

MATH 5620 - Numerical Analysis
Practice Midterm

①

Problem 1 $y_n - y_{n-2} = \frac{h}{3} [f_n - 3f_{n-1} + 2f_{n-2}]$

(a) This is an implicit method since $f_n = f(t_n, y_n)$

(b) The associated polynomials to this method are:

$$p(z) = z^2 - 1$$

$$q(z) = \frac{1}{3} [z^2 - 3z + 2]$$

• This method is stable since the roots of $p(z)$ are ± 1 (simple roots w/ $|z|=1$)

• This method is not consistent since:

$$p(1) = 0 \quad \checkmark$$

$$p'(z) = 2z$$

$$p'(1) = 2$$

$$q(1) = \frac{1}{3} [1 - 3 + 2] = 0 \quad \times$$

Hence method is not convergent, since convergent \Leftrightarrow (stable & consistent)

Problem 2

(a) Jacob's method for solving $Ax = b$

$$x^{(0)} = \text{given}$$

For $k = 1, \dots$

$$x^{(k)} = D^{-1} [(D-A)x^{(k-1)} + b]$$

where: $D = \text{diagonal of } A = \text{diag}(\text{diag}(A))$

$$(b) \quad D^{-1}A = \begin{bmatrix} 1 & a_{12}/a_{11} & \dots & a_{1n}/a_{11} \\ a_{21}/a_{22} & 1 & \dots & a_{2n}/a_{22} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1}/a_{nn} & \dots & \dots & 1 \end{bmatrix}$$

$$I - D^{-1}A = \begin{bmatrix} 0 & a_{12}/a_{11} & \dots & a_{1n}/a_{11} \\ a_{21}/a_{22} & \dots & \dots & \vdots \\ \vdots & \dots & \dots & \vdots \\ a_{n1}/a_{nn} & \dots & a_{nn}/a_{nn} & 0 \end{bmatrix}$$

$$\|I - D^{-1}A\|_{\infty} = \max_{i=1, \dots, n} \sum_{\substack{j=1 \\ j \neq i}}^n \frac{|a_{ij}|}{|a_{ii}|}$$

$$\text{Since } A \text{ is diag. dom.: } \frac{\sum_{j=1, j \neq i}^n |a_{ij}|}{|a_{ii}|} < 1$$

$$\Rightarrow \|I - D^{-1}A\|_{\infty} < 1$$

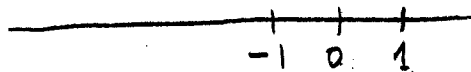
(c) A matrix splitting method converges when $\|I - Q^{-1}A\| < 1$ for some induced matrix norm. Here $Q = D$, so the method converges for diag. dom. matrices.

(d) This is only a sufficient condition for convergence. There may be matrices that are not diag. dom and for which Jacobi converges.

Problem 3

③

(a) We need to devise an integration formula that is exact for polynomials up to degree 2:



$$\int_0^1 p(t) dt = Ap(1) + Bp(0)$$

Using basis $p_0(t) = 1$
 $p_2(t) = t$

we get system:

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 1 \\ 1/2 \end{bmatrix} \Rightarrow B = \frac{1}{2}, A = \frac{1}{2}$$

Thus we get A-M:

$$\boxed{y_{n+1} = y_n + \frac{k}{2} [f_{n+1} + f_n]} \quad (\text{implicit trapezoidal rule})$$

(b) Written in the general form our method's coefficients are:

$$\begin{aligned} a_1 &= 1 & b_1 &= \frac{1}{2} \\ a_0 &= -1 & b_0 &= \frac{1}{2} \end{aligned}$$

therefore:

$$d_0 = a_1 + a_0 = 0$$

$$\begin{aligned} d_1 &= (0 \cdot a_0 - b_0) + \left(\frac{1}{1!} a_1 - \frac{1^0}{0!} b_1 \right) \\ &= -\frac{1}{2} + 1 - \frac{1}{2} = 0 \end{aligned}$$

$$\begin{aligned} d_2 &= (0 \cdot a_0 - 0 \cdot b_0) + \frac{1^2}{2!} a_1 - \frac{1^2}{1!} b_1 \\ &= \frac{1}{2} - \frac{1}{2} = 0 \end{aligned}$$

$$\begin{aligned} d_3 &= (0 \cdot a_0 - 0 \cdot b_0) + \frac{1^3}{3!} a_1 - \frac{1^2}{2!} b_1 \\ &= \frac{1}{6} - \frac{1}{4} = -\frac{1}{12} \neq 0 \end{aligned}$$

Therefore the method is of order 2 and the local truncation error is:

$$-\frac{1}{12} k^3 y^{(3)}(t_{n-1}) + O(k^4)$$

Problem 4

$$(a) \quad y(t+h) = y(t) + h y'(t) + \frac{h^2}{2} y''(t) + O(h^3)$$

$$= y + h f + h^2 \frac{df}{dt} + O(h^3)$$

and $\frac{df(t,y)}{dt} = f_t(t,y) + y' f_y(t,y)$

$$= f_t + f f_y$$

Thus:

$$\boxed{y(t+h) = y + h f + \frac{h^2}{2} [f_t + f f_y] + O(h^3)}$$

$$(b) \quad y(t+h) = y + w_1 h f + w_2 h f(t+\alpha h, y + \beta h f) + O(h^3)$$

$$= y + w_1 h f + w_2 h [f + \alpha h f_t + \beta h f f_y + O(h^2)] + O(h^3)$$

$$= y + \underbrace{w_1 h f + w_2 h f}_{= R(w_1 + w_2) f} + w_2 h^2 (\alpha f_t + \beta f f_y) + O(h^3)$$

(c) For the method to be order 2, it has to match Taylor series from (a).

$$w_1 + w_2 = 1 \quad (h \text{ term})$$

$$w_2 \alpha = \frac{1}{2} \quad (h^2 \text{ term})$$

$$w_2 \beta = \frac{1}{2}$$

(d) If $w_1 = \frac{1}{4}$, $w_2 = \frac{3}{4}$ and:

$$\alpha = \frac{\frac{1}{2}}{\frac{3}{4}} = \frac{2}{3}$$

$$\beta = \frac{\frac{1}{2}}{\frac{3}{4}} = \frac{2}{3}$$

Thus the method is:

$y_0 = \text{initial condition}$

for $i=0 \dots n$

$$\begin{cases} F_1 = h f(t_i, y_i) \\ F_2 = h f(t_i + \frac{2}{3}h, y_i + \frac{2}{3}F_1) \\ y_{i+1} = y_i + \frac{1}{4}F_1 + \frac{3}{4}F_2 \end{cases}$$