- 1. (ch4) Complete enough of the following to add to 100%.
 - (a) [100%] Let V be the vector space of all continuous functions defined on $-2 \le x \le 2$. Define S to be the set of all functions f(x) in V such that $f(0) = \int_{-2}^{2} f(|x|) dx$, f(-1) = 0. Prove that S is a subspace of V, by using the Subspace Criterion.
 - (b) [30%] Let V be the set of all 3×1 column vectors \mathbf{x} with components x_1, x_2, x_3 . Assume the usual \mathbb{R}^3 rules for addition and scalar multiplication. Let S be the subset of S defined by the equations $\mathbf{a} \cdot \mathbf{x} = \mathbf{b} \cdot \mathbf{x}$, where \mathbf{a} and \mathbf{b} are vectors in V. Prove that S is a subspace of V.
 - (c) [70%] Solve for the unknowns x_1 , x_2 , x_3 , x_4 in the system of equations below by augmented matrix RREF methods, showing all details. Report the vector form of the general solution.

@ $\vec{0}$ is in S, because function f(x) = 0 satisfies both equations. Let f_1, f_2 be in S. Then both equations are satisfied by f_1, f_2 ; if C_1, C_2 denote constant Then $f = C_1 f_1 + C_2 f_2$ satisfies

T.
$$f(0) = c$$
, $f_1(0) + c_1 f_2(0)$
= $c_1 \int_{-2}^{2} f_1(1 \times 1) dx + c_2 \int_{-2}^{2} f_2(1 \times 1) dx$
= $\int_{-2}^{2} (e_1 f_1 + e_2 f_2) (1 \times 1) dx$
= $\int_{-2}^{2} f(1 \times 1) dx$

II.
$$f(-1) = e_1 f_1(-1) + e_2 f_2(-1)$$

= $e_1(0) + e_2(0)$
= $e_1(0) + e_2(0)$

By Thm 1, 4.2, subspace Criterion, Sis a subspace of V

- b Let $\vec{c} = \vec{a} \vec{b}$ so The restriction equation is $\vec{c} \cdot \vec{x} = \vec{o}$. Let matrix A have rows \vec{c} , \vec{o} , \vec{o} . Then $A\vec{x} = \vec{o}$ defines S. By Thm 2, 4.2 E&P, S is a subspace of \vec{V} .

$$\begin{cases} x_1 - 4x_3 + 3x_4 = 1 \\ x_2 + 2x_3 = 0 \\ 0 = 0 \end{cases}$$
 is The reduced external System. Free = x_3 , x_4 .

$$\begin{cases} x_1 = 4t_1 - 3t_2 + 1 \\ x_2 = -2t_1 \\ x_3 = t_1 \\ x_4 = t_2 \end{cases}$$
 gen sol

$$\overset{2}{\times} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + t_1 \begin{pmatrix} 4 \\ -2 \\ 1 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} -3 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

Use this page to start your solution. Staple extra pages as needed.

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- 2. (ch5) Complete (a), (b) and either (c) or (d). Do not do both (c) and (d).
 - (a) [30%] Given 3x''(t) + 8x'(t) + 2x(t) = 0, which represents a damped spring-mass system with m = 3, c = 8, k = 2, solve the differential equation [20%] and classify the answer as over-damped, critically damped or under-damped [10%].
 - (b) [10%] Both undetermined coefficients and variation of parameters can solve $x'' + x' = t^2$. Without actually solving, which method is fastest? Explain your reasoning.
 - (c) [60%] Find by undetermined coefficients the steady-state periodic solution for the equation $x'' + 2x' + 5x = 5\sin(2t)$.
 - (d) [60%] If you did (c) above, then skip this one! Find by variation of parameters a particular solution x_p for the equation $x'' + 2x' + 5x = e^{t^2} \tan(t)$. To save time, don't try to evaluate integrals (it's impossible).
- a) 312+81+2=0 has roots $r_1 = \frac{1}{3}(-4+\sqrt{10})$, $r_2 = \frac{1}{3}(-4-\sqrt{10})$. The gen solis $\chi(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}$. Overdamped.
- 6 undetermined coefficients is faster, because only polynomials appear. For var. of parem., integrals like It 2 eat at appear.
- © trial $y = d_1 \cos 2t + d_2 \sin 2t$. Substitute. Then $d_1 = \frac{-20}{17}, d_2 = \frac{5}{17}$. $y = \frac{-20}{17} \cos 2t + \frac{5}{17} \sin 2t$
- (d) $x_1 = e^{t} \cos 2t$, $x_2 = e^{t} \sin 2t$ because $Re \operatorname{noots} \int r^2 + 2r + 5 = 0$ are $-1 \pm 2i$. Then $W = \begin{vmatrix} x_1 & x_2 \\ x_1' & x_2' \end{vmatrix} = 2e^{-2t}$. By (33) in EPP,

$$\gamma_{\rho}(t) = u_{1}(t) \chi_{1}(t) + u_{2}(t) \chi_{2}(t)$$

$$= u_{1} e^{t} \cos 2t + u_{2} e^{t} \sin 2t$$

$$u_{1} = -\int \frac{x_{2}f}{w} = -\int \frac{e^{t} \sin 2t}{2e^{-2t}} e^{t^{2}} \tan(t) dt$$

$$u_{2} = \int \frac{x_{1}f}{w} = \int \frac{e^{t} \cos 2t}{2e^{-2t}} e^{t^{2}} \tan(t) dt$$

- 3. (ch5) Complete all parts below.
 - (a) [75%] A non-homogeneous linear differential equation with constant coefficients has right side $f(x) = xe^{-x} + 3x^2 + x \sin x$ and characteristic equation $r(r+1)^2(r^2+1) = 0$. Determine the **corrected** trial solution for y_p according to the method of undetermined coefficients. To save time, **do not** evaluate the undetermined coefficients (that is, do undetermined coefficient steps $\boxed{1}$ and $\boxed{2}$, but skip steps $\boxed{3}$ and $\boxed{4}$)! Undocumented detail or guessing earns no credit.
 - (b) [25%] Using the *recipe* for higher order constant-coefficient differential equations, write out the general solution when the characteristic equation is $(r^3 4r)^2(r+2)(r^2 + r + 1) = 0$.

