

$$E = \frac{f^{(2n)}(\xi)}{(2n)!} \int_a^b \left(\prod_{i=0}^{n-1} (x - x_i) \right)^2 w(x) dx, \quad (108)$$

where $\xi \in (a, b)$.

§ 4.5 Romberg Integration

Idea: use Richardson's extrapolation to increase accuracy of composite trapezoidal rule.
 → get high accuracy method from multiple applications of a low accuracy method.

Recall composite trapezoidal rule:

$$\int_a^b f(x) dx = \frac{h}{2} \left(f(x_0) + f(x_m) + 2 \sum_{j=1}^{m-1} f(x_j) \right) - \frac{(b-a) h^2 f''(\xi)}{12}$$

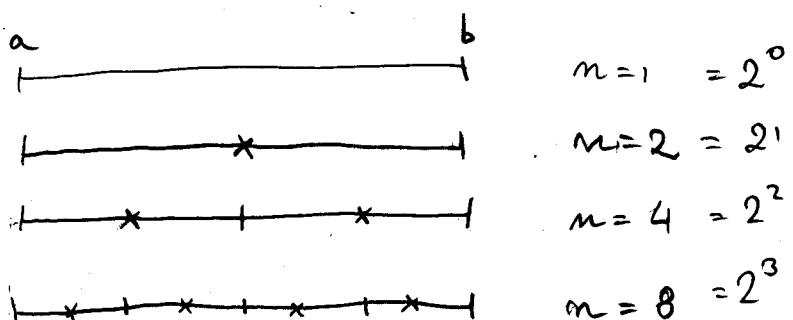
where $\xi \in (a, b)$ $h = \frac{b-a}{m}$ and $x_j = a + jh$.

Romberg integration needs to evaluate composite trapezoidal rule

for $n = 2^k$,

$k = 0, 1, \dots, M$

without superfluous function evaluations



* = new function evaluations
 | = function evaluation available from previous "level".

(109)

Thus composite trapz rule becomes with $h_k = \frac{2^{-k}}{2^k-1} (b-a)$:

$$\int_a^b f(x) dx = \frac{h_k}{2} \left[f(a) + f(b) + 2 \sum_{i=1}^{2^k-1} f(a + i h_k) \right] - \frac{(b-a)}{12} h_k^2 f''(\xi_k)$$

$$= R_{k,0} + \text{error}$$

where $\xi_k \in (a, b)$.

So: $R_{0,0} = \frac{h_0}{2} (f(a) + f(b)) = \frac{b-a}{2} (f(a) + f(b))$

$$R_{1,0} = \frac{h_1}{2} (f(a) + f(b) + 2f(a+h_1))$$

$$= \frac{1}{2} R_{0,0} + h_1 f(a+h_1)$$

$$R_{2,0} = \frac{1}{2} R_{1,0} + h_2 (f(a+h_2) + f(a+3h_2))$$

$$R_{k,0} = \frac{1}{2} R_{k-1,0} + h_k \sum_{j=1}^{2^{k-1}} f(a + (2j-1)h_k)$$

Evaluation only at odd numbered nodes.

It can be shown that:

$$\textcircled{1} \quad \int_a^b f(x) dx = R_{k,0} + K_1 h_k^2 + K_2 h_k^4 + K_3 h_k^6 + \dots$$

$$\textcircled{2} \quad \int_a^b f(x) dx = R_{k+1,0} + K_1 h_{k+1}^2 + K_2 h_{k+1}^4 + K_3 h_{k+1}^6 + \dots$$

$$= R_{k+1,0} + K_1 \frac{h_k^2}{4} + K_2 \frac{h_k^4}{16} + K_3 \frac{h_k^6}{64} + \dots$$

Do Richardson's extrapolation trick to cancel out leading term in error: (110)

$$4 \times ② - ① :$$

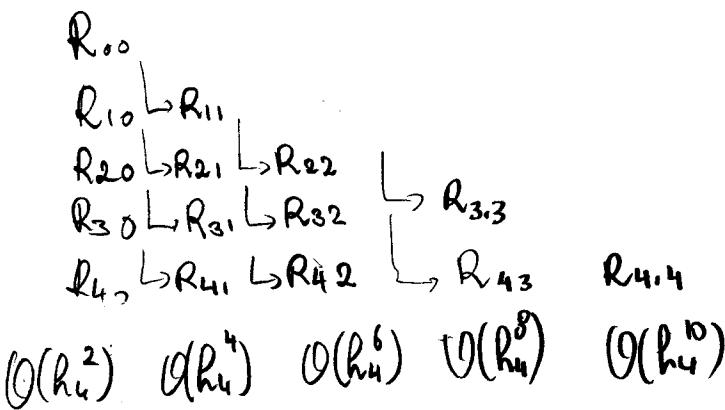
$$3 \int_a^b f(x) dx = 4R_{k+1,0} - R_{k,0} - \frac{3}{4} h_k^4 - \frac{15}{16} h_k^6 - \dots$$

$$\int_a^b f(x) dx = \underbrace{\frac{4R_{k+1,0} - R_{k,0}}{4 - 1}}_{- \frac{1}{4} h_k^4 - \frac{5}{16} h_k^6 - \dots} = R_{k+1,1} = O(h_k^4) \text{ approx}$$

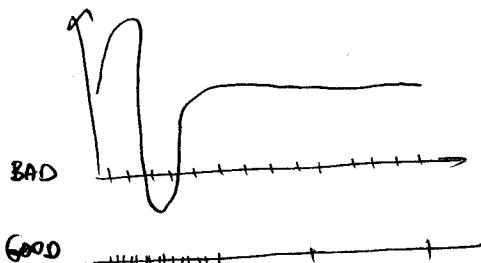
If we keep doing same thing:

$$R_{k+1,j} = \frac{4^j R_{k+1,j-1} - R_{k,j-1}}{4^j - 1} = O(h_k^{2(j+1)})$$

Organizing work in a table we get: (for example)



§ 4.6 Adaptive quadrature methods



Using a uniform partition of an interval for a quadrature rule for approximating the integral of a function is not the most efficient way of doing things!

Obviously we can do better if we adapt the # of points to put more points where they are needed the most \Rightarrow principle behind adaptive methods.

key ingredient: we need a way that tells us how good our quadrature is working. We could do a number of things: for example using more nodes to estimate error term or using a more accurate method. Here we choose to refine # of points to estimate error.

On some interval $[a, b]$:

$$(*) \int_a^b f(x) dx = \underbrace{\frac{b-a}{6} (f(a) + f(\frac{a+b}{2}) + f(b))}_{\text{for some } \xi \in (a, b)} - \frac{h^5}{90} f^{(4)}(\xi) \quad \text{where } h = \frac{b-a}{2}$$

Of course we could estimate error if we knew $f^{(4)}$ but this is asking too much from end user!

Instead we apply Simpson's rule again on two subintervals of $[a, b]$:

$$\begin{aligned} (***) \int_a^b f(x) dx &= S(a, \frac{a+b}{2}) + S(\frac{a+b}{2}, b) - \frac{h^5}{25920} f^{(4)}(\xi_1) - \frac{h^5}{25920} f^{(4)}(\xi_2) \\ &= " - \frac{h^5}{90} \left(\frac{1}{16}\right) f^{(4)}(\tilde{\xi}) \end{aligned}$$

where $\xi_1 \in (a, \frac{a+b}{2})$, $\xi_2 \in (\frac{a+b}{2}, b)$ and $\tilde{\xi} \in (a, b)$.

Now assume $f^{(4)}$ does not vary too much on (a, b) so:

(11)

$$f^{(4)}(\xi) \approx f^{(4)}(\tilde{\xi})$$

so to estimate the error we simply do $(\star\star) - (\star)$ to get:

$$\frac{h^5}{90} f^{(4)}(\xi) \approx -\frac{16}{15} \left[S(a, \frac{a+b}{2}) + S(\frac{a+b}{2}, b) - S(a, b) \right]$$

Plugging into $(\star\star)$ and bounding integration error:

$$\left| \int_a^b f(x) dx - S(a, \frac{a+b}{2}) - S(\frac{a+b}{2}, b) \right| \leq \frac{1}{15} \left| S(a, b) - S(a, \frac{a+b}{2}) - S(\frac{a+b}{2}, b) \right|$$

So if we want $(\star\star)$ to be accurate to within ϵ we need:

$$\left| S(a, b) - S(a, \frac{a+b}{2}) - S(\frac{a+b}{2}, b) \right| < 15\epsilon$$

To be conservative (and account for some changes in $f^{(4)}$) we can require 10ϵ bound.

Algorithm: the book implements a recursive procedure using a for loop.
This is like writing a tree traversal algorithm with for loops: very complicated! \rightarrow use recursion: i.e. a function that calls itself.

- △ Using recursion is probably less efficient than running code in the book but it's much easier to understand!
- △ Also some programming languages are limited in # of recursion levels that are allowed or if you run a C program you may get "stack overflow" or other messages of the kind.
- △ It may be good to impose a limit on # of recursions in "industrial" code as infinite recursions can be nastier than infinite loops!

function $r = \text{adapt Simpson}(a, b, f, \epsilon)$

$$S = \frac{b-a}{6} (f(a) + 4f\left(\frac{a+b}{2}\right) + f(b))$$

$$S_1 = \frac{b-a}{12} (f(a) + 4f\left(a + \frac{b-a}{4}\right) + f\left(\frac{a+b}{2}\right))$$

$$S_2 = \frac{b-a}{12} (f\left(\frac{a+b}{2}\right) + 4f\left(a + \frac{3(b-a)}{4}\right) + f(b))$$

If $|S - S_1 - S_2| < \epsilon$

$$r = S_1 + S_2 ; \quad \because \text{we are happy with approx}$$

else

$$\rightarrow r = \text{adapt Simpson}\left(a, \frac{a+b}{2}, f, \epsilon/2\right) + \text{adapt Simpson}\left(\frac{a+b}{2}, b, f, \epsilon/2\right)$$

- recursive calls of adaptive Simpson code for left and right halves of intervals.
Requiring that error be $\epsilon/2$ ensures the total error from left + right subint
will not exceed ϵ when summed up.
- instead of accumulating only integrals we can also accumulate e.g. points of
discretization.