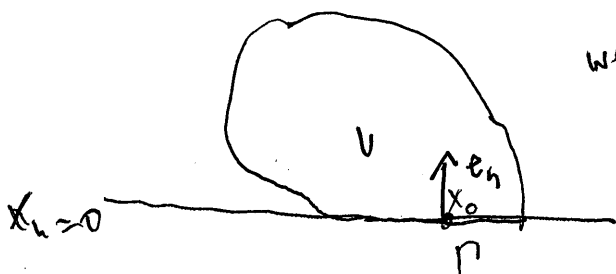


Non-characteristic Boundary data

We are given $x_0 \in \Gamma$ wish to solve $P(Du, u, x) = 0$ in U
(near x_0)



we may as well assume that

$$v(x_0) = e_n, \text{ and that}$$

Γ is flat near x_0 lying in

$$\{x_n = 0\}.$$

This can be achieved for smooth curved body by
a change of variables.

Now we wish to solve the characteristic
ODE with $x(0)$ near x_0 , but we
need initial data for p, z .

$$p(0) = p_0, \quad z(0) = z_0, \quad x(0) = x_0$$

clearly $\boxed{z_0 = g(x_0)}$ from boundary condition of u .

Since $u|_{\Gamma} = g|_{\Gamma}$ for $y \in \Gamma$

$$\boxed{\partial_{x_i} u(x_0) = \partial_{x_i} g(x_0) \text{ for } i = 1, \dots, n-1.}$$

furthermore we require the PDE to hold

$$\boxed{F(\phi_0, z_0, x_0) = 0}$$

this gives n - eqns for the n unknowns

ϕ_0^i , but there may be no solution
of multiple solutions for ϕ_0^n .

Not only must we solve the compatibility conditions

at x_0 , but also near x_0 ,

we need at mapping $q(y)$ so that

$$\text{CII} \quad \begin{cases} q^i(y) = g_{x_i}(y) \\ F(q(y), g(y), y) = 0 \end{cases} \quad \text{for } y \text{ near } x_0$$

$$\text{w/ } q(y) = \phi_0 \quad \text{at } x_0.$$

Lemma There exists a unique solution $g(\cdot)$ of (1) for all $y \in P$ sufficiently near x_0 as long as

$$F_{p_n}(p_0, z_0, x_0) \neq 0.$$

The proof uses the Implicit Function Theorem

proof: define $G: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$G^i(p, y) = p_i - g_i(y) \quad i=1, \dots, n-1$$

$$G^n(p, y) = F(p, g(y), y)$$

$G(p_0, x_0) = 0$ by assumption and

$$D_p G(p_0, x_0) = \begin{pmatrix} 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \\ F_{p_1}(p_0, z_0, x_0) & \dots & F_{p_n}(p_0, z_0, x_0) \end{pmatrix}$$

$\left(\frac{\partial G^i}{\partial p_j} \right)_{ij}$

$$\det D_p G(p_0, x_0) = F_{p_n}(p_0, z_0, x_0) \neq 0$$

$\neq 0$

$$D_p G(p_0, x_0)$$

non-degenerate

implicit function theorem $\Rightarrow \exists$ a unique solution $g(y)$

$F(g(y), g(y), y) = 0$ for y in a small nbhd of x_0 .

~~Solving~~

~~Inverting~~

$$\cancel{X = X(y, s)} \rightarrow y$$

Now that we have initial data

$(q(y), g(y), y)$ for the characteristic ODEs

for y close to x_0

for any such $y = (y_1, \dots, y_{n-1}, 0)$ we solve

$$\begin{cases} \dot{p} = -D_x F(p, z, X) - p D_z F(p, z, X) \\ \dot{z} = p \cdot D_p F(p, z, X) \\ \dot{X} = D_p H(p, z, X) \end{cases}$$

w/

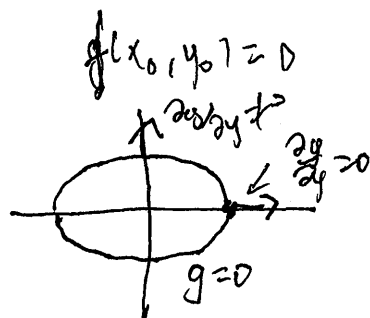
$$\cancel{X(y)} \quad \cancel{X(0, y)} = \cancel{q(y)}$$

initial data

$$\begin{cases} p(0, y) = q(y) \\ z(0, y) = g(y) \\ X(0, y) = y \end{cases}$$

Implicit function thm :

e.g. $f: \mathbb{R}^2 \rightarrow \mathbb{R}$



D -level set is locally a C^1 surface

near (x_0, y_0) if $Df(x_0, y_0) \neq 0$

if $Df(x_0, y_0) \cdot (0, 1) = \frac{\partial f}{\partial y}(x_0, y_0) \neq 0$

then $\{f=0\}$ is locally a graph

$\exists$ g s.t. C^1 s.t.

$$f(x, g(x)) = 0 \quad \text{for } x \text{ near } x_0$$

$$g(x_0) = y_0$$

$x \in \mathbb{R}^n, y \in \mathbb{R}^m$

$U \subseteq \mathbb{R}^{n+m}$

(x, y) pts in $\mathbb{R}^{n+m}$

$f: U \rightarrow \mathbb{R}^m$ is $C^1, f = (f_1, \dots, f_m)$

$$D_y f = \begin{pmatrix} f_{y_1}^1 & \dots & f_{y_m}^1 \\ \vdots & & \vdots \\ f_{y_1}^m & \dots & f_{y_m}^m \end{pmatrix} \quad n \times m \text{ matrix}$$

Thm Assume $f \in C^1(U; \mathbb{R}^m)$ and $|\det D_y f(x_0, y_0)| \neq 0$.

Then $\exists V$ open $\subset U$ w/ $(x_0, y_0) \in V, W \subseteq \mathbb{R}^n$

w/ $x_0 \in W$ and a C^1 mapping $g: W \rightarrow \mathbb{R}^m$ s.t.

(i) $g(x_0) = y_0$

(ii) $f(x, g(x)) = z_0 (= f(x_0, y_0))$

and

(iii) if $(x, y) \in V$ w/ $f(x, y) = z_0$ then $y = g(x)$

(iv) if $f \in C^k$ then $g \in C^k$.

Lemma Assume $F_p(p_0, z_0, x_0) \neq 0$. Then $\exists$ an

open interval $I \subseteq \mathbb{R}$ containing 0, a nbhd W of x_0 in $\mathbb{R}^{n-1}$, and a nbhd V of x_0 in $\mathbb{R}^n$ such that for each $x \in V$ there exist unique $s \in I$, $y \in W$ such that

$$x = X(s, y)$$

and $x \mapsto s, y$ is C^2 mapping.

Proof: ~~$X(0, x_0)$~~ $X(0, x_0) = x_0$ so we can

use inverse fun thm to locally invert

$$X: \mathbb{R}^n \rightarrow \mathbb{R}^n \quad \text{as long as}$$

$$\det DX(0, x_0) \neq 0.$$

$$\text{Since } X(0, y) = y$$

~~$$\frac{\partial}{\partial y_i} X(0, x_0) = \delta_{ij}$$~~

$$\frac{\partial}{\partial y_i} X^j(0, x_0) = \begin{cases} \delta_{ij} & j \neq n \\ 0 & j = n \end{cases}$$

And since

$$\frac{\partial x^i}{\partial s}(0, x_0) = F_{p_i}(p_0, z_0, x_0) \quad \text{from the ODE}$$

$$DX(0, x_0) = \begin{pmatrix} F_{p_1}(p_0, z_0, x_0) & 1 & & \\ \vdots & & \ddots & \\ F_{p_n}(p_0, z_0, x_0) & 0 & \dots & 0 \end{pmatrix}$$

~~$\frac{\partial x^i}{\partial s}$~~

$$|\det DX(0, x_0)| = F_{p_n}(p_0, z_0, x_0) \neq 0$$

so inverse function theorem applies.

Thm Assume $f \in C^1(U; \mathbb{R}^n)$ and $|\det Df(x_0)| \neq 0$. Then

there exists an open set $V \subset U$ w/ $x_0 \in V$, and $W \subset \mathbb{R}^n$

w/ $z_0 = f(x_0) \in W$ s.t.

