Differential Equations and Linear Algebra 2250 Midterm Exam 2 [12:25 lecture]

Version 27.10.2010 West

Scores
1.
2.
3.

Instructions: This in-class exam is 50 minutes. No calculators, notes, tables or books. No answer check is expected. Details count 3/4, answers count 1/4.

1. (The 3 Possibilities with Symbols)

Let a, b and c denote constants and consider the system of equations

$$\begin{pmatrix} -b & -1 & 0 \\ b & 1 & a \\ c+b & 3 & a \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ a^2+a \\ a^2 \end{pmatrix}$$

(a) [40%] Determine a, b and c such that the system has a unique solution. $a(-2b+c) \neq 0$

(b) [30%] Determine a, b and c such that the system has no solution. -2b+c=0, $a \neq 0$

(c) [30%] Determine a, b and c such that the system has infinitely many solutions. q = 0

(a)
$$\begin{vmatrix} -b & -1 & 0 \\ b & 1 & 0 \end{vmatrix} = -a(-2b+c) \Rightarrow \text{ unique Sol for } a(-2b+c) \neq 0$$

(b) 3 a

Combo (1,2,1) combo (1,3,3) when C-2b=0 (So That (a) fails), Ten There is a signal equation 0=a (from combo (3,2,-1)) for any $a \neq 0$, No Sol for $a \neq 0$ and C-2b=0. Part (a) fails also for a=0, but This is hardled in (c) below.

(c) when a=0, Pen The suptam is homogeneous with at least The sol x=y=z=0, so case (b) does not happen. Phere is a now of here in The last frame of (b). This implies co-many sols for $a \neq 0$. There is no condition on symbols by.

Use this page to start your solution. Attach extra pages as needed.

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- 2. (Vector Spaces) Do all parts. Details not required for (a)-(d).
 - (a) [10%] True or false: Assume subspace S of \mathbb{R}^3 contains vectors $\begin{pmatrix} 1\\1\\0 \end{pmatrix}$ and $\begin{pmatrix} 1\\0\\1 \end{pmatrix}$. Then $\begin{pmatrix} 3\\2\\1 \end{pmatrix}$ is
 - (b) [10%] True or false: The set of all linear combinations of functions x, e^x , $\sin(x)$ forms a subspace Sof the vector space of all functions on $-\infty < x < \infty$.
 - (c) [10%] True or false: Relations $\ln(1+x^2)=0, y+z=0$ define a subspace in \mathbb{R}^3 .
 - (d) [10%] True or false: Equations 2x + y = 0, 3y + 4z = 0 define a subspace in \mathbb{R}^3 .
 - (e) [20%] State one theorem, without proof, that concludes that all linear combinations of the matrices
 - and $\begin{pmatrix} 2 & 0 \\ 1 & 3 \end{pmatrix}$ forms a subspace S of the vector space V of all 2×2 matrices.
 - (f) [40%] Find a basis of vectors for the subspace of \mathbb{R}^4 given by the system of restriction equations

- (a) $I\left(\begin{pmatrix} 1\\0\\0\end{pmatrix}+I\left(\begin{pmatrix} 1\\0\\1\end{pmatrix}=\begin{pmatrix} 3\\1\\1\end{pmatrix}\right)$
- (b) sponn theorem
- (c) $\begin{cases} \ln(1+x^2)=0 \\ y+z=0 \end{cases}$ (=) $\begin{cases} x=0 \\ y+z=0 \end{cases}$ ternel theorem
- (d) (2x+y=0 karnel theorem
- (e) Spor theorem

Let vi, v2,..., ve be vectors in the space V. Then the set spon(v,,,,ve) of all linear combinations of vivering is a subspace of V.

V- spece of metrices . 2x2.

$$k = 2$$

$$V_1 = \begin{pmatrix} 1 & 0 \\ 2 & 2 \end{pmatrix}$$

$$V_2 = \begin{pmatrix} 2 & 0 \\ 1 & 3 \end{pmatrix}$$

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- 3. (Independence and Dependence) Do all parts.
 - (a) [10%] State an independence test for 3 vectors in \mathbb{R}^3 . Write the hypothesis and conclusion, not just the name of the test.
 - (b) [10%] State two more independence tests [different than (a)] for 3 vectors in \mathbb{R}^3 .
 - (c) [10%] **Define** what it means for column 2 of a 4×4 matrix A to be a non-pivot column of A.
 - (d) [30%] Let $\mathbf{u}_1,\ \mathbf{u}_2,\ \mathbf{u}_3$ denote the rows of the matrix

$$A = \left(\begin{array}{rrrr} 0 & 1 & 0 & 2 & 1 \\ 1 & 2 & 0 & 5 & 1 \\ 0 & 1 & 0 & 3 & 0 \end{array}\right).$$

Display the details of an independence test for the vectors \mathbf{u}_1 , \mathbf{u}_2 , \mathbf{u}_3 .

