

Differential forms (from the beginning)

Multilinear Algebra

Recall $\mathcal{L}(\mathbb{R}^n, \mathbb{R})$ space of linear maps $\mathbb{R}^n \rightarrow \mathbb{R}$

$$v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \in \mathbb{R}^n \quad dx_i(v) = v_i$$

$\{dx_1, \dots, dx_n\}$ are a basis for $\mathcal{L}(\mathbb{R}^n, \mathbb{R})$

given $\phi \in \mathcal{L}(\mathbb{R}^n, \mathbb{R})$ call $a_i = \phi(e_i)$

$$\text{then } \phi(v) = a_1 dx_1 + \dots + a_n dx_n$$

$$\text{if } \phi = c_1 dx_1 + \dots + c_n dx_n = 0$$

$$\text{then } 0 = \phi(e_i) = c_j \quad \text{for all } i=1, \dots, n$$

$\underline{I} = (i_1, \dots, i_k)$ is an ordered k -tuple

$$dx_{\underline{I}} : \mathbb{R}^{nk} \rightarrow \mathbb{R} \quad \text{by}$$

$$dx_{\mathbb{I}}(v_1, \dots, v_k) = \begin{vmatrix} dx_{i_1}(v_1) & \dots & dx_{i_1}(v_k) \\ \vdots & & \vdots \\ dx_{i_k}(v_1) & \dots & dx_{i_k}(v_k) \end{vmatrix}$$

if $v_i = \begin{pmatrix} v_{i,1} \\ \vdots \\ v_{i,k} \end{pmatrix}$

$$dx_{\mathbb{I}}(v_1, \dots, v_k) = \begin{vmatrix} v_{1,i_1} & \dots & v_{k,i_1} \\ \vdots & & \vdots \\ v_{1,i_k} & \dots & v_{k,i_k} \end{vmatrix}$$

i.e. taking rows i_1, \dots, i_k out of

matrix $\begin{bmatrix} v_1 & \dots & v_k \end{bmatrix}$

e.g. in \mathbb{R}^2 $dx_{(1,2)}(v_1, v_2) = \begin{vmatrix} v_{1,1} & v_{2,1} \\ v_{1,2} & v_{2,2} \end{vmatrix}$

where $dx_{\mathbb{I}}$ is an alternating multilinear function of v_1, \dots, v_k

i.e. linear in each argument and

$$dx_{\mathbb{I}}(v_1, \dots, v_i, \dots, v_j, \dots, v_k) = -dx_{\mathbb{I}}(v_1, \dots, v_j, \dots, v_i, \dots, v_k)$$

Alternatively

Given any k -type index \mathbb{I} call $\mathbb{I}^<$

to be \mathbb{I} arranged in increasing order

e.g. $\mathbb{I} = \langle 3, 1, 2 \rangle \quad (3, 2, 1) \quad \mathbb{I}^< = (1, 2, 3)$

$$dx_{(3, 2, 1)} = -dx_{(1, 2, 3)}$$

since \mathbb{I} had to do

1 - transposition

to get from \mathbb{I} to $\mathbb{I}^<$

In general

$$dx_{\mathbb{I}^<} = (-1)^s dx_{\mathbb{I}}$$

$s = \#$ of transpositions

Then the set $dx_{\mathbb{I}}$ in \mathbb{I} increasing k -type in $\{1, \dots, n\}$

spans the linear space $\Delta^k(\mathbb{R}^n)^{\otimes k}$ of alternating

multi-linear functions from $(\mathbb{R}^n)^k \rightarrow \mathbb{R}$.

im $T \in \Lambda^k(\mathbb{R}^n)^*$

$$T = \sum_{\mathbf{I} \text{ increasing}} a_{\mathbf{I}} dx_{\mathbf{I}}$$

$$a_{\mathbf{I}} = T(e_{i_1}, \dots, e_{i_k})$$

$$\dim(\Lambda^k(\mathbb{R}^n)^*) = \binom{n}{k}$$

$dx_{\mathbf{I}}(v_1, \dots, v_k)$ is the signed volume of the

projection of parallelogram spanned by v_1, \dots, v_k

into x_{i_1}, \dots, x_{i_k} - plane.