(1) $f: V \rightarrow W$ is 1-1 and onto

(2) $f^{-1}: W \rightarrow V$ is C^1

(3) if $f \in C^k$ then $f^{-1} \in C^k$

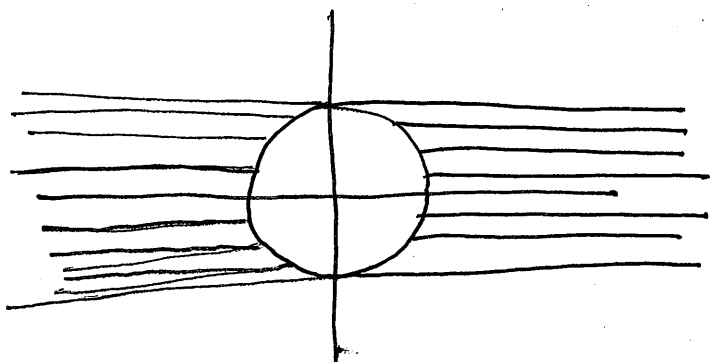
Example

$$\begin{cases} \partial_{x_1} u = 0 & \text{in } \mathbb{R}^2 \setminus B_1(0,1) \\ u = g & \text{on } \partial B_1(0,1) \end{cases}$$

$$F(p, z, x) = p_2$$

$$\text{s.t. } \begin{cases} \dot{X} = e_2 \\ \dot{z} = 0 \\ \dot{\phi} = 0 \end{cases} \quad \begin{cases} X(0, x_0) = x_0 \\ \text{irrelevant} & z(0, x_0) = g(x_0) \end{cases}$$

$$X(t, x_0) = x_0 + t e_2$$



all bdy points are non-characteristic except $\pm e_2$ where $v = \pm e_2$ respectively

$$\text{s.t. } v \cdot F_p(p_0, z_0, x_0) = e_1 \cdot v = 0$$

$$\text{iff } x_0 = \pm e_2$$

otherwise ~~u(x) =~~

$$u(x) = g(x_0) = g(x_1 - t, x_2) \quad \text{where } t \text{ s.t.}$$

$$(x_1 - t)^2 + x_2^2 = 1 \quad \text{--- (if } x_1 > 0)$$

$$(x_1 - t)^2 = 1 - x_2^2 \quad \text{for} \quad -1 \leq x_2 \leq 1$$

$$x_1 - t = \pm \sqrt{1 - x_2^2}$$

$$t = x_1 \mp \sqrt{1 - x_2^2}$$

$$u(x) = g(x_1 - \operatorname{sgn}(x_1) \sqrt{1 - x_2^2}, x_2)$$

Example Eikonal equation.

$$\begin{cases} |Du| = 1 & \text{in } \mathbb{R}^2 \setminus B(0,1) \\ u = \cos x_2 & \text{on } \partial B(0,1) \end{cases}$$

$$\begin{cases} \dot{p} = 0 \\ \dot{z} = p \cdot D_p F(p, z, x) = p \cdot \frac{p}{|p|} = |p| \\ \dot{x} = \frac{p}{|p|} \end{cases}$$

$$\text{w/ } \begin{cases} x(0) = (\cos \theta, \sin \theta) \\ z(0) = \sin \theta \\ \text{note } p(0) = p_n^0 (\cos \theta, \sin \theta) + p_t^0 (-\sin \theta, \cos \theta) \end{cases}$$

we can compute p_t by

$$p_t^0 = Dg \cdot \tau = x_2 \cdot (-\sin \theta, \cos \theta) = \cos \theta$$

then using $|p(0)| = 1$ from the PDE

we get $p_n^0 = \sqrt{1 - \cos^2 \theta} = \pm \sin \theta$

(no multiple solutions) ~~choose +, this only affects time direction of orb for $\mathbb{R}$.~~

