace of V , by using the Subspace Criterion.

(b) [30%] If you solved (a), then skip (b) and (c). Let V be the set of all 4×1 column vectors \mathbf{x} with components x_1, x_2, x_3, x_4 . Assume the usual \mathcal{R}^4 rules for addition and scalar multiplication. Let S be the subset of V defined by the equations $C\mathbf{x} = \mathbf{0}$, $\mathbf{b} \cdot \mathbf{x} = 0$, where C is a 2×4 matrix and \mathbf{b} is a nonzero vector in V . Prove that S is a subspace of V .

(c) [70%] If you solved (a), then skip (b) and (c). Solve for the unknowns x_1, x_2, x_3, x_4 in the system of equations below by showing all details of a frame sequence from the augmented matrix C to $\text{rref}(C)$. Report the **vector form** of the general solution.

$$\begin{array}{cccccc} x_1 & + & 2x_2 & - & 2x_3 & + & 3x_4 & = & 1 \\ & & & + & x_2 & + & 2x_3 & + & & = & 1 \\ x_1 & + & 3x_2 & + & & + & 3x_4 & = & 2 \\ x_1 & + & 4x_2 & + & 2x_3 & + & 3x_4 & = & 3 \end{array}$$

(a) $\vec{0}$ in S : Define $\vec{0}$ by equation $f(x) = 0$. Then $f'(1) = 0$ and $f(0) + \int_0^1 x f(x^2) dx = 0 + 0 = 0$ implies $\vec{0}$ in S .

$c_1 \vec{v}_1 + c_2 \vec{v}_2$ in S : Define \vec{v}_1, \vec{v}_2 by eqs f_1, f_2 . Define $\vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2$. Then $f = c_1 f_1 + c_2 f_2$ is the eq for \vec{v} .

$$\begin{aligned} f'(1) &= c_1 f_1'(1) + c_2 f_2'(1) = c_1 (f_1(0) + \int_0^1 x f_1(x^2) dx) + c_2 (f_2(0) + \int_0^1 x f_2(x^2) dx) \\ &= (c_1 f_1(0) + c_2 f_2(0)) + \int_0^1 x (c_1 f_1(x^2) + c_2 f_2(x^2)) dx \\ &= f(0) + \int_0^1 x f(x) dx \end{aligned}$$

proof complete by the subspace criterion.

(b) Define $A = \text{aug}(\text{row}(c, 1), \text{row}(c, 2), \mathbf{b}^T)$. Then $A\vec{x} = \vec{0} \Leftrightarrow C\vec{x} = \vec{0}$ and $\mathbf{b}^T \vec{x} = 0$ (or $\mathbf{b} \cdot \vec{x} = 0$). Apply the kernel theorem. Then S is a subspace of \mathcal{R}^4 .

$$A = \left(\begin{array}{cccc|c} 1 & 2 & -2 & 3 & 1 \\ 0 & 1 & 2 & 0 & 2 \\ 1 & 3 & 0 & 3 & 0 \\ 1 & 4 & 2 & 3 & 3 \end{array} \right) \quad \text{rref}(A) = \left(\begin{array}{cccc|c} 1 & 0 & -6 & 3 & 1 \\ 0 & 1 & 2 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$\begin{cases} x_1 - 6x_3 + 3x_4 = 1 \\ x_2 + 2x_3 = 2 \\ 0 = 0 \\ 0 = 0 \end{cases}$$

Reduced Echelon Sys

$$\begin{cases} x_1 = 1 + 6t_1 - 3t_2 \\ x_2 = -3t_1 \\ x_3 = t_1 \\ x_4 = t_2 \end{cases}$$

general solution

$$\vec{x} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + t_1 \begin{pmatrix} 6 \\ -3 \\ 1 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} -3 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

vector general solution

Start your solution on this page. Staple on extra pages as needed.

2. (ch5) Complete (a), (b) and then either (c) or (d). Do not do both (c) and (d).

(a) [30%] Given $8x''(t) + 26x'(t) + 21x(t) = 0$, which represents a damped spring-mass system with $m = 8$, $c = 26$, $k = 21$, solve the differential equation [20%] and classify the answer as over-damped, critically damped or under-damped [10%].