We define the wedge product generalizing cross product

$\mathbf{I}, \mathbf{J} \in \mathcal{I}_k$, ℓ -type respectively

$$dx_{\mathbf{I}} \wedge dx_{\mathbf{J}} = dx_{(\mathbf{I}\mathbf{J})}$$

e.g.

$$dx_{(1,2)} \wedge dx_3 = dx_{(1,2,3)}$$

$$dx_{(3,1,5)} \wedge dx_{(4,2)} = dx_{(1,3,4,2,5)} = -dx_{(1,2,4,3,5)}$$

Then we extend by linearity $\omega \in \Delta^k(\mathbb{R}^n)$, $\eta \in \Delta^l(\mathbb{R}^n)$

$$\begin{aligned}\omega \wedge \eta &= \left(\sum_I a_I dx_I \right) \left(\sum_J b_J dx_J \right) \\ &= \sum_{I, J} a_I b_J dx_I \wedge dx_J\end{aligned}$$

Ex - $\omega = a_1 dx_1 + a_2 dx_2$ $\eta = b_1 dx_1 + b_2 dx_2$

Prop (i) $(\omega + \phi) \wedge \eta = \omega \wedge \eta + \phi \wedge \eta$, $(c\omega) \wedge \eta = c(\omega \wedge \eta)$

(ii) $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ $\omega \in \Delta^k$, $\eta \in \Delta^l$

(iii) $(\omega \wedge \eta) \wedge \phi = \omega \wedge (\eta \wedge \phi)$

Multilinear Algebra (contd...)

Last time define $\Delta^k(\mathbb{R}^n)$, wedge / exterior product

$$dx_i \wedge dx_j = dx_{(i,j)}$$

$\Delta^k(\mathbb{R}^n)$ is k -fold exterior product of \mathbb{R}^n

i.e. define wedge product for some vectors

as we did for dual vectors

$$\left. \begin{array}{l} v \wedge w = -w \wedge v \\ v \wedge v = 0 \end{array} \right\} \begin{array}{l} \text{extend from basis} \\ \text{by bilinearity} \end{array}$$

example

$$u, v \in \mathbb{R}^3$$

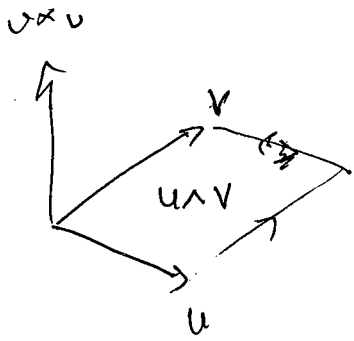
$$u = u_1 e_1 + u_2 e_2 + u_3 e_3$$

$$v = v_1 e_1 + v_2 e_2 + v_3 e_3$$

$$u \wedge v = (u_1 v_2 - u_2 v_1) e_1 \wedge e_2 + (u_1 v_3 - u_3 v_1) e_1 \wedge e_3 + (u_2 v_3 - u_3 v_2) e_2 \wedge e_3$$

$\{e_1 \wedge e_2, e_1 \wedge e_3, e_2 \wedge e_3\}$ is a basis for $\Delta^2(\mathbb{R}^3)$

$$\text{i.e. } \Delta^2(\mathbb{R}^3) \cong \mathbb{R}^3$$



$u \wedge v$ scales like $u \wedge v$

$$(t u \wedge s v) = t s (u \wedge v)$$

note that under the identification

$$e_1 \wedge e_2 \mapsto e_3$$

$$e_1 \wedge e_3 \mapsto e_2$$

$$e_2 \wedge e_3 \mapsto e_1$$

wedge and cross product are the same

wedge product generalizes (in a sense) the cross product.

$$\underline{\Lambda}^k(\mathbb{R}^n) = \{ \text{space of } k\text{-dim parallelograms in } \mathbb{R}^n \}$$

$$\underline{\Lambda}^k(\mathbb{R}^n)^* = \{ \text{or " linear functionals on } \underline{\Lambda}^k(\mathbb{R}^n) \}$$

Differential forms

$\Lambda^k(\mathbb{R}^n)$ is a natural linear space for integration

of k-dim systems, but we want the

corresponding nonlinear space.

0-form is a smooth function on \mathbb{R}^n

for k -form ω

~~form~~ ω on \mathbb{R}^n is

$$\omega = f(x) dx_1 \wedge \dots \wedge dx_n \quad x \in \mathbb{R}^n, \quad f \text{ smooth}$$

a differential k -form is

$$\omega = \sum_I f_I(x) dx_I = \sum_{i_1 < \dots < i_k} f_I(x) dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

where k -tuple I

$$f_I: \mathbb{R}^n \rightarrow \mathbb{R} \quad \text{smooth}$$

we can do the natural algebraic operations

- adding 2 k -forms
- scalar mult (mult by a 0-form)
- wedge k_1, k_2 forms.

