

Section 3.4

#27 Find the matrix B of $T(\vec{x}) = A\vec{x}$ with respect to $\mathcal{B} = (\vec{v}_1, \vec{v}_2, \vec{v}_3)$

$$A = \begin{bmatrix} 4 & 2 & -4 \\ 2 & 1 & -2 \\ -4 & -2 & 4 \end{bmatrix}, \quad \vec{v}_1 = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \quad \vec{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

$$A\vec{v}_1 = \begin{bmatrix} 4 & 2 & -4 \\ 2 & 1 & -2 \\ -4 & -2 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix} = \begin{bmatrix} 18 \\ 9 \\ -18 \end{bmatrix} = 9 \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix} = 9\vec{v}_1$$

$$A\vec{v}_2 = \begin{bmatrix} 4 & 2 & -4 \\ 2 & 1 & -2 \\ -4 & -2 & 4 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = 0 \cdot \vec{v}_1 + 0 \cdot \vec{v}_2 + 0 \cdot \vec{v}_3$$

$$A\vec{v}_3 = \begin{bmatrix} 4 & 2 & -4 \\ 2 & 1 & -2 \\ -4 & -2 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow B = \begin{bmatrix} 9 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

#34. $\beta = (\vec{v}_1, \vec{v}_2, \vec{v}_3)$ basis of \mathbb{R}^3 consisting of perpendicular unit vectors. $\vec{v}_3 = \vec{v}_1 \times \vec{v}_2$. Find the β -matrix for

$$T(\vec{x}) = \vec{x} - 2(\vec{v}_3 \cdot \vec{x}) \cdot \vec{v}_3$$

Solution:

$$T(\vec{v}_1) = \vec{v}_1 - 2(\vec{v}_3 \cdot \vec{v}_1) \cdot \vec{v}_3 = \vec{v}_1$$

$$T(\vec{v}_2) = \vec{v}_2 - 2(\vec{v}_3 \cdot \vec{v}_2) \cdot \vec{v}_3 = \vec{v}_2$$

$$T(\vec{v}_3) = \vec{v}_3 - 2(\vec{v}_3 \cdot \vec{v}_3) \cdot \vec{v}_3 = -\vec{v}_3$$

$$\Rightarrow B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$\Rightarrow T$ represents a reflection about the plane spanned by \vec{v}_1, \vec{v}_2 .

#39. Find β of \mathbb{R}^3 st β -matrix of T is diagonal if T is a reflection about the line in \mathbb{R}^3 spanned by $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$.

Solution:

We are looking for $\beta = (\vec{v}_1, \vec{v}_2, \vec{v}_3)$ so that

$$T(\vec{v}_1) = k_1 \vec{v}_1$$

$$T(\vec{v}_2) = k_2 \vec{v}_2$$

$$T(\vec{v}_3) = k_3 \vec{v}_3$$

$$\text{, because then } B = \begin{bmatrix} k_1 & 0 & 0 \\ 0 & k_2 & 0 \\ 0 & 0 & k_3 \end{bmatrix}$$

For \vec{v}_1 we can take $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, since $T\left(\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ $\therefore k_1 = 1$.

For \vec{v}_2 $\&$ \vec{v}_3 we can take vectors that are perpendicular to \vec{v}_1 , since then $T(\vec{v}_2) = -\vec{v}_2$ $\&$ $T(\vec{v}_3) = -\vec{v}_3$, so $k_2 = k_3 = -1$.

We are looking for $\vec{v}_2 \in \mathbb{R}^3$ st $\vec{v}_3 \cdot \vec{v}_1 = 0$ & $\vec{v}_2 \cdot \vec{v}_1 = 0$,
 i.e. we're looking for the kernel of $A = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}$.

$$\Rightarrow x_1 = -2x_2 - 3x_3$$

$$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$$

$$\Rightarrow \vec{v}_2 = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \text{ \& \; } \vec{v}_3 = \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$$

#46. Consider the plane $x_1 + 2x_2 + x_3 = 0$. Find a basis B of this plane such that $[\vec{x}]_B = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ for $\vec{x} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$.

Solution:

$$V = \{x_1 + 2x_2 + x_3 = 0\}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in V \Leftrightarrow x_1 = -2x_2 - x_3$$

We are looking for $\vec{v}_1 = \begin{bmatrix} -2a-b \\ a \\ b \end{bmatrix}$ & $\vec{v}_2 = \begin{bmatrix} -2c-d \\ c \\ d \end{bmatrix}$

$$\text{st } \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} = 2 \begin{bmatrix} -2a-b \\ a \\ b \end{bmatrix} - \begin{bmatrix} -2c-d \\ c \\ d \end{bmatrix} = \begin{bmatrix} -4a-2b+2c+d \\ 2a-c \\ 2b-d \end{bmatrix} \Rightarrow$$

