

Linear algebra preliminaries

- Linear space

E is a linear space iff $v_1, v_2 \in E \Rightarrow \alpha v_1 + \beta v_2 \in E$
for all $\alpha, \beta \in \mathbb{R}$

(note: one can change \mathbb{R} here by \mathbb{C} , but we will stick w/ \mathbb{R})

in english: E is closed under linear operations (add and mult. by scalar)

Example: \mathbb{R}^n , $\mathbb{P}_n = \text{poly of degree } \leq n$

$C[0,1]$, $C^2[0,1]$, etc..

- Linear span: Let v_1, v_2, \dots, v_k be vectors in a linear space E .

$$\text{span}\{v_1, v_2, \dots, v_k\} = \left\{ \sum_{i=1}^k \alpha_i v_i \mid \alpha_i \in \mathbb{R}, i=1 \dots k \right\}$$

= set of all linear comb. of v_i .

= another example of linear space

- Linear independence A family of vectors v_1, v_2, \dots, v_k is linearly indep. iff:

$$\sum_{i=1}^k \alpha_i v_i = 0 \Leftrightarrow \alpha_i = 0, i=1 \dots k$$

in english: one cannot express one vector as a lin. comb. of the others

- Basis: A basis for a linear-space E is a set of linearly indep vectors $\{v_1, v_2, \dots, v_k\}$ such that

$$E = \text{span} \{v_1, v_2, \dots, v_k\}$$

$$\dim E = k = \text{dimension}$$

$= \#$ of linearly indep vectors spanning E .

Example: $\mathbb{R}^n = \text{span} \{\underline{e}_1, \underline{e}_2, \dots, \underline{e}_n\}$

where $\underline{e}_i = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ | \\ 1 \\ 0 \end{pmatrix}_{\text{i-th pos.}} = i\text{th canonical basis vector}$

$$\Rightarrow \dim \mathbb{R}^n = n$$

$\bullet T_n = \text{span} \{1, x, x^2, \dots, x^n\}$ (lin. indep can be shown using FTA)

$$\Leftrightarrow \dim T_n = n+1.$$

$\bullet C[0, 1]$ is infinite dimensional.

A normed linear space is a vector space E

endowed with a norm $\|\cdot\|: E \rightarrow \mathbb{R}_+$ which satisfies the following properties:

$$\text{i) } \|x\| \geq 0 \quad \forall x \in E$$

$$\text{ii) } \|x\| = 0 \Leftrightarrow x = 0$$

$$\text{iii) } \|2x\| = |2| \|x\|$$

$$\text{iv) } \|x+y\| \leq \|x\| + \|y\| \quad (\text{triangle inequality})$$

Norms can be used to measure distance.

Examples in \mathbb{R}^n

$$\|x\|_2 = \left(\sum_{i=1}^n |x_i|^2 \right)^{\frac{1}{2}} \quad \begin{matrix} \text{Euclidean} \\ (\ell_2 \text{ norm}) \end{matrix}$$

$$\|x\|_1 = \sum_{i=1}^n |x_i| \quad (\ell_1 \text{ norm})$$

$$\|x\|_\infty = \max_{i=1 \dots n} |x_i| \quad (\ell_\infty \text{ norm})$$

$$\|x\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{\frac{1}{p}}$$

$$1 \leq p \leq \infty \quad (\ell_p \text{ norm})$$

Examples in $C[0,1]$

$$\|f\|_2 = \left(\int_0^1 (f(x))^2 dx \right)^{\frac{1}{2}}$$

$$\|f\|_1 = \int_0^1 |f(x)| dx$$

$$\|f\|_\infty = \max_{x \in [0,1]} |f(x)|$$

$$\|f\|_p = \left(\int_0^1 |f(x)|^p dx \right)^{\frac{1}{p}}$$

$$1 \leq p \leq \infty$$

which norm we use depends on application -

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An inner product is a symm. positive bilinear
form defined over a linear space E ; i.e.:
 dot
 scalar

$(\cdot, \cdot) : E \times E \rightarrow \mathbb{R}$

with properties:

i) $(x, y) = (y, x)$ (Symmetric)

ii) $(x, x) \geq 0$ and

$(x, x) = 0 \Leftrightarrow x = 0$ (positive)

iii) $(\alpha x + \beta y, z) = \alpha(x, z) + \beta(y, z)$

(bilinear)

(need only dim. w.r.t.
one argument as form
is symmetric)

An inner product defines a metric

$$\|x\| = (x, x)^{\frac{1}{2}}$$

Examples of inner products:

$$\mathbb{R}^n: (x, y) = x^T y = \sum_{i=1}^n x_i y_i$$

$$C[0,1] \quad (f, g) = \int_0^1 f g \, dx$$

Inner product convey angle and distance information.

f is orthogonal to g iff $(f, g) = 0$

f is orthogonal to $G \subseteq E$ iff:

$$\forall g \in G \quad (f, g) = 0$$

If $G = \text{span}\{g_1, \dots, g_k\}$ then:

f is orthogonal to $G \Leftrightarrow (f, g_i) = 0, i=1 \dots k$

We often abbreviate orthogonal with \perp .