$\Lambda^k(\mathbb{R}^n)$ = vector space of k -forms on \mathbb{R}^n

$\omega \in \Lambda^k(\mathbb{R}^n)$ $\eta \in \Lambda^l(\mathbb{R}^n)$ ~~$\phi \in \Lambda^m(\mathbb{R}^n)$~~

• addition, $\omega + (\eta + \phi) = (\omega + \eta) + \phi$

• $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$

• $(\omega \wedge \eta) \wedge \phi = \omega \wedge (\eta \wedge \phi)$

• $k=l$ $(\omega + \eta) \wedge \phi = \omega \wedge \phi + \eta \wedge \phi$

Exterior derivative

f a 0-form then

$df(x) = Df(x)$ is naturally a 1-form

$$= \sum_{i=1}^n \frac{\partial f}{\partial x_i} dx_i$$

if ω is a k -form $\omega = \sum_I f_I(x) dx_I$

defn $dw = \sum_I df_I \wedge dx_I = \sum_I \sum_{j=1}^n \frac{\partial f}{\partial x_j} dx_j \wedge dx_I$

~~Examples~~

~~Note: formal product rule~~

~~Note~~

~~$d(dx_1 \wedge \dots \wedge dx_k) = d^2 x_i$~~

Examples

① $f: \mathbb{R} \rightarrow \mathbb{R}$ smooth

$df(x) = f'(x) dx$

②

$\omega = y dx + x dy \in A^1(\mathbb{R}^2)$

$d\omega = dy \wedge dx + dx \wedge dy = 0$

③

~~$\omega = -y dx + x dy$~~

$d\omega = -dy \wedge dx + dx \wedge dy = 2 dx \wedge dy$

④

$\omega = P dx + Q dy$

$d\omega = \frac{\partial P}{\partial y} dy \wedge dx + \frac{\partial Q}{\partial x} dx \wedge dy = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx \wedge dy$

Thm

$\omega \in A^k(\mathbb{R}^n), \eta \in A^l(\mathbb{R}^n), f$ smooth

$L = \mathbb{R} \quad d(\omega + \eta) = d\omega + d\eta$

$d(f\omega) = df \wedge \omega + f d\omega$

$d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^k \omega \wedge d\eta$

$d(d\omega) = 0$

Proof

$$d(\omega \wedge \eta) = d(fg) \wedge dx_I \wedge dx_J$$

$$\text{where } \omega = f dx_I = (g df + f dg) \wedge dx_I \wedge dx_J$$

$$\eta = g dx_J = g df \wedge dx_I \wedge dx_J + f dg \wedge dx_I \wedge dx_J$$

$$= d\omega \wedge \eta + (-1)^k \omega \wedge d\eta$$

$$\omega = f dx_I$$

$$d(\omega) = d\left(\sum_{j=1}^n \frac{\partial f}{\partial x_j} dx_j \wedge dx_I\right)$$

$$= \sum_{i=1}^n \sum_{j=1}^n \frac{\partial^2 f}{\partial x_i \partial x_j} dx_i \wedge dx_j \wedge dx_I$$

$$= \sum_{i < j} \left(\frac{\partial^2 f}{\partial x_i \partial x_j} - \frac{\partial^2 f}{\partial x_j \partial x_i} \right) dx_i \wedge dx_j \wedge dx_I$$

$$= 0$$

by equality of mixed partials.

□

so

$$d: A^k(\mathbb{R}^n) \rightarrow A^{k+1}(\mathbb{R}^n)$$

$$d^2 = 0$$

We can integrate k -form on \mathbb{R}^n naturally, ~~but~~

or even k -form on k -dim submanifold of \mathbb{R}^n

but how to define integral of k -dim surface?