(e) [40%] Extract from the list below a largest set of independent vectors.

$$\mathbf{v}_{1} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \mathbf{v}_{2} = \begin{pmatrix} 0 \\ 2 \\ 2 \\ -2 \\ 2 \end{pmatrix}, \mathbf{v}_{3} = \begin{pmatrix} 0 \\ 1 \\ 1 \\ -1 \\ 1 \end{pmatrix}, \mathbf{v}_{4} = \begin{pmatrix} 0 \\ 3 \\ 3 \\ -3 \\ 3 \end{pmatrix}, \mathbf{v}_{5} = \begin{pmatrix} 0 \\ 4 \\ 4 \\ 2 \\ 10 \end{pmatrix}, \mathbf{v}_{6} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 2 \\ 2 \end{pmatrix}, \mathbf{v}_{7} = \begin{pmatrix} 0 \\ 3 \\ 3 \\ -1 \\ 5 \end{pmatrix}.$$

- If A = ang(v, vz,vz), then v, vz,vz are independent (det (A) +0. (Deferminant test) * We can only apply this test since A is square.
- (b) rank test, pivot theorem
- (c) Col. 2 of a 4x4 matrix A is a non-pivot column of A if it can be written as a linear combination of the pivot columns, which are the columns of A which correspond to columns of rref(A) with leading ones.

$$\text{ref}(A) = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & -1 \end{pmatrix} \Rightarrow \text{rank}(A) = 3 \Rightarrow \text{LI rows}.$$

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Pivot theorem > {V2, V5} is a largest L.I. set.

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Instructions: This in-class exam is 50 minutes. No calculators, notes, tables or books. No answer check is expected. Details count 3/4, answers count 1/4.

4. (Determinants) Do all parts.

(a) [20%] Cramer's Rule for the system $A\mathbf{x} = \mathbf{v}$ displays the unique solution \mathbf{x} componentwise as quotients of $n \times n$ determinants. Write out, without computing any determinant values, the formulas for

 $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad \mathbf{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}, \quad \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}.$

(b) [30%] Assume given 4×4 matrices A, B. Suppose $E_3B^3 = 2(E_2E_1A)$ and E_1 , E_2 , E_3 are elementary matrices representing respectively a combination, a swap and a multiply by 5. Assume det(A) = -4. Find det(B).

(c) [20%] Determine all values of x for which B^{-1} exists, where $B = \begin{pmatrix} 1 & 2x - 1 & 3x & 1 & 1 \\ 2 & 0 & 2 & 1 \\ 3x & 0 & 10 & 0 \\ 1 & 1 & 1 & 0 \end{pmatrix}$.

(d) [30%] Apply the adjugate [adjoint] formula for the inverse to find the value of the entry in row 3, column 2 of $(2I+B)^{-1}$, where I is the identity matrix and B is given below. Other methods are not acceptable.

acceptable.
$$B = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 0 \\ -1 & 2 & -1 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 2 & 1 \\ 2 & 0 & 1 \\ 2 & 0 & 1 \end{pmatrix}, \quad \lambda_2 = \frac{\begin{vmatrix} a & v_1 \\ c & v_2 \end{vmatrix}}{\begin{vmatrix} a & b \\ c & d \end{vmatrix}}$$

 $|E_3||B||B||B| = |2I||E_2||E_1||A|| \Rightarrow 5||B||^3 = 2^4(-1)(1)(-4) \Rightarrow |B| = 3||64||$ OBSERVE I is $4\times 4 \Rightarrow |2I| = \text{product of diagonal elements} = 2.2.2.2 = 2^4$

B-1 exists () |B| + 0. Expand |B| by cofactors along col= 4, Non (E)

(1) $=\frac{(-1)\begin{vmatrix} 3 & 1 \\ -1 & 2 \end{vmatrix}}{|A|}$

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- 5. (Linear Differential Equations) Do all parts.
 - (a) [20%] Solve for the general solution of y''' + 8y'' + 32y' = 0.
 - (b) [40%] The characteristic equation is $r^2(r^2-r)^2(r^2+2r+5)^2(r^2+16)=0$. Find the general solution y of the linear homogeneous constant-coefficient differential equation.
 - (c) [20%] A fourth order linear homogeneous differential equation with constant coefficients has two solutions $e^{2x}\cos x$ and $e^{-x}\sin x$. What are the roots of the characteristic equation?
 - (d) [20%] A linear homogeneous differential equation with constant coefficients with characteristic equation roots r = 0, 0, 1, 1, 1, 1 + 2i, 1 - 2i, listed according to multiplicity, is solved incorrectly and then initial conditions are applied to give a particular solution

$$y(x) = xe^x + (2x^3e^x) + \frac{11}{7}e^x \sin(2x) + (15xe^{-x} + e^{-x})$$

Circle the terms in the solution which are certainly in error.

- $\Upsilon((r+4)^2+16)=0$, roots = 0, -4±4i, atoms=1, $e^{4x}\cos(4x)$, $e^{4x}\sin(4x)$ y=1.c. 1 3 atoms
- r4 (r-1)2 ((r+1)2+4)(r2+16)=0 Y= 0,0,0,0,1,1,-1 ± 2i,-1 ± 2i, +4i $e^{toms} = 1, x, x^2, x^3$ e^{x}, xe^{x} ex cos(2x), xexcos(2x) ex sin(2x), x ex sin (2x)

8 = 1.c. of The 12 atoms

- eax cos(bx), eax smi(bx) come from Euler's Theorem with roots q±ib
- (a) roots = 1,1,1,1 produce x^3e^x , by Euler's Theorem roots = -1,-1 produce $x \in x$, "

 not =-1 produce e^x) Because -1 is not a root of the characteristic equatur, then the last two turns (minology ex) are in even. The term $2x^3e^{\times}$ is an euro because I is a triple root of Re characteristic equation, not a guard root.