

# The six phases of a two-parameter scaled Brownian penalization

Hugo Panzo

Department of Mathematics  
University of Connecticut

May 10, 2016



# Brownian penalization

Introduced by Roynette-Vallois-Yor in a series of papers beginning around 2005.

## Ingredients:

- 1 canonical Brownian motion:  $(C[0, \infty), X_t, \mathcal{F}_t, \mathcal{F}_\infty, \mathbb{W})$
- 2 adapted weight process  $0 \leq \Gamma_t$  with  $0 < E[\Gamma_t] =: Z_t^\Gamma < \infty$

If there exists a probability measure  $Q^\Gamma$  on  $\mathcal{F}_\infty$  such that for all  $s \geq 0$  and  $\Lambda_s \in \mathcal{F}_s$

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^\Gamma} E[1_{\Lambda_s} \Gamma_t] = Q^\Gamma(\Lambda_s)$$

then the coordinate process under  $Q^\Gamma$  is called Brownian motion penalized by  $\Gamma$ .

## scaled Brownian penalization

By only considering events up to a fixed time in the defining limit, ordinary penalization doesn't "penalize the entire path". A remedy of this situation is the *scaled penalization* which produces a probability measure on  $C[0, 1]$ .

### Additional ingredients:

- canonical space of  $C[0, 1]$  paths:  $(C[0, 1], Y_s, \mathcal{A})$
- scaling exponent  $\alpha \geq 0$

If there exists a non-trivial probability measure  $Q^{\alpha, \Gamma}$  on  $\mathcal{A}$  such that for all bounded and continuous  $F : C[0, 1] \rightarrow \mathbb{R}$

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^\Gamma} E_0 \left[ F \left( \frac{X_{\bullet t}}{t^\alpha} \right) \Gamma_t \right] = Q^{\alpha, \Gamma} [F(Y_\bullet)]$$

then the coordinate process under  $Q^{\alpha, \Gamma}$  is called Brownian motion penalized by  $\Gamma$  with  $\alpha$  scaling.

# a two-parameter unscaled Brownian penalization

Introduced in Roynette-Vallois-Yor 2005.

## preliminaries:

- 1  $S_t := \sup_{0 \leq s \leq t} X_s$  is the running maximum
- 2 parameters  $h, \nu \in \mathbb{R}$ ,  $h$  can be interpreted as drift
- 3 weight process  $\Gamma_t = \exp(hX_t + \nu S_t)$
- 4  $Q^\Gamma$  has three different "phases" depending on where  $(h, \nu)$  lies in the parameter plane

## Theorem (Roynette-Vallois-Yor 2005)

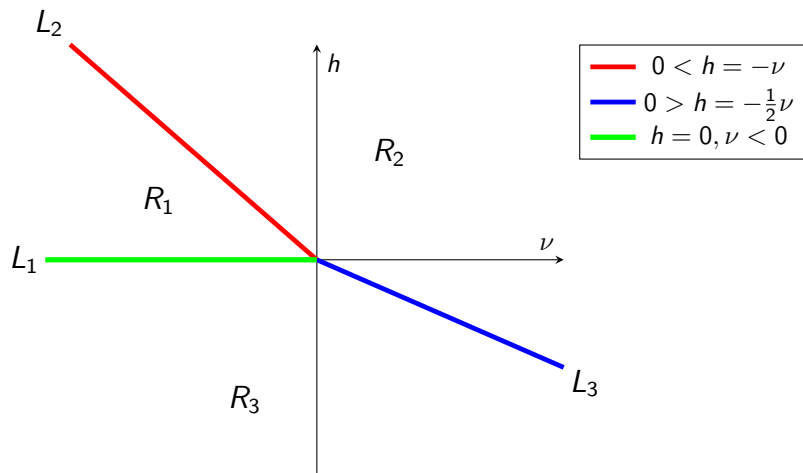
For all  $s \geq 0$  and  $\Lambda_s \in \mathcal{F}_s$ ,

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^{h,\nu}} E_0 [1_{\Lambda_s} \exp(hX_t + \nu S_t)] = E_0 [1_{\Lambda_s} M_s^{h,\nu}]$$

where  $M_s^{h,\nu}$  is a positive martingale given by

$$M_s^{h,\nu} = \begin{cases} -(h+\nu)e^{(h+\nu)S_s}(S_s - X_s) + e^{(h+\nu)S_s} & : (h,\nu) \in R_1 \\ e^{(h+\nu)X_s - \frac{1}{2}(h+\nu)^2 s} & : (h,\nu) \in R_2 \\ e^{(h+\nu)S_s - \frac{1}{2}h^2 s} \left( \cosh(h(S_s - X_s)) - \frac{h+\nu}{h} \sinh(h(S_s - X_s)) \right) & : (h,\nu) \in R_3. \end{cases}$$

## phase diagram



### Remark

In the unscaled penalization,  $L_2, L_3 \in R_2$  and  $L_1 \in R_1$ .

# Brownian meander

## Path construction:

- 1 Start with a standard Brownian path of duration 1.
- 2 Shift the last incomplete excursion so it starts at time 0.
- 3 Take absolute value.
- 4 Rescale path to have duration 1.

## Theorem (Imhof 1984)

Let  $m$  be a Brownian meander and  $r$  be a Bessel-3 process of duration 1. Then for measurable  $F : C[0, 1] \rightarrow \mathbb{R}$

$$E[F(m_\bullet)] = \sqrt{\frac{\pi}{2}} E_0 \left[ F(r_\bullet) \frac{1}{r_1} \right]$$

$$E_0[F(r_\bullet)] = \sqrt{\frac{2}{\pi}} E[F(m_\bullet)m_1].$$

# Denisov's path decomposition

## Theorem (Denisov 1984)

Let  $W$  be a standard Brownian path of duration 1 and let  $\theta$  be the time that its maximum is attained. Then

$$m_s := \frac{1}{\sqrt{\theta}}(W_\theta - W_{\theta(1-s)}), \quad 0 \leq s \leq 1$$

and

$$\tilde{m}_s := \frac{1}{\sqrt{1-\theta}}(W_\theta - W_{\theta+(1-\theta)s}), \quad 0 \leq s \leq 1$$

are independent Brownian meanders.



## Critical Line $L_1$ : old result

### Theorem (Roynette-Yor 2009)

Let  $\nu < 0$  and  $m$  be a Brownian meander. Then for bounded and continuous  $F : C[0, 1] \rightarrow \mathbb{R}$

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^\nu} E_0 \left[ F \left( \frac{X_{\bullet, t}}{\sqrt{t}} \right) \exp(\nu S_t) \right] = E[F(-m_\bullet)].$$

# Critical Line $L_2$

## Theorem

Let  $(h, \nu) \in L_2$  and  $m$  be a Brownian meander. For bounded and continuous  $F : C[0, 1] \rightarrow \mathbb{R}$  we have

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^{h, \nu}} E_0 \left[ F \left( \frac{X_{\bullet t}}{\sqrt{t}} \right) \exp(hX_t + \nu S_t) \right] = E[F(m_1 - m_{1-\bullet})].$$

## Key tool of proof:

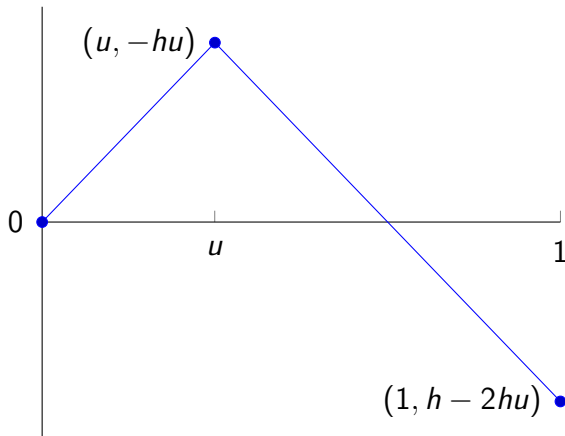
- 1 Imhof relation

## Remark (*Brownian ascent*)

Denisov's path decomposition implies that  $m_1 - m_{1-\bullet}$  is a Brownian path conditioned to end at its maximum.

## Critical Line $L_3$ : preliminary

Fix  $h < 0$ . For  $0 < u < 1$ , consider the path  $\omega_u$  that linearly interpolates between the points  $(0, 0)$ ,  $(u, -hu)$  and  $(1, h - 2hu)$ .



# Critical Line $L_3$ : main result

## Theorem

Let  $(h, \nu) \in L_3$ . For bounded and continuous  $F : C[0, 1] \rightarrow \mathbb{R}$  we have

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^{h, \nu}} E_0 \left[ F \left( \frac{X_{\bullet t}}{t} \right) \exp(hX_t + \nu S_t) \right] = \int_0^1 F(\omega_u) du.$$

## Key tools of proof:

- 1 Denisov's path decomposition
- 2 multi-variable Laplace method

# Region $R_1$ : different scaling for path and endpoint

## Theorem

Let  $(h, \nu) \in R_1$ ,  $\lambda > 0$  and  $\theta \in \mathbb{R}$ . Then

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^{h, \nu}} E_0 [\exp(i\theta X_t - \lambda S_t) \exp(hX_t + \nu S_t)] = \frac{h^2(h + \nu)^2(\nu - \lambda)}{\nu(h + i\theta)^2(h + \nu + i\theta - \lambda)^2}.$$

The associated joint density is

$$P(X_\infty \in dx, S_\infty \in dy) = \frac{h^2(h + \nu)^2}{-\nu} (2y - x) \exp(hx + \nu y) 1_{x < y} 1_{y > 0} dy dx.$$

## Theorem

Let  $(h, \nu) \in R_1$  and  $e$  be a normalized Brownian excursion. For bounded and continuous  $F : C[0, 1] \rightarrow \mathbb{R}$  we have

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^{h, \nu}} E_0 \left[ F \left( \frac{X_{\bullet, t}}{\sqrt{t}} \right) \exp(hX_t + \nu S_t) \right] = E[F(-e_\bullet)].$$

## Regions $R_2$ and $R_3$

### Theorem

Let  $F : C[0, 1] \rightarrow \mathbb{R}$  be bounded and continuous. Then we have

$$\lim_{t \rightarrow \infty} \frac{1}{Z_t^{h, \nu}} E_0 \left[ F \left( \frac{X_{\bullet t}}{t} \right) \exp(hX_t + \nu S_t) \right] = \begin{cases} F(\bullet(h + \nu)) & : (h, \nu) \in R_2 \\ F(\bullet h) & : (h, \nu) \in R_3. \end{cases}$$

### Remark

When  $(h, \nu) \in L_3$ , note that  $h + \nu = -h$ . So the  $L_3$  limit path can be seen to switch from  $R_2$  behavior to  $R_3$  behavior at a random time uniform on  $[0, 1]$ .

# FCLT for Regions $R_2$ and $R_3$

## Theorem

Let  $W$  be a Brownian path of duration 1. For bounded and continuous  $F : C[0, 1] \rightarrow \mathbb{R}$ , the following limits hold:

$$\left. \begin{array}{l} \text{if } (h, \nu) \in R_2, \text{ then} \\ \lim_{t \rightarrow \infty} \frac{1}{Z_t^{h, \nu}} E_0 \left[ F \left( \frac{X_{\bullet t} - \bullet t(h + \nu)}{\sqrt{t}} \right) \exp(hX_t + \nu S_t) \right] \\ \\ \text{if } (h, \nu) \in R_3, \text{ then} \\ \lim_{t \rightarrow \infty} \frac{1}{Z_t^{h, \nu}} E_0 \left[ F \left( \frac{X_{\bullet t} - \bullet th}{\sqrt{t}} \right) \exp(hX_t + \nu S_t) \right] \end{array} \right\} = E_0 [F(W_{\bullet})].$$

Thanks for your attention!