

**Elementary Matrices** An elementary matrix  $E$  is the result of applying a combination, multiply or swap rule to the identity matrix. The computer algebra system maple displays typical  $4 \times 4$  elementary matrices (C=Combination, M=Multiply, S=Swap) as follows.

<pre>with(linalg): Id:=diag(1,1,1,1); C:=addrow(Id,2,3,c); M:=mulrow(Id,3,m); S:=swaprow(Id,1,4);</pre>	<pre>with(LinearAlgebra): Id:=IdentityMatrix(4); C:=RowOperation(Id,[3,2],c); M:=RowOperation(Id,3,m); S:=RowOperation(Id,[4,1]);</pre>
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The answers:

$$C = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & c & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \quad M = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & m & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

$$S = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}.$$

### Constructing elementary matrices $E$

- Mult** Change a one in the identity matrix to symbol  $m \neq 0$ .
- Combo** Change a zero in the identity matrix to symbol  $c$ .
- Swap** Interchange two rows of the identity matrix.

### Constructing $E^{-1}$ from elementary matrix $E$

- Mult** Change diagonal multiplier  $m \neq 0$  in  $E$  to  $1/m$ .
- Combo** Change multiplier  $c$  in  $E$  to  $-c$ .
- Swap** The inverse of  $E$  is  $E$  itself.

**Theorem 1** (The `rref` and elementary matrices)

Let  $A$  be a given matrix of row dimension  $n$ . Then there exist  $n \times n$  elementary matrices  $E_1, E_2, \dots, E_k$  such that

$$\text{rref}(A) = E_k \cdots E_2 E_1 A.$$

The result is the observation that left multiplication of matrix  $A$  by elementary matrix  $E$  gives the answer  $EA$  for the corresponding multiply, combination or swap operation. The matrices  $E_1, E_2, \dots$  represent the multiply, combination and swap operations performed in the frame sequence which take the First Frame into the Last Frame, or equivalently, original matrix  $A$  into  $\text{rref}(A)$ .

## A certain 6-frame sequence.

$$A_1 = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 4 & 0 \\ 3 & 6 & 3 \end{pmatrix} \quad \text{Frame 1, original matrix.}$$

$$A_2 = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 0 & -6 \\ 3 & 6 & 3 \end{pmatrix} \quad \text{Frame 2, combo(1,2,-2).}$$

$$A_3 = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 0 & 1 \\ 3 & 6 & 3 \end{pmatrix} \quad \text{Frame 3, mult(2,-1/6).}$$

$$A_4 = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & -6 \end{pmatrix} \quad \text{Frame 4, combo(1,3,-3).}$$

$$A_5 = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{Frame 5, combo(2,3,-6).}$$

$$A_6 = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{Frame 6, combo(2,1,-3). Found rref}(A_1).$$

The corresponding  $3 \times 3$  elementary matrices are

$$E_1 = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{Frame 2, combo(1,2,-2) applied to } I.$$

$$E_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1/6 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{Frame 3, mult(2,-1/6) applied to } I.$$

$$E_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{pmatrix} \quad \text{Frame 4, combo(1,3,-3) applied to } I.$$

$$E_4 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -6 & 1 \end{pmatrix} \quad \text{Frame 5, combo(2,3,-6) applied to } I.$$

$$E_5 = \begin{pmatrix} 1 & -3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{Frame 6, combo(2,1,-3) applied to } I.$$

The frame sequence can be written as follows.

$$A_2 = E_1 A_1$$

Frame 2,  $E_1$  equals  
combo(1,2,-2) on  $I$ .

$$A_3 = E_2 A_2$$

Frame 3,  $E_2$  equals  
mult(2,-1/6) on  $I$ .

$$A_4 = E_3 A_3$$

Frame 4,  $E_3$  equals  
combo(1,3,-3) on  $I$ .

$$A_5 = E_4 A_4$$

Frame 5,  $E_4$  equals  
combo(2,3,-6) on  $I$ .

$$A_6 = E_5 A_5$$

Frame 6,  $E_5$  equals  
combo(2,1,-3) on  $I$ .

$$A_6 = E_5 E_4 E_3 E_2 E_1 A_1$$

Summary frames 1-6.

Then

$$\text{rref}(A_1) = E_5 E_4 E_3 E_2 E_1 A_1,$$

which is the result of the Theorem.

The summary:

$$\mathbf{A}_6 = \begin{pmatrix} 1 & -3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -6 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{6} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \mathbf{A}_1$$

Because  $\mathbf{A}_6 = \text{rref}(\mathbf{A}_1)$ , the above equation gives the inverse relationship

$$\mathbf{A}_1 = \mathbf{E}_1^{-1} \mathbf{E}_2^{-1} \mathbf{E}_3^{-1} \mathbf{E}_4^{-1} \mathbf{E}_5^{-1} \text{rref}(\mathbf{A}_1).$$

Each inverse matrix is simplified by the rules for constructing  $\mathbf{E}^{-1}$  from elementary matrix  $\mathbf{E}$ , the result being

$$\mathbf{A}_1 = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -6 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 6 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \text{rref}(\mathbf{A}_1)$$