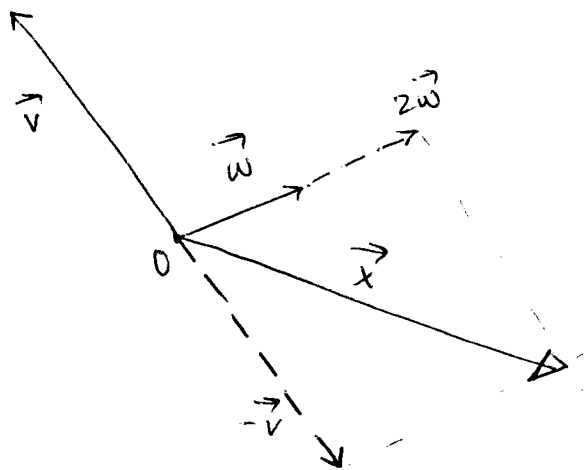
$$\Rightarrow \left[\begin{array}{ccc|cc} 2 & 0 & -1 & 0 & -1 \\ 0 & 2 & 0 & -1 & 1 \\ -4 & -2 & 2 & 1 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|cc} 2 & 0 & -1 & 0 & -1 \\ 0 & 2 & 0 & -1 & 1 \\ 0 & -2 & 0 & 1 & -1 \end{array} \right] \sim$$

$$\sim \left[\begin{array}{ccc|cc} 2 & 0 & -1 & 0 & -1 \\ 0 & 2 & 0 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \Rightarrow \begin{array}{l} 2a - c = -1 \Rightarrow c = 2a + 1 \\ 2b - d = 1 \Rightarrow d = 2b - 1 \end{array}$$

$$\begin{aligned} a=1 &\Rightarrow c=3 \\ b=0 &\Rightarrow d=-1 \end{aligned}$$

$$\rightarrow \vec{v}_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \quad \& \quad \vec{v}_2 = \begin{bmatrix} -5 \\ 3 \\ -1 \end{bmatrix}$$

#48. Sketch vector \vec{x} with $[\vec{x}]_{\mathcal{B}} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, where \mathcal{B} is a basis consisting of \vec{v} & \vec{w} .



#59. Is a matrix $\begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$ similar to $\begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$?

Solution:

Is there an invertible $S = \begin{bmatrix} x & y \\ z & w \end{bmatrix}$ st

$$\begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} x & y \\ z & w \end{bmatrix} = \begin{bmatrix} x & y \\ z & w \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$$

$$\Leftrightarrow \begin{bmatrix} 2x & 2y \\ 3z & 3w \end{bmatrix} = \begin{bmatrix} 2x & x+3y \\ 2z & z+3w \end{bmatrix} \Leftrightarrow$$

$$2x = 2x$$

$$2y = x + 3y \Rightarrow x = -y$$

$$3z = 2z \Rightarrow z = 0$$

$$3w = z + 3w$$

$$\Rightarrow 3w = 3w$$

$$\Leftrightarrow S = \begin{bmatrix} -y & y \\ 0 & w \end{bmatrix} \text{ and if}$$

$y \neq 0 \neq w$ S is invertible, so the answer is YES.

Section 4.1.

#5. Is $V = \{p(t) \cdot p(-t) = -p(t), \forall t\}$ a subspace of P_2 ? If so, find its basis.

Solution

• Let $f, g \in V$ & $k, l \in \mathbb{R}$. Then

$$\begin{aligned} (kf + lg)(-t) &= (kf)(-t) + (lg)(-t) = kf(-t) + lg(-t) = -kf(t) - lg(t) = \\ &= -(kf + lg)(t) \quad \Rightarrow \quad kf + lg \in V \Rightarrow V \text{ is a subspace.} \end{aligned}$$

• $f \in V$ & $f(t) = at^2 + bt + c$

$$f(-t) = at^2 - bt + c$$

$$-f(t) = -at^2 - bt - c$$

$$\left\{ \begin{array}{l} f(-t) = -f(t) \Rightarrow \\ at^2 - bt + c = -at^2 - bt - c \Rightarrow \end{array} \right.$$

$$at^2 - bt + c = -at^2 - bt - c \Rightarrow$$

$$\Rightarrow 2at^2 + 2c = 0 \Rightarrow a = 0 \text{ \& \;} c = 0$$

$$\Rightarrow f(t) = bt$$

\Rightarrow Basis of V is $\{t\}$.

#10: Do all 3×3 matrices A st $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ is in the kernel of A form a subspace of $M_{3,3}$?

Solution:

Yes. Let $A, B \in M_{3,3}$ st $A \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \vec{0}$ & $B \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \vec{0}$. Let $k, l \in \mathbb{R}$. Then

$$(kA + lB) \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = kA \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + lB \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = k \cdot \vec{0} + l \cdot \vec{0} = \vec{0} \Rightarrow$$

$$\Rightarrow \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \in \ker(kA + lB)$$

#12. $V =$ set of all infinite sequences.