(a) trial
$$y = (d_1 + d_2 \times + d_3 \times^2) + (d_4 e^{-x} + d_5 \times e^{-x})$$

 $+(d_6 + d_7 \times) \cos x + (d_9 + d_9 \times) \sin x)$
There are 3 groups of related atoms.
 $L = \begin{cases} e^{0x}, e^{-x}, xe^{-x}, \cos x, \sin x \end{cases} = a tom list for The chan eg.$
Corrected $y = (d_1 + d_2 \times + d_3 \times^2) \times (d_9 + d_9 \times e^{-x}) \times^2 + (d_9 e^{-x} + d_9 \times e^{-x}) \times^2 + (d_9 + d_9 \times e^$

(b)
$$r^{2}(r-2)^{2}(r+2)^{2}(r+2)(r^{2}+r+1) = 0$$

 $r^{2}(r-2)^{2}(r+2)^{3}(r^{2}+r+1) = 0$
 $roots = 0,0,2,2,-2,-2,-2,\frac{1}{2}\pm\frac{\sqrt{3}}{2}i$
 $L = \{1, x, e^{2x}, xe^{2x}, e^{-2x}, xe^{-2x}, e^{x^{2}}e^{-2x}, e^{x^{2}}e^$

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- 4. (ch6) Complete all of the items below.
 - (a) [30%] Find the eigenvalues of the matrix $A = \begin{bmatrix} 5 & -2 & 1 & 4 \\ 2 & 5 & -3 & 5 \\ 0 & 0 & 0 & 7 \\ 0 & 0 & 0 & 5 \end{bmatrix}$. To save time, **do not** find eigenvectors!
 - (b) [70%] Given $A = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 4 & 1 \\ 0 & 1 & 4 \end{bmatrix}$, then there exists an invertible matrix P and a diagonal matrix Dsuch that AP = PD. Is $\mathbf{v} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ a possible column of P? Explain why or why not.
 - Expand A-2I by cofactors along The last now, Repeat. Then $(5-\lambda)(0-\lambda)((5-\lambda)^2+4)=0$ $|\lambda=5,0,5\pm2\lambda|$
 - It is a column \vec{v} of $\vec{P} \iff A\vec{v} = \lambda\vec{v}$ for some λ . $A\vec{v} = \begin{pmatrix} 1 & 1 & -1 \\ 0 & 4 & 1 \\ 0 & 1 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ $=\begin{pmatrix} 2\\ 4\\ 1\end{pmatrix}$ # 2 (!) for any 2.

No

5. (ch6) Complete all parts below.

Consider the 3×3 matrix

$$A = \left(\begin{array}{ccc} 3 & 1 & -1 \\ 0 & 3 & 1 \\ 0 & 1 & 3 \end{array}\right).$$

Already computed are eigenpairs

$$\left(3, \left(\begin{array}{c}1\\0\\0\end{array}\right)\right), \quad \left(4, \left(\begin{array}{c}0\\1\\1\end{array}\right)\right).$$

- (a) [40%] Compute and then display an invertible matrix P and a diagonal matrix D such that AP = PD.
- (c) [30%] Describe precisely, and explicitly for A above, Fourier's model for the computation of Ax.
- (c) [30%] Display the vector general solution $\mathbf{x}(t)$ of the linear differential system $\mathbf{x}' = A\mathbf{x}$.

(a) Eigenvalues satisfy det
$$(A-\lambda I)=0$$
. Then $(3-\lambda)((3-\lambda)^2-1)=0$. To $\lambda = 3, 2, 4$. We are missing eigenpair $(2, 7)$.

$$B = A-2I \qquad \qquad \cong \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 1 \end{pmatrix} \text{ Combo}$$

$$= \begin{pmatrix} 1 & 1 & -1 \\ 0 & 1 & 1 \end{pmatrix} \qquad \qquad \text{Free} = x_3$$

$$= \begin{pmatrix} 1 & 1 & -1 \\ 0 & 1 & 1 \end{pmatrix} \text{ combo}$$

$$\begin{cases} x_1 = 2 + 1 \\ x_2 = -t_1 \\ x_3 = t_1 \end{cases}$$

$$P = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \end{pmatrix} \qquad P = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} \qquad \text{Then } AP = PD, by Theorem.$$

(b)
$$A \begin{pmatrix} C_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + C_3 \begin{pmatrix} 2 \\ -1 \end{pmatrix} \end{pmatrix} = 3C_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 4C_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + 2C_3 \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$
(c)
$$x(t) = c_1 e^{3t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 e^{4t} \begin{pmatrix} 0 \\ 1 \end{pmatrix} + c_3 e^{t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$