(b) [20%] Find a particular solution $y_p(t)$ and the homogeneous solution $y_h(x)$ for $y^{iv} + 4y'' = 10$.

(c) [50%] Find by undetermined coefficients the steady-state periodic solution for the equation $x'' + 4x' + 5x = 3\sin(2t)$.

(d) [50%] If you did (c) above, then skip this one! Find by variation of parameters a particular solution x_p for the equation $x'' + 4x' + 5x = e^{t^3} \tan(t^2)$. To save time, don't try to evaluate integrals (it's impossible).

(a) $(2r+3)(4r+7)=0$ $x(t) = c_1 e^{-3t/2} + c_2 e^{-7t/4}$ over-damped

(b) $r^2(r^2+4)=0$ Trial sol $y = d_1 x^2$ by the fixup rule
 $y_p = \frac{10}{4} \frac{x^2}{2} = \frac{5x^2}{4}$ $x_h = c_1 + c_2 x + c_3 \cos 2x + c_4 \sin 2x$
 $y = y_h + y_p$

(c) $x_{ss} = \frac{-24}{65} \cos(2t) + \frac{3}{65} \sin(2t)$. Define $x = d_1 \cos 2t + d_2 \sin 2t$.
 No fixup rule. Get equations $\begin{cases} d_1 + 8d_2 = 0 \\ -8d_1 + d_2 = 3 \end{cases}$. Solve, $d_1 = \frac{-24}{65}$, $d_2 = \frac{3}{65}$.

(d) $(r+2)^2 + 1 = 0$. atoms = $e^{-2t} \cos t, e^{-2t} \sin t$. $W = e^{-4t}$, $x_1 = \text{First atom}$,
 $x_2 = \text{second atom}$, $f = e^{t^3} \tan(t^2)$.

$$x_p = \left(- \int \frac{x_2 f}{W} \right) x_1 + \left(\int \frac{x_1 f}{W} \right) x_2$$

$$x_p = \left(- \int e^{2t} \sin t e^{t^3} \tan(t^2) dt \right) e^{-2t} \cos t$$

$$+ \left(\int e^{2t} \cos t e^{t^3} \tan(t^2) dt \right) e^{-2t} \sin t$$

Start your solution on this page. Staple on extra pages as needed.

3. (ch5) Complete all parts below.

(a) [70%] A non-homogeneous linear differential equation with constant coefficients has right side $f(x) = xe^x + 2(x+1)(x^2+2) + x \cos 2x$ and characteristic equation $r^2(r-1)^3(r^2+4) = 0$. Determine the **corrected** trial solution for y_p according to the method of undetermined coefficients and the **fixup rule**. To save time, **do not** evaluate the undetermined coefficients and **do not** find $y_p(x)$! Undocumented detail or guessing earns no credit.

(b) [30%] Write out the general solution of the homogeneous linear constant coefficient equation whose characteristic equation is $(r^3+r)^2(r^2+r)^3(r^2+4r)^3 = 0$.

(a) atoms of $f = 1, x, x^2, x^3, e^x, xe^x, \cos 2x, \sin 2x, x \cos 2x, x \sin 2x$

Char eq roots = $0, 0, 1, 1, 1, 2i, -2i$

$$y = x^2 (d_1 + d_2 x + d_3 x^2 + d_4 x^3)$$

atom root = 0

$$+ x^3 (d_5 e^x + d_6 x e^x)$$

atom root = 1

$$+ x (d_7 \cos 2x + d_8 \sin 2x + d_9 x \cos 2x + d_{10} x \sin 2x) \quad \text{atom root} = 2i$$

(b) $r^2(r^2+1)^2 r^3(r+1)^3 r^3(r+4)^3 = 0$

roots = $0, 0, 0, 0, 0, 0, 0, 0, i, -i, i, -i, -1, -1, -1, -4, -4, -4$

$$y = c_1 + c_2 x + c_3 x^2 + c_4 x^3 + c_5 x^4 + c_6 x^5 + c_7 x^6 + c_8 x^7$$

$$+ (c_9 + c_{10} x) \cos x + (c_{11} + c_{12} x) \sin x$$

$$+ (c_{13} + c_{14} x + c_{15} x^2) e^{-x}$$

$$+ (c_{16} + c_{17} x + c_{18} x^2) e^{-4x}$$

Start your solution on this page. Staple on extra pages as needed.

4. (ch6) Complete all of the items below.

(a) [30%] Find the eigenvalues of the matrix $A = \begin{pmatrix} 4 & -2 & 1 & 12 \\ 2 & 4 & -3 & 15 \\ 0 & 0 & 3 & 7 \\ 0 & 0 & -1 & -5 \end{pmatrix}$. To save time, **do not** find eigenvectors!

(b) [40%] Given $A = \begin{pmatrix} 1 & 1 & -1 \\ 0 & 3 & 1 \\ 0 & 1 & 3 \end{pmatrix}$, assume there exists an invertible matrix P and a diagonal matrix D such that $AP = PD$. Circle all possible columns of P from the list below.

$$\begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \\ -1 \end{pmatrix}$$

(c) [30%] Find all eigenpairs for the matrix $A = \begin{pmatrix} 1 & 2 \\ -2 & 1 \end{pmatrix}$. Expect complex numbers in the answers.

Ⓐ Cofactor expansion gives $\det(A - \lambda I) = \text{polynomial of degree 4}$.
The roots are $\lambda = 2, -4, 4 \pm 2i$

Ⓑ $\begin{pmatrix} 1 & 1 & -1 \\ 0 & 3 & 1 \\ 0 & 1 & 3 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \\ 4 \end{pmatrix} \neq \lambda \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$ for any λ . Not an eigenvector.
The others work.

Ⓒ $\det(A - \lambda I) = (1 - \lambda)^2 + 4$. Roots $1 \pm 2i$

$$B = A - (1 + 2i)I$$

$$= \begin{pmatrix} -2i & 2 \\ -2 & -2i \end{pmatrix}$$

$$\begin{pmatrix} -i & 1 \\ 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & i \\ 0 & 0 \end{pmatrix}$$

$$\begin{cases} x_1 + ix_2 = 0 \\ 0 = 0 \end{cases}$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = t_1 \begin{pmatrix} -i \\ 1 \end{pmatrix}$$

choose $\vec{v}_1 = \begin{pmatrix} -i \\ 1 \end{pmatrix}$
 $\vec{v}_2 = \text{conjugate of } \vec{v}_1 = \begin{pmatrix} i \\ 1 \end{pmatrix}$

$$\text{Eigenpairs} = \left(2i, \begin{pmatrix} -i \\ 1 \end{pmatrix} \right), \left(-2i, \begin{pmatrix} i \\ 1 \end{pmatrix} \right)$$

Start your solution on this page. Staple on extra pages as needed.

5. (ch6) Complete all parts below.

Consider the 3×3 matrix

$$A = \begin{pmatrix} 4 & 2 & -2 \\ 0 & 3 & 1 \\ 0 & 1 & 3 \end{pmatrix}.$$

Already computed are eigenpairs

$$\left(2, \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \right), \left(4, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right).$$

- (a) [25%] Find the remaining eigenpairs of A .
 (b) [25%] Display an invertible matrix P and a diagonal matrix D such that $AP = PD$.
 (c) [25%] Display explicitly Fourier's model for A .
 (d) [25%] Display the vector general solution $\mathbf{x}(t)$ of the linear differential system $\mathbf{x}' = A\mathbf{x}$.

Ⓐ $\det(A - \lambda I) = (4 - \lambda)((3 - \lambda)^2 - 1) = (4 - \lambda)(2 - \lambda)(4 - \lambda)$

$B = A - 4I$
 $= \begin{pmatrix} 0 & 2 & -2 \\ 0 & -1 & 1 \\ 0 & 1 & -1 \end{pmatrix}$

$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = t_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$

$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \text{ rref}(B)$

Last eigenpair = $\left(4, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right)$

Ⓑ $D = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} \quad P = \begin{pmatrix} 2 & 1 & 0 \\ -1 & 0 & 1 \\ 1 & 0 & 1 \end{pmatrix}$

Ⓒ $A \left(c_1 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_3 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right) = c_1 (2) \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + c_2 (4) \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_3 (4) \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$

Ⓓ $\vec{x}(t) = c_1 e^{2t} \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + c_2 e^{4t} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_3 e^{4t} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$

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