ω n -form in $\mathbb{R}^n \Rightarrow \omega = \sum f(x) dx_1 \wedge \dots \wedge dx_n$
(oriented)
 $R \subset \mathbb{R}^n$, partition into R_j

take i.e. each R_j parallelogram in \mathbb{R}^n

is \mathbb{R} -int x_j and

$$a_{j1} \wedge \dots \wedge a_{jn} \in \Lambda^n(\mathbb{R}^n)$$

$$\int_R \omega = \lim_{\text{mesh}(R) \rightarrow 0} \sum_i f(x_j) dx_{(1, \dots, n)}(a_{j1}, \dots, a_{jn})$$

$$= f(x_j) |R_j|$$

Pull backs

$$g: U \subset \mathbb{R}^m \rightarrow \mathbb{R}^n \text{ smooth}$$

(e.g. think of a smooth curve)

, we $\Lambda^k(\mathbb{R}^n)$

We define the pullback $g^* \omega$ as follows

if $\omega = f$ is a 0-form

$$g^* f = f \circ g$$

(i.e. take evaluation along param curve)

to pull back the basis 1-forms

~~g~~ call $x = g(u)$

$$g^* dx_i = dg_i = \sum_{j=1}^m \frac{\partial g_i}{\partial u_j} du_j$$

$$g^* dx_I = g^* (dx_{i_1} \wedge \dots \wedge dx_{i_k}) = dg_{i_1} \wedge \dots \wedge dg_{i_k} = dg_I$$

and
$$g^* \left(\sum_I f_I dx_I \right) = \sum_I (f_I \circ g) dg_I$$

Example 1 $g: \mathbb{R} \rightarrow \mathbb{R}^2$ $g(t) = (\cos t, \sin t)$

$$g^* dx = -\sin t dt$$

$$g^* dy = \cos t dt$$

it

$$\omega = x dx + y dy$$

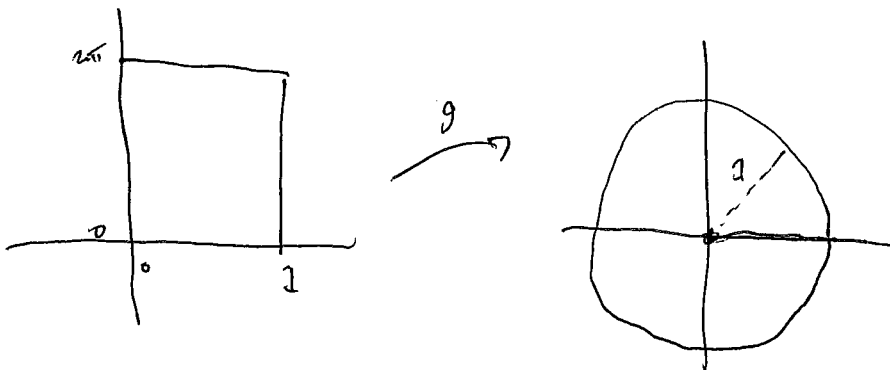
$$g^* \omega = \cos t (-\sin t) dt + \sin t (\cos t) dt = 0$$

$$\left\{ \begin{array}{l} \text{if } \omega = -y dx + x dy \\ g^* \omega = (-\sin t)(-\sin t dt) + \cos t (\cos t dt) \\ = (\sin^2 t + \cos^2 t) dt = dt \end{array} \right.$$

$$\textcircled{2} \quad g: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

~~$$g(t, \theta) = (r \cos \theta, r \sin \theta)$$~~

$$g(r, \theta) = (r \cos \theta, r \sin \theta)$$



$$\left\{ \begin{array}{l} \omega = x dx + y dy \\ g^* \omega = r \cos \theta g^* dx + r \sin \theta g^* dy \\ = r \cos \theta (\cos \theta dr - r \sin \theta d\theta) + r \sin \theta (\sin \theta dr + r \cos \theta d\theta) \\ = r (\cos^2 \theta + \sin^2 \theta) dr + 0 d\theta = r dr \end{array} \right.$$

$$\left\{ \begin{array}{l} \omega = dx \wedge dy \\ g^* \omega = g^* dx \wedge g^* dy = (\cos \theta dr - r \sin \theta d\theta) \wedge (\sin \theta dr + r \cos \theta d\theta) \\ = r (\cos^2 \theta + \sin^2 \theta) dr \wedge d\theta = r dr \wedge d\theta \end{array} \right.$$

(i.e. we recover change of variables then for polar coordinates)

