

PRACTICE MIDTERM
SOLUTIONS

Problem 1

$$\|x\| = \|A^{-1}Ax\| \leq \|A^{-1}\| \|Ax\|$$

$$\Rightarrow \|Ax\| \geq \|A^{-1}\|^{-1} \|x\|.$$

Problem 2

$$y = x + t^* v$$

$$t^* = \frac{v^T(b - Ax)}{v^T Av}$$

$$v^T(b - Ay) = v^T(b - Ax - t^* Av)$$

$$= v^T(b - Ax) - t^* v^T Av$$

$$= v^T(b - Ax) - \frac{v^T(b - Ax)}{v^T Av} v^T Av$$

$$= 0$$

Problem 3

$$(a) \quad u(t) = \frac{\partial y(t; \alpha)}{\partial \alpha}$$

$$\begin{aligned}
 u'' &= \frac{\partial y''(t; \alpha)}{\partial \alpha} = \frac{\partial}{\partial \alpha} \left[f(t, y(t; \alpha), y'(t; \alpha)) \right] \\
 &= \frac{\partial t}{\partial \alpha} f_t(t, y, y') + \frac{\partial y}{\partial \alpha} f_y(t, y, y') + \frac{\partial y'}{\partial \alpha} f_{y'}(t, y, y') \\
 &= u f_y(t, y, y') + u' f_{y'}(t, y, y')
 \end{aligned}$$

$$u(\alpha) = \frac{\partial y(a; \alpha)}{\partial \alpha} = 1$$

$$u'(a) = \frac{\partial y'(a; \alpha)}{\partial \alpha} = 0$$

$$(b) \quad \phi(\alpha) = y(b; \alpha) - \beta$$

$$\phi'(\alpha) = \frac{\partial y(b; \alpha)}{\partial \alpha} = u(b)$$

(c) let $y_1 = y$ and $y_2 = u$ then:

$$\text{(sys)} \quad \begin{cases}
 y_1' = y_3 \\
 y_2' = y_4 \\
 y_3' = f(t, y_1, y_3) \\
 y_4 = y_2 f(t, y_1, y_3) + y_4 f(t, y_1, y_3)
 \end{cases}$$

$$\text{I.C.:} \quad \begin{array}{l|l}
 y_1(a) = y(a) = \alpha & y_3(a) = y'(a) = \alpha \\
 y_2(a) = u(a) = 1 & y_4(a) = u'(a) = 0
 \end{array}$$

(d) For initial condition we take equation of line satisfying B.C. of BVP:

$$y(t) = \alpha(t-b) + \beta$$

$$z_0 = y(a) = \alpha(a-b) + \beta$$

for $k = 0, 1, 2, \dots$

solve (SYS) with I.C. $(z_k, 1, \alpha, 0)$

$$z_{k+1} = z_k - \frac{y_1(b) - \beta}{y_2(b)}$$

IF $|z_{k+1} - z_k| < \text{TOL}$ STOP

another possible stopping criterion is:

$$|y_1(b) - \beta| < \text{TOL}.$$

Problem 4

$$(a) \quad y(t_{i+1}) = y(t_i) + h y'(t_i) + \frac{h^2}{2!} y''(t_i) + \frac{h^3}{3!} y^{(3)}(t_i) + \frac{h^4}{4!} y^{(4)}(\xi_i^+)$$

$$y(t_{i-1}) = y(t_i) - h y'(t_i) + \frac{h^2}{2!} y''(t_i) - \frac{h^3}{3!} y^{(3)}(t_i) + \frac{h^4}{4!} y^{(4)}(\xi_i^-)$$

where $\xi_i^+ \in [t_i, t_{i+1}]$ and $\xi_i^- \in [t_{i-1}, t_i]$.