$W =$ set of all arithmetic sequences. $= (a, a+k, a+2k, \dots)$
for some $a, k \in \mathbb{R}$

Is W a subspace of V ?

Solution:

Let $(x_0, x_1, x_2, \dots), (y_0, y_1, y_2, \dots) \in W$ & $k, l \in \mathbb{R}$.

$(x_0, x_1, x_2, \dots) \in W \Rightarrow x_n = x_0 + n \cdot p$, for some $p \in \mathbb{R}$

$(y_0, y_1, y_2, \dots) \in W \Rightarrow y_n = y_0 + n \cdot r$, for some $r \in \mathbb{R}$

$$k(x_0, x_1, x_2, \dots) + l(y_0, y_1, y_2, \dots) = (kx_0 + ly_0, kx_1 + ly_1, \dots, kx_n + ly_n, \dots) =$$

$$= (kx_0 + ly_0, \dots, k(x_0 + np) + l(y_0 + nr), \dots) =$$

$$= (kx_0 + ly_0, \dots, (kx_0 + ly_0) + n \cdot (kp + lr), \dots) =$$

$=$ arithmetic sequence with initial element $kx_0 + ly_0$ &
additive constant $kp + lr \in \mathbb{R} \Rightarrow$

$\Rightarrow W$ is a subspace of V .

#31. Find a basis & dimension of $V = \{S \in M_{2,2} : \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} S = S \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}\}$

Solution:

$$S = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in V \Leftrightarrow \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} S = S \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \Leftrightarrow$$

$$\Leftrightarrow \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \Leftrightarrow \begin{bmatrix} c & d \\ a & b \end{bmatrix} = \begin{bmatrix} a & -b \\ c & -d \end{bmatrix} \Leftrightarrow$$

$$\Leftrightarrow \begin{matrix} c = a \\ d = -b \end{matrix} \Rightarrow S = \begin{bmatrix} a & b \\ a & -b \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix} \Rightarrow$$

$\Rightarrow \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$ & $\begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix}$ span V . Since they are lin. ind., they

form a basis of $V \Rightarrow \dim V = 2$.

#35. $V = \{A \in M_{33} : AB = BA\}$; $B = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

Find basis of V & its dimension

Solution:

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \in V$$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\begin{bmatrix} 2a_{11} & 3a_{12} & 4a_{13} \\ 2a_{21} & 3a_{22} & 4a_{23} \\ 2a_{31} & 3a_{32} & 4a_{33} \end{bmatrix} = \begin{bmatrix} 2a_{11} & 2a_{12} & 2a_{13} \\ 3a_{21} & 3a_{22} & 3a_{23} \\ 4a_{31} & 4a_{32} & 4a_{33} \end{bmatrix}$$

$3a_{12} = 2a_{12} \Rightarrow a_{12} = 0$, Similarly for all off-diagonal entries

$$\Rightarrow A = \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{bmatrix} = a_{11} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}}_{A_1} + a_{22} \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}}_{A_2} + a_{33} \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{A_3}$$

$\Rightarrow A_1, A_2, A_3$ span V and are lin. independent $\Rightarrow (A_1, A_2, A_3)$ is a basis $\rightarrow \dim V = 3$.

#37: $V = \{A \in M_{33} : AB = BA\}$ where $B = \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$

Basis of V & dim of V ?

Solution:

As above we get

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \in V \Leftrightarrow \begin{bmatrix} aa_{11} & ba_{12} & ca_{13} \\ aa_{21} & ba_{22} & ca_{23} \\ aa_{31} & ba_{32} & ca_{33} \end{bmatrix} = \begin{bmatrix} aa_{11} & aa_{12} & aa_{13} \\ ba_{21} & ba_{22} & ba_{23} \\ ca_{31} & ca_{32} & ca_{33} \end{bmatrix}$$

- a, b, c are all distinct

then we are in the same situation as above and vectors

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ is a basis}$$

and $\dim V = 3$

- $a \neq b = c$

$$\begin{bmatrix} aa_{11} & ba_{12} & ba_{13} \\ aa_{21} & ba_{22} & ba_{23} \\ aa_{31} & ba_{32} & ba_{33} \end{bmatrix} = \begin{bmatrix} aa_{11} & aa_{12} & aa_{13} \\ ba_{21} & ba_{22} & ba_{23} \\ ba_{31} & ba_{32} & ba_{33} \end{bmatrix} \Rightarrow \begin{matrix} a_{12} = a_{13} = a_{21} = \\ = a_{31} = 0 \end{matrix}$$

$$\Rightarrow \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{bmatrix} = a_{11} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + a_{22} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + a_{23} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} +$$

$$+ a_{32} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} + a_{33} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$\Rightarrow \dim V = 5$

- $a = b = c \Rightarrow B = a \cdot I \quad AB = A \cdot (aI) = a \cdot A \cdot I = a \cdