

HW 5 Solutions MATH 2280-2

3.5.4g

$y'' - 4y' + 4y = 2e^{2x}$ to solve using variation of parameters

Char poly: $p(r) = r^2 - 4r + 4 = (r-2)^2$

(1) $\Rightarrow y_H(x) = a e^{2x} + b x e^{2x}$

(2) $y_H'(x) = a' e^{2x} + b' x e^{2x} + a(e^{2x})' + b(x e^{2x})'$

(2') let $a' e^{2x} + b' x e^{2x} = 0$

(3) $y_H''(x) = a'(e^{2x})' + b'(x e^{2x})' + a(e^{2x})'' + b(x e^{2x})''$

\sim We get a system of equations for a' and b'

(2)' : $a' e^{2x} + b' x e^{2x} = 0$

(3) - $4 \times$ (2) + $4 \times$ (1): $a' 2e^{2x} + b'(1+2x)e^{2x} = 2e^{2x}$

$\Leftrightarrow e^{2x} \begin{bmatrix} 1 & x \\ 2 & 1+2x \end{bmatrix} \begin{bmatrix} a' \\ b' \end{bmatrix} = \begin{bmatrix} 0 \\ 2e^{2x} \end{bmatrix}$

$\begin{bmatrix} a' \\ b' \end{bmatrix} = \frac{e^{2x}}{e^{4x}(1+2x-2x)} \begin{bmatrix} 1+2x & -x \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 2e^{2x} \end{bmatrix}$

$= -e^{-2x}(2e^{2x}) \begin{pmatrix} -x \\ 1 \end{pmatrix} = 2 \begin{pmatrix} -x \\ 1 \end{pmatrix}$

$\Rightarrow a(x) = \int -2x dx = -x^2$

$b(x) = \int 2 dx = 2x$

\Rightarrow a particular sol is:

$y_p(x) = -x^2 e^{2x} + 2x^2 e^{2x} = x^2 e^{2x}$

(2)

Since we did a problem similar to 3.5.49 in class, here is another example (not in HW) of variation of parameters

(3.5.52) $y'' + 9y = \sin 3x$ to solve using var of params.

$$p(r) = r^2 + 9 = (r+3i)(r-3i)$$

(1) $y_H(x) = a \cos 3x + b \sin 3x$

(2) $y_H'(x) = a' \cos 3x + b' \sin 3x + a(\cos 3x)' + b(\sin 3x)'$

(2') we set $a' \cos 3x + b' \sin 3x = 0$

(3) $y_H''(x) = a'(\cos 3x)' + b'(\sin 3x)' + a(\cos 3x)'' + b(\sin 3x)''$

We get two eq for a' and b' :

$$\begin{cases} a' \cos 3x + b' \sin 3x = 0 & (2') \\ -3a' \sin 3x + 3b' \cos 3x = \sin 3x & (3) + 9 \times (1) \end{cases}$$

$$\Leftrightarrow \begin{bmatrix} \cos 3x & \sin 3x \\ -3 \sin 3x & 3 \cos 3x \end{bmatrix} \begin{bmatrix} a' \\ b' \end{bmatrix} = \begin{bmatrix} 0 \\ \sin 3x \end{bmatrix}$$

$$\begin{aligned} \begin{bmatrix} a' \\ b' \end{bmatrix} &= \frac{1}{3 \cos^2 3x + 3 \sin^2 3x} \begin{bmatrix} 3 \cos 3x & -\sin 3x \\ 3 \sin 3x & \cos 3x \end{bmatrix} \begin{bmatrix} 0 \\ \sin 3x \end{bmatrix} \\ &= \frac{1}{3} \begin{bmatrix} -\sin^2 3x \\ \sin 3x \cos 3x \end{bmatrix} \end{aligned}$$

$$\Rightarrow a(x) = \int \frac{-\sin^2 3x}{3} dx = \frac{1}{3} \left(\frac{1}{6} \cos 3x \sin 3x - \frac{1}{2} x \right)$$

$$b(x) = \int \frac{1}{3} \sin 3x \cos 3x dx = -\frac{1}{18} \cos^2 3x$$

$$\Rightarrow y_p(x) = \frac{1}{18} \cos^2 3x \sin 3x - \frac{x}{6} \cos 3x - \frac{1}{18} \cos^2 3x \sin 3x$$

$$= -\frac{x}{6} \cos 3x$$

3.6.2 $x'' + 4x = 5 \sin 3t \quad x(0) = x'(0) = 0$

$x_H(t) = a \cos 2t + b \sin 2t$

$x_p(t) = c \sin 3t \Rightarrow -9c \sin 3t + 4c \sin 3t = 5 \sin 3t$

$\Rightarrow c = -1$

$\Rightarrow x_p(t) = -\sin 3t$

$\Rightarrow x(t) = x_H(t) + x_p(t) = a \cos 2t + b \sin 2t - \sin 3t$

$x(0) = 0 = a$

$x'(0) = 2b - 3 = 0 \Rightarrow b = \frac{3}{2}$

$\Rightarrow x(t) = \frac{3}{2} \sin 2t - \sin 3t$, period is 2π

Plot: see back

3.6-11 $L(x) = x'' + 4x' + 5x = 10 \cos 3t$ $x(0) = x'(0) = 0$

Look for x_p in $V = \text{span} \{ \cos 3t, \sin 3t \}$

We have: $L(\cos 3t) = -9 \cos 3t - 12 \sin 3t + 5 \cos 3t = -4 \cos 3t - 12 \sin 3t$

$L(\sin 3t) = -9 \sin 3t + 12 \cos 3t + 5 \sin 3t = 12 \cos 3t - 4 \sin 3t$

thus: and if $x_p(t) = a \cos 3t + b \sin 3t$:

$$(L)x = \begin{bmatrix} -4 & 12 \\ -12 & -4 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 10 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} a \\ b \end{bmatrix} = \frac{1}{4} \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$\Rightarrow x_p(t) = -\frac{1}{4} \cos 3t + \frac{3}{4} \sin 3t = \frac{\sqrt{10}}{4} \left(-\frac{1}{\sqrt{10}} \cos 3t + \frac{3}{\sqrt{10}} \sin 3t \right)$$

$$= \frac{\sqrt{10}}{4} \cos(3t - \alpha)$$

where $\alpha = \arccos\left(-\frac{1}{\sqrt{10}}\right) \approx 1.8925$

Characteristic polynomial is $p(r) = r^2 + 4r + 5$ roots are $r = -2 \pm i$

$\Rightarrow x_h(t) = e^{-2t} (a \cos t + b \sin t)$

$\Rightarrow x(t) = \frac{\sqrt{10}}{4} \cos(3t - \alpha) + \underbrace{e^{-2t} (a \cos t + b \sin t)}_{x_p(t)}$

Using initial cond:

$x(0) = \frac{\sqrt{10}}{4} \cos(\alpha) + a = 0$

$\Rightarrow a = -\left(\frac{\sqrt{10}}{4}\right) \left(-\frac{1}{\sqrt{10}}\right) = \frac{1}{4}$

$x'(0) = -\frac{3}{4} \sqrt{10} \sin(3t - \alpha) - e^{-2t} ((2a - b) \cos t + (a + 2b) \sin t)$

$x'(0) = +\frac{3}{4} \sqrt{10} \sin \alpha - (2a - b) = \frac{3}{4} - \frac{1}{2} + b = 0$

$\Rightarrow b = -\frac{7}{4}$

$\Rightarrow x_p(t) = e^{-2t} \left[\frac{1}{4} \cos t - \frac{7}{4} \sin t \right] = \frac{\sqrt{50}}{4} e^{-2t} \left[\frac{1}{\sqrt{50}} \cos t - \frac{7}{\sqrt{50}} \sin t \right]$

$= \frac{\sqrt{50}}{4} e^{-2t} \cos(t - \beta) \quad \beta = 2\pi + \arcsin\left(-\frac{7}{\sqrt{50}}\right) \approx 4.8543$

plot: see book

3.6.16 $L(x) = mx'' + cx' + kx = F_0 \cos \omega t$ (mass-spring system)

where $m=1$, $c=4$, $k=5$, $F_0=2$.

note: char. poly. of DE is same as in 3.6.11 \Rightarrow roots $r = -2 \pm i$
 we only need to find particular solution to DE. \Rightarrow use undetermined coeff method.
 look for $x_p \in V = \text{span} \{ \cos \omega t, \sin \omega t \}$

$$L(\cos \omega t) = -\omega^2 \cos \omega t - 4\omega \sin \omega t + 5 \cos \omega t = (5 - \omega^2) \cos \omega t - 4\omega \sin \omega t$$

$$L(\sin \omega t) = -\omega^2 \sin \omega t + 4\omega \cos \omega t + 5 \sin \omega t = 4\omega \cos \omega t + (5 - \omega^2) \sin \omega t$$

Thus the matrix A of L restricted to V is:

$$A = \begin{bmatrix} 5 - \omega^2 & -4\omega \\ 4\omega & 5 - \omega^2 \end{bmatrix}$$

Thus if $x_p = a \cos \omega t + b \sin \omega t$: $\begin{bmatrix} a \\ b \end{bmatrix} = A^{-1} \begin{bmatrix} 10 \\ 0 \end{bmatrix}$

$$= \frac{10}{(5 - \omega^2)^2 + 16\omega^2} \begin{bmatrix} 5 - \omega^2 \\ 4\omega \end{bmatrix}$$

The amplitude of the steady periodic solution is:

$$C(\omega) = \sqrt{a^2 + b^2} = \left(\frac{10^2}{[(5 - \omega^2)^2 + 16\omega^2]^2} \right)^{1/2}$$

$$= \frac{10}{\sqrt{(5 - \omega^2)^2 + 16\omega^2}} = \frac{10}{\sqrt{25 + 6\omega^2 + \omega^4}}$$

$$C'(\omega) = -\frac{5(4\omega^3 + 12\omega)}{(25 + 6\omega^2 + \omega^4)^{3/2}} < 0 \text{ thus } C(\omega) \text{ is monotonically decreasing and there is no practical resonance.}$$

For plot of $C(\omega)$ see book.

4.1.2

$x^{(4)} + 6x'' - 3x' + x = \cos 3t$ in the form of a first order system

$x \equiv x_0$

$x_0' = x_1$

$x_1' = x_2$

$x_2' = x_3$

$x_3' = -6x_2 + 3x_1 - x_0 + \cos 3t$

ob: letting $x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$

$\Leftrightarrow \frac{dx}{dt} = A x + F$
where

$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 3 & -6 & 0 \end{bmatrix}$

$F = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \cos 3t \end{bmatrix}$

4.1.3

$t^2 x'' + t x' + (t^2 - 1)x = 0$

$x \equiv x_0$

$x_0' = x_1$

$t^2 x_1' = -t x_1 + (t^2 - 1)x_0$

4.1.13

$\begin{cases} x' = -2y \\ y' = 2x \\ x(0) = 1, y(0) = 0 \end{cases}$

$\Rightarrow y = -\frac{1}{2} x'$
 $\Rightarrow -\frac{1}{2} x'' = 2x$
 $x'' + 4x = 0$

$\Rightarrow x(t) = a \cos 2t + b \sin 2t$

$x(0) = a = 1$

$y(0) = -\frac{1}{2} x'(0) = -\frac{1}{2} (2b) = 0$

thus $\begin{cases} x(t) = \cos 2t \\ y(t) = \sin 2t \end{cases}$

See book for plot

4.1.16

$$\begin{cases} x' = 8y \\ y' = -2x \end{cases}$$

$$\Rightarrow y = \frac{x'}{8}$$

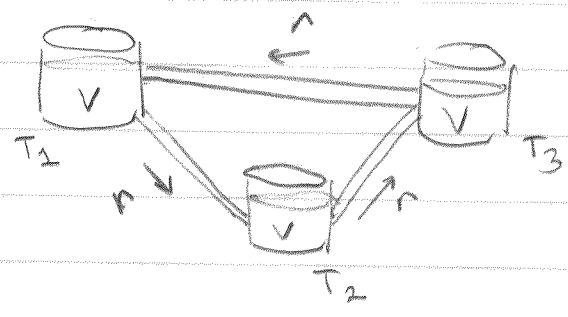
$$\Rightarrow \frac{x''}{8} = -2x$$

$$\Rightarrow x'' + 16x = 0$$

$$\Rightarrow \boxed{\begin{aligned} x(t) &= a \cos 4t + b \sin 4t \\ y(t) &= \frac{x'(t)}{8} = -\frac{a}{2} \sin 4t + \frac{b}{2} \cos 4t \end{aligned}}$$

see book for plot.

4.1.26



In tank 1: $\frac{dx_1}{dt} = r \frac{x_3}{V} - r \frac{x_1}{V}$

Concentration in tank 3: $\frac{dx_3}{dt} = r \frac{x_2}{V} - r \frac{x_3}{V}$

$$\frac{dx_1}{dt} = r \frac{x_3}{V} - r \frac{x_1}{V}$$

$$= \frac{10}{100} (x_3 - x_1)$$

$$\Rightarrow \begin{cases} 10 x_1' = x_3 - x_1 \\ 10 x_2' = x_1 - x_2 \\ 10 x_3' = x_2 - x_3 \end{cases}$$

Similarly:

5.1.13

$$\begin{cases} x' = 2x + 4y + 3e^t \\ y' = 5x - y - t^2 \end{cases}$$

Let $\underline{x} = \begin{pmatrix} x \\ y \end{pmatrix}$ then system is $\underline{x}' = A\underline{x} + \underline{F}(t)$

where $A = \begin{bmatrix} 2 & 4 \\ 5 & -1 \end{bmatrix}$ and $\underline{F}(t) = \begin{bmatrix} 3e^t \\ -t^2 \end{bmatrix}$