$$V = F_{p_n}(p^0, x_0, x_0) = \frac{p_n^0}{|p|} = p_n^0 = \pm \sin \theta$$

so noncharacteristic condition holds for

$$\theta \neq 0 \text{ or } \pi$$

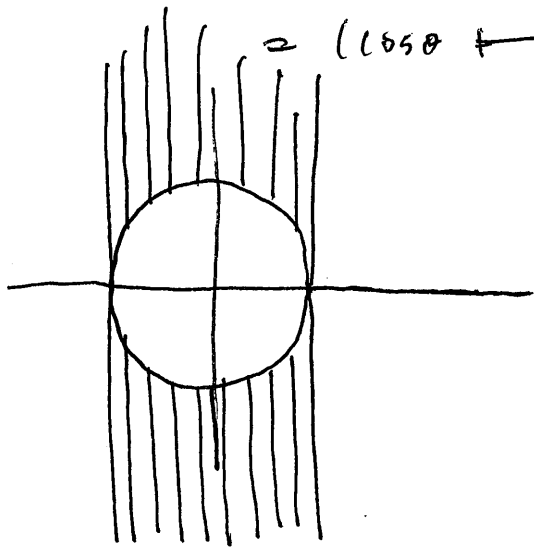
$$p(t) = \text{and } p^0 \text{ with}$$

$$z(t) = \sin \theta + |p_0|t = \sin \theta + t$$

$$x(t) = (\cos \theta, \sin \theta) + p_0 t = (\cos \theta, \sin \theta) + (\cos \theta, \sin \theta) \begin{matrix} \sin \theta \\ \cos \theta \end{matrix} t + (-\sin \theta, \cos \theta) \begin{matrix} \cos \theta \\ \sin \theta \end{matrix} t$$

$$= (\cos \theta + \cos^2 \theta t - \sin^2 \theta t, \sin \theta + 2 \sin \theta \cos \theta t)$$

$$= (\cos \theta + \cos(2\theta)t, \sin \theta + \sin(2\theta)t)$$



Conservation Laws

We consider the IVP for the scalar conservation law

$$(1) \begin{cases} u_t + F(u)_x = 0 & \text{in } \mathbb{R} \times (0, \infty) \\ u(x, 0) = g(x) & \text{in } \mathbb{R} \end{cases}$$

Recall, after writing the equation as

$$u_t + F'(u)u_x = 0 \quad \text{in } \mathbb{R} \times (0, \infty)$$

Characteristics are

$$\dot{x} = F'(u(x(t), t)) = F'(g(x_0))$$

$$\text{Since } \dot{z} = \frac{d}{dt} u(x(t), t) = 0$$

In general the characteristics will cross leading to multiple possible solutions ~~which are not smooth~~.
~~singular not all of~~

• Weak solution

Suppose to start that
$$\begin{cases} u_t + F(u)_x = 0 \\ u(x, 0) = g(x) \end{cases}$$

u is a smooth solution.

Let $v: \mathbb{R} \times (0, \infty) \rightarrow \mathbb{R}$ smooth

w/ compact support

let v a test function (like when

we introduced distributions)

multiply the PDE by v and integrate by parts

$$0 = \int_0^b \int_{\mathbb{R}} (u_t + F(u)_x) v \, dx \, dt$$

$$\text{by } \int_{\mathbb{R}} = - \int_0^{\infty} \int_{\mathbb{R}} u v_t + F(u) v_x \, dx \, dt - \int_{\mathbb{R}} u(x, 0) v(x, 0) \, dx$$

using $u(x, 0) = g(x)$ we get

$$(2) \quad \int_0^{\infty} \int_{\mathbb{R}} u v_t + F(u) v_x \, dx \, dt + \int_{\mathbb{R}} g v|_{t=0} \, dx = 0$$

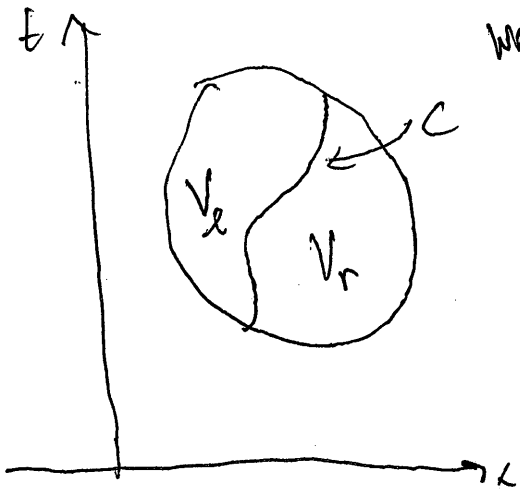
for all test functions v

Def: We say $u \in L^{\infty}(\mathbb{R} \times (0, \infty))$ is an integral solution

of (1) if (2) holds for every test functions

What kind of non-smooth solutions can we have?

We consider a very particular kind of discontinuous u



We suppose that v is an integral solution of (1) in $V \subseteq \mathbb{R} \times (0, \infty)$

with a smooth ~~is~~ on
either side of a smooth curve
 C parametrized by ~~$\gamma = \gamma(t)$~~
 $\gamma(t), t)$

V_e is the part of V to the left of C

V_r is the velocity to the right of C

And we suppose v smooth in V_e and V_r ,
and v unit at V_e, V_r .
Choosing w w/ supp in V_e .

$$0 = \int_0^\infty \int_{-\infty}^\infty u v_t + F(u) v_x dx dt = - \int_0^\infty \int_{-\infty}^\infty (u_x + F(u)_x) v dx dt$$

Since u is smooth in V_e and V is compactly supported in V_e .

$$\Rightarrow U_x + f(u)_x = 0 \quad \text{physic in } V_L$$

same result in V_r

now let v w/ cpt support in V , not necessarily vanishing on C . Then

$$0 = \int_0^\infty \int_{\mathbb{R}} u v_t + F(u) v_x dx dt$$

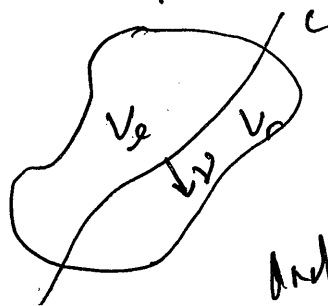
$$= \iint_{V_L} u v_t + F(u) v_x dx dt + \iint_{V_R} u v_t + F(u) v_x dx dt$$

Since v cptly supported in V

$$\begin{aligned} \iint_{V_L} u v_t + F(u) v_x &= - \iint_{V_L} [u_t + F(u)_x] v dx dt \\ &\quad + \int_C [u_L v_x + F(u_L) v_x] v ds \\ &= \int_C v (u_L v_t + F(u_L) v_x) ds \end{aligned}$$

where v is unit normal to ∂C pointing

from V_L into V_R ; $v = (v_x, v_t)$



and $u_L(x,t) = \lim_{y \rightarrow x^-} u(y,t)$

and $u_L(x,t)$ is the "left limit"

$$u_L(x,t) = \lim_{y \rightarrow x^-} u(y,t)$$

similarly

$$\iint_{V_r} u v_t + F(u) v_x \, dx dt = - \int_C [\bar{u}_r v_t + F(u_r) v_x] v \, ds$$

so

$$\int_C [(u_x - u_r) v_t + (F(u_x) - F(u_r)) v_x] v \, ds = 0$$

for every v a ^{smooth} test support in V .

$$\Rightarrow (u_x - u_r) v_t + (F(u_x) - F(u_r)) v_x = 0$$

pointwise on C .

now using the parametrization

$$C = \{ (\gamma(t), t) : t \in \mathbb{I} \}$$

unit tangent vector is $\frac{(\dot{\gamma}, 1)}{\sqrt{1 + |\dot{\gamma}|^2}}$

unit normal is $\frac{(-1, \dot{\gamma})}{\sqrt{1 + |\dot{\gamma}|^2}}$

Quasi-linear equations

(linear in p)

also just need equations for x, z
not p .

Fully Nonlinear (nonlinear in p)

now need full method of characteristics.

example

so $\#$ $F(u_x) - F(u_r) = \hat{\gamma}(u)(u_x - u_r)$

or $\hat{\gamma} = \frac{F(u_x) - F(u_r)}{u_x - u_r}$

We call $[u] = u_x - u_r = \text{jump of } u \text{ across curve } C$

$$[F(u)] = F(u_x) - F(u_r) = \text{jump of } F(u)$$

$$\sigma = \hat{\gamma} = \text{speed of curve } C$$

then $\sigma = \frac{[F(u)]}{[u]}$ Rankine-Hugoniot condition