Note the appearance of determinant in the example

$$g^*(dx_{\mathbb{R}^n}) = dg_{i_1} \wedge \dots \wedge dg_{i_k} = \left(\sum_{j=1}^n \frac{\partial g_{i_1}}{\partial u_j} du_j \right) \wedge \dots \wedge \left(\sum_{j=1}^n \frac{\partial g_{i_k}}{\partial u_j} du_j \right)$$

$$= \sum_{\substack{I \\ \text{inter k-tuple}}} \left(\sum_{\substack{\sigma \\ \text{perm} \\ \text{of } I}} \frac{\partial g_{i_1}}{\partial u_{\sigma(1)}} \dots \frac{\partial g_{i_k}}{\partial u_{\sigma(k)}} \operatorname{sgn}(\sigma) \right) du_I$$

$$= \sum_{\substack{I \\ \text{inter k-tuple}}} \det \left[\frac{\partial g_I}{\partial u_J} \right] du_I$$

$$= \sum_{\substack{I \\ \text{inter k-tuple}}} \begin{vmatrix} \frac{\partial g_{i_1}}{\partial u_{j_1}} & \dots & \frac{\partial g_{i_1}}{\partial u_{j_k}} \\ \vdots & & \vdots \\ \frac{\partial g_{i_k}}{\partial u_{j_1}} & \dots & \frac{\partial g_{i_k}}{\partial u_{j_k}} \end{vmatrix} du_{j_1} \wedge \dots \wedge du_{j_k}$$

Prop: $U \subseteq \mathbb{R}^m$ open $g: U \rightarrow \mathbb{R}^n$ smooth, we have that

$$g^*(d\omega) = d(g^*\omega)$$

Proof for $k=0$ (clear) and

$$d(g^*f) = d(f \circ g) = \sum_j \left(\sum_i \frac{\partial f}{\partial x_i} \circ g \frac{\partial g_{i_1}}{\partial u_j} \right) du_j = \sum_i \frac{\partial f}{\partial x_i} \circ g \left(\sum_j \frac{\partial g_{i_1}}{\partial u_j} du_j \right)$$

$$= \sum_{i=1}^n g^* \frac{\partial f}{\partial x_i} g^* dx_i$$

$$= g^* \left(\sum_{i=1}^n \frac{\partial f}{\partial x_i} dx_i \right) = g^* (df)$$

in general

$$g^* (d(f dx_{\mathbb{I}})) = g^* (df \wedge dx_{\mathbb{I}}) = g^*(df) \wedge g^*(dx_{\mathbb{I}})$$

$$= g^*(df) \wedge dg_{\mathbb{I}}$$

$$= d(g^* f) \wedge dg_{\mathbb{I}} =$$

$$= d(g^* f \wedge dg_{\mathbb{I}}) = d(g^*(f \wedge dx_{\mathbb{I}}))$$

$$\nearrow d^2 g_{\mathbb{I}} = 0$$

□

Connection w/ integration

n -form

$$\omega = f(x) dx_1 \wedge \dots \wedge dx_n$$

define

$$\int_V \omega = \int_V f$$

$U \subset \mathbb{R}^n$ open, with measure D .

old Riemann integral for fns

Thm $V \subseteq \mathbb{R}^n$ region, $g: V \rightarrow \mathbb{R}^n$ smooth 1-1 w/

$\det(Dg) > 0$. Then for any n -form $\omega = f dx_1 \wedge \dots \wedge dx_n$

on $g(V)$ we have

$$\int_{g(V)} \omega = \int_V g^* \omega$$

proof: already saw

$$g^* \omega = g^* (f dx_1 \wedge \dots \wedge dx_n)$$

$$= (f \circ g) g^* (dx_1 \wedge \dots \wedge dx_n)$$

$$= f \circ g \det[Dg] = f \circ g |\det Dg|$$

(same as change of vds form)

□

Def: let $U \subseteq \mathbb{R}^k$, $g: U \rightarrow \mathbb{R}^n$ smooth 1-1

w/ Dg has rank k $\forall x \in U$.

Call $M = g(V)$ this is a

parametrized k -dim manifold we define

$$\int_M \omega = \int_V g^* \omega$$

Note: this agrees w/ defn for curves that

we already gave

If g_1, g_2 both param M and

$$\det [Dg_2^{-1} \circ g_1] > 0 \quad (\text{same orientation}) \text{ then}$$

$$\int_{U_2} g_2^* \omega = \int_{\substack{U_1 \\ U_1}} (g_2^{-1} \circ g_1)^* (g_2^* \omega)$$

$$= \int_{U_1} (g_2 \circ g_2^{-1} \circ g_1)^* \omega \quad \downarrow \text{exercise}$$

$$= \int_{U_1} g_1^* \omega$$