5.1.18

$$\begin{cases} x' = tx - y + e^t z \\ y' = 2x + t^2 y - z \\ z' = e^{-t} x + 3ty + t^3 z \end{cases}$$

Let $\underline{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ then system is $\underline{x}' = A(t)\underline{x}$

with $A = \begin{bmatrix} t & -1 & e^t \\ 2 & t^2 & -1 \\ e^{-t} & 3t & t^3 \end{bmatrix}$

5.1.22

$$\underline{x}' = \underbrace{\begin{bmatrix} -3 & 2 \\ -3 & 4 \end{bmatrix}}_A \underline{x} \quad \text{We have } \underline{x}_1 = e^{3t} \begin{pmatrix} 1 \\ 3 \end{pmatrix} \Rightarrow \underline{x}'_1 = 3e^{3t} \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$\text{Moreover } A \underline{x}_1 = e^{3t} \begin{pmatrix} -3 & 2 \\ -3 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \end{pmatrix} = e^{3t} \begin{pmatrix} 3 \\ 9 \end{pmatrix} \Rightarrow \underline{x}'_1 = A \underline{x}_1$$

$$\text{For } \underline{x}_2 = e^{-2t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \Rightarrow \underline{x}'_2 = -2e^{-2t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\text{Moreover } A \underline{x}_2 = \begin{bmatrix} -3 & 2 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -4 \\ -2 \end{bmatrix} \Rightarrow \underline{x}'_2 = A \underline{x}_2$$

The two solutions are lin. indep. since:

$$W(t) = \begin{vmatrix} \underline{x}_1 & \underline{x}_2 \end{vmatrix} = \begin{vmatrix} e^{3t} & 2e^{-2t} \\ 3e^{3t} & e^{-2t} \end{vmatrix} = e^t (1 - 6) = -5e^t \neq 0 \quad \forall t.$$

A general sol to system is of the form $\underline{x} = a \underline{x}_1 + b \underline{x}_2$.

5.1.27

$$\underline{x}' = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \underline{x} \quad \underline{x}_1 = e^{2t} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow \underline{x}'_1 = 2e^{2t} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$A \underline{x}_1 = \begin{pmatrix} 2 \\ 2 \\ 2 \end{pmatrix} e^{2t} \Rightarrow \underline{x}'_1 = A \underline{x}_1$$

$$\underline{x}_2 = e^{-t} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \Rightarrow \underline{x}'_2 = e^{-t} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}; A \underline{x}_2 = e^{-t} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \Rightarrow \underline{x}'_2 = A \underline{x}_2$$

$$\underline{x}_3 = e^{-t} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \Rightarrow \underline{x}'_3 = e^{-t} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}; A \underline{x}_3 = e^{-t} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \Rightarrow \underline{x}'_3 = A \underline{x}_3$$

$$\text{The Wronskian is } W(t) = \begin{vmatrix} \underline{x}_1 & \underline{x}_2 & \underline{x}_3 \end{vmatrix} = \begin{vmatrix} e^{2t} & e^{-t} & e^{-t} \\ 1 & 0 & 1 \\ 1 & 1 & -1 \end{vmatrix} = 2 + 1 = 3 \neq 0 \quad \forall t, \text{ solutions are lin. indep.}$$

A general sol to system is $\underline{x} = a \underline{x}_1 + b \underline{x}_2 + c \underline{x}_3$.

5.1.31

We must find solutions with initial cond $\underline{x}_0 = \begin{pmatrix} 0 \\ 5 \end{pmatrix} = \underline{x}(0)$.

$$\text{Since } \underline{x}(t) = a e^{3t} \begin{pmatrix} 1 \\ 3 \end{pmatrix} + b e^{-2t} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$= \begin{bmatrix} e^{3t} & 2e^{-2t} \\ 3e^{3t} & e^{-2t} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$\Rightarrow \underline{x}(0) = \begin{pmatrix} 0 \\ 5 \end{pmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$\Rightarrow \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix} \Rightarrow \underline{x}(t) = 2e^t \begin{pmatrix} 2 \\ -3 \end{pmatrix} - e^{2t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

5.1.36

We must find a solution with init cond $\underline{x}_0 = \underline{x}(0) = \begin{pmatrix} 10 \\ 12 \\ -1 \end{pmatrix}$

$$\text{Since } \underline{x}(t) = a e^{2t} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + b e^{-t} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + c \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} e^{-t}$$

$$\underline{x}(0) = \begin{pmatrix} 10 \\ 12 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & -1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 7 \\ 3 \\ 5 \end{pmatrix} \Rightarrow \underline{x}(t) = 7e^{2t} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + 3e^{-t} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + 5e^{-t} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$