Name ____________________ Class Time _____

Math 2250 Maple Project 3: Linear Algebra
February 2006

Due date: See the internet due dates. Maple lab 3 has problems L3.1, L3.2, L3.3.

References: Code in `maple` appears in `2250mapleL3-S2006.txt` at URL `http://www.math.utah.edu/~gustafso/`. This document: `2250mapleL3-S2006.pdf`.

Problem L3.1. (Matrix Algebra)

Define $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$, $B = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix}$, $\mathbf{v} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ and $\mathbf{w} = \begin{pmatrix} -1 \\ 4 \\ 1 \end{pmatrix}$. Create a worksheet in `maple` which states this problem in text, then defines the four objects. The worksheet should contain text, `maple` code and displays. Continue with this worksheet to answer **(1)**–**(7)** below. Submit problem L3.1 as a worksheet printed on 8.5 by 11 inch paper. See Example 1 for maple commands.

(1) Compute AB and BA. Are they the same?

(2) Compute $A+B$ and $B+A$. Are they the same?

(3) Let $C = A+B$. Compare C^2 to $A^2 + 2AB + B^2$. Explain why they are different.

(4) Compute the transpose of AB and compare it to the product of the transpose of A with the transpose of B, multiplied in the correct order so that you expect equality.

(5) Solve for $\mathbf{X}$ in $B\mathbf{X} = \mathbf{v}$ by three different methods.

(6) Solve $A\mathbf{Y} = \mathbf{v}$ for $\mathbf{Y}$. Do an answer check.

(7) Solve $A\mathbf{Z} = \mathbf{w}$. Explain your answer.

Problem L3.2. (Row space)

Let $A = \begin{pmatrix} 1 & 1 & 1 & 2 & 6 \\ 2 & 3 & -2 & 1 & -3 \\ 0 & 1 & -4 & -3 & -15 \\ 1 & 2 & -3 & -1 & -9 \end{pmatrix}$. Find three different bases for the row space of A, using the following methods.

1. The method of Example 2, below.
2. The `maple` command `rowspace(A)`.
3. The **rref**-method: select rows from **rref**(A).

Verify that all three bases are equivalent.

Problem L3.3. (Matrix Equations)

Let $A = \begin{pmatrix} 8 & 10 & 3 \\ -3 & -5 & -3 \\ -4 & -4 & 1 \end{pmatrix}$, $T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 5 \end{pmatrix}$. Let P denote a 3×3 matrix. Assume the following result (proved below):

> **Lemma 1**. The equality $AP = PT$ holds if and only if the columns $\mathbf{v}_1$, $\mathbf{v}_2$, $\mathbf{v}_3$ of P satisfy $A\mathbf{v}_1 = \mathbf{v}_1$, $A\mathbf{v}_2 = -2\mathbf{v}_2$, $A\mathbf{v}_3 = 5\mathbf{v}_3$.

(a) Determine three specific columns for P such that $\det(P) \neq 0$ and $AP = PT$. Infinitely many answers are possible. See Example 4 for the maple method that determines a column of P.

(b) After reporting the three columns, check the answer by computing $AP - PT$ (it should be zero) and $\det(P)$ (it should be nonzero).

Staple this page on top of the maple work sheets. Examples on the next page ...

Example 1. Let $A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & -1 & 1 \\ 3 & 0 & -1 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} 9 \\ 8 \\ 3 \end{pmatrix}$. Create a `maple` work sheet. Define and display matrix A and vector $\mathbf{b}$. Then compute

(1) The inverse of A.

(2) The augmented matrix $C = \mathbf{aug}(A, \mathbf{b})$.

(3) The reduced row echelon form $R = \mathbf{rref}(C)$.

(4) The column $\mathbf{X}$ of R which solves $A\mathbf{X} = \mathbf{b}$.

(5) The matrix A^3.

(6) The transpose of A.

(7) The matrix $A - 3A^2$.

(8) The solution $\mathbf{X}$ of $A\mathbf{X} = \mathbf{b}$ by two methods different than (4).

Solution: A lab instructor can help you to create a blank work sheet in `maple`, enter code and print the work sheet. The code to be entered appears below. To get help, enter `?linalg` into a worksheet, then select commands that match ones below.

```
with(linalg):
A:=matrix([[1,2,3],[2,-1,1],[3,0,-1]]);
b:=vector([9,8,3]);
print("(1)"); inverse(A);
print("(2)"); C:=augment(A,b);
print("(3)"); R:=rref(C);
print("(4)"); X:=col(R,4);
print("(5)"); evalm(A^3);
print("(6)"); transpose(A);
print("(7)"); evalm(A-3*(A^2));
print("(8)"); X:=linsolve(A,b); X:=evalm(inverse(A) &* b);
```

Example 2. Let $A = \begin{pmatrix} 1 & 1 & 1 & 2 & 6 \\ 2 & 3 & -2 & 1 & -3 \\ 3 & 5 & -5 & 1 & -8 \\ 4 & 3 & 8 & 2 & 3 \end{pmatrix}$.

(1) Find a basis for the column space of A.

(2) Find a basis for the row space of A.

(3) Find a basis for the nullspace of A.

(4) Find $\mathbf{rank}(A)$ and $\mathbf{nullity}(A)$.

(5) Find the dimensions of the nullspace, row space and column space of A.

Solution: The theory applied: *The columns of B corresponding to the leading ones in* $\mathbf{rref}(B)$ *are independent and form a basis for the column space of B.* These columns are called the **pivot columns** of B. Results for the row space can be obtained by applying the above theory to the transpose of the matrix.
The `maple` code which applies is

```
with(linalg):
A:=matrix([[ 1, 1, 1, 2, 6],
           [ 2, 3,-2, 1,-3],
           [ 3, 5,-5, 1,-8],
           [ 4, 3, 8, 2, 3]]);
print("(1)"); C:=rref(A); # leading ones in columns 1,2,4
```

```
              BASIScolumnspace=col(A,1),col(A,2),col(A,4);
print("(2)"); F:=rref(transpose(A)); # leading ones in columns 1,2,3
              BASISrowspace=row(A,1),row(A,2),row(A,3);
print("(3)"); nullspace(A); linsolve(A,vector([0,0,0,0]));
print("(4)"); RANK=rank(A); NULLITY=coldim(A)-rank(A);
print("(5)"); DIMnullspace=coldim(A)-rank(A); DIMrowspace=rank(A);
              DIMcolumnspace=rank(A);
```

Example 3. Let $A = \begin{pmatrix} 1 & 1 & 1 & 2 & 6 \\ 2 & 3 & -2 & 1 & -3 \\ 3 & 5 & -5 & 1 & -8 \\ 4 & 3 & 8 & 2 & 3 \end{pmatrix}$. Verify that the following column space bases of A are equivalent.

$$\mathbf{v}_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix}, \quad \mathbf{v}_2 = \begin{pmatrix} 1 \\ 3 \\ 5 \\ 3 \end{pmatrix}, \quad \mathbf{v}_3 = \begin{pmatrix} 2 \\ 1 \\ 1 \\ 2 \end{pmatrix},$$

$$\mathbf{w}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ -3 \end{pmatrix}, \quad \mathbf{w}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 17 \end{pmatrix}, \quad \mathbf{w}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ -9 \end{pmatrix}.$$

Solution: The theory says that bases $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ and $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$ are equivalent bases if and only if the augmented matrices $F = \mathbf{aug}(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$, $G = \mathbf{aug}(\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3)$ and $H = \mathbf{aug}(F, G)$ satisfy the rank condition $\mathbf{rank}(F) = \mathbf{rank}(G) = \mathbf{rank}(H) = 3$.

The `maple` code which applies is

```
with(linalg):
A:=matrix([[ 1, 1, 1, 2, 6],
           [ 2, 3,-2, 1,-3],
           [ 3, 5,-5, 1,-8],
           [ 4, 3, 8, 2, 3]]);
v1:=col(A,1); v2:=col(A,2); v3:=col(A,4);
w1:=vector([1, 0, 0, -3]); w2:=vector([0, 1, 0, 17]); w3:=vector([0, 0, 1, -9]);
F:=augment(v1,v2,v3);
G:=augment(w1,w2,w3);
H:=augment(F,G);
rank(F); rank(G); rank(H);
```

We remark that the second basis $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$ of the example was discovered from the `maple` code

```
B:=rref(transpose(A)); # pivot cols 1,2,3
w1:=row(B,1); w2:=row(B,2); w3:=row(B,3);
```

Example 4. Let $A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & -1 & 1 \\ 3 & 0 & 0 \end{pmatrix}$. Solve the equation $A\mathbf{x} = -3\mathbf{x}$ for $\mathbf{x}$.

The `maple` details appear below. The idea is to write the problem as a homogeneous problem $(A - (-3)I)\mathbf{x} = \mathbf{0}$, which always has a solution.

```
with(linalg):
A:=matrix([[1,2,3],[2,-1,1],[3,0,0]]);
linsolve(evalm(A-(-3)*diag(1,1,1)),vector([0,0,0]));
# ans: t_1*vector([-2,1,2])
# Basis == partial on t_1 == vector([-2,1,2])
```

Proof of Lemma 1. Define $r_1 = 1$, $r_2 = -2$, $r_3 = 5$. Assume $AP = PT$, $P = \mathbf{aug}(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$ and $T = \mathbf{diag}(r_1, r_2, r_3)$. The definition of matrix multiplication implies that $AP = \mathbf{aug}(A\mathbf{v}_1, A\mathbf{v}_2, A\mathbf{v}_3)$ and $PT = \mathbf{aug}(r_1\mathbf{v}_1, r_2\mathbf{v}_2, r_3\mathbf{v}_3)$. Then $AP = PT$ holds if and only if the columns of the two matrices match, which is equivalent to the three equations $A\mathbf{v}_1 = r_1\mathbf{v}_1$, $A\mathbf{v}_2 = r_2\mathbf{v}_2$, $A\mathbf{v}_3 = r_3\mathbf{v}_3$. The proof is complete.

End of Maple Lab 3: Linear Algebra.