Adding both equations and solving for $y''(t_i)$ we get:

$$y''(t_i) = \frac{y(t_{i+1}) - 2y(t_i) + y(t_{i-1}))}{h^2} - \frac{h^2}{24} \left[y^{(4)}(\xi_i^+) + y^{(4)}(\xi_i^-) \right]$$

$$= 2y^{(4)}(\xi_i)$$

for some $\xi_i \in [t_{i-1}, t_{i+1}]$

(b) and (c):

$$L = \frac{1}{h^2} \begin{bmatrix} -2 & 1 & & & \\ 1 & -2 & 1 & & \\ & \ddots & \ddots & \ddots & \\ & & & 1 & -2 \\ & & & & 1 & -2 \end{bmatrix} \in \mathbb{R}^{n \times n}$$

$$D = \frac{1}{2h} \begin{bmatrix} 0 & p_1 & & & \\ -p_2 & 0 & p_2 & & \\ & & \ddots & \ddots & \\ & & & p_{n-1} & \\ p_n & & & & 0 \end{bmatrix} \in \mathbb{R}^{n \times n}$$

$$Q = \text{diag}(q_1, q_2, \dots, q_n)$$

where we use notation:

$$p_i \equiv p(t_i)$$

$$q_i \equiv q(t_i)$$

$$r_i \equiv r(t_i)$$

FD approx is:

$$\underbrace{(L - D - Q)}_A Y = B, \quad Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$B = \begin{bmatrix} r_1 - \alpha/h^2 - p_1/2h \\ r_2 \\ \vdots \\ r_{n-1} \\ r_n - \beta/h^2 + p_n/2h \end{bmatrix}$$

Problem 5

(5)

(a) Here:

$$A = \frac{1}{k^2} \begin{bmatrix} -2 & 1 & & & \\ & 1 & -2 & & \\ & & \ddots & \ddots & \\ & & & \ddots & 1 \\ & & & & 1 & -2 \end{bmatrix} \in \mathbb{R}^{m \times m}$$

$$U(t) = \begin{bmatrix} U_1(t) \\ U_2(t) \\ \vdots \\ U_m(t) \end{bmatrix}$$

$$V = \begin{bmatrix} \eta(x_1) \\ \eta(x_2) \\ \vdots \\ \eta(x_m) \end{bmatrix}$$

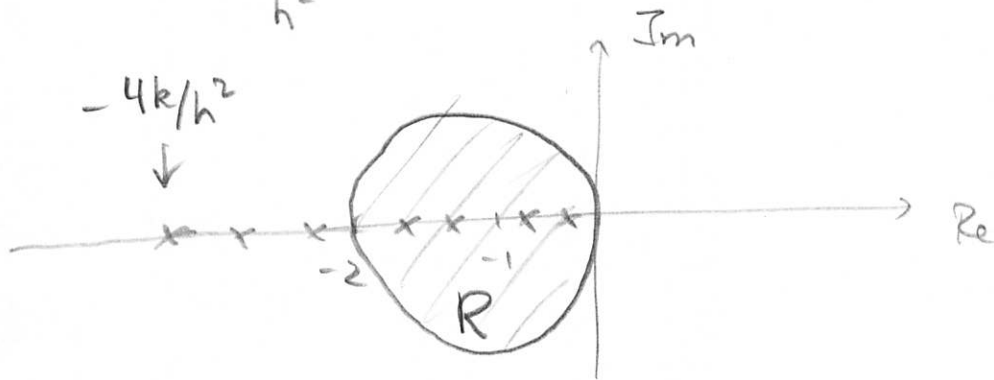
(b)
$$U^{n+1} = U^n + k A U^n$$
$$= (I + k A) U^n$$

(c)
$$U^1 = (I + k A) V$$
$$U^2 = (I + k A)^2 V$$
$$\vdots$$
$$U^n = (I + k A)^n V$$

(d) we need $k\lambda_p(A) \in$ absolute stability region for all p . (6)

$$\lambda_p(A) = \frac{2}{h^2} (\cos(p\pi h) - 1)$$

$$\Rightarrow -\frac{4k}{h^2} \leq k\lambda_p(A) \leq 0$$



For $k\lambda_p(A) \in R$ we need:

$$-2 \leq \frac{-4k}{h^2}$$
$$\Rightarrow \boxed{\frac{k}{h^2} \leq \frac{1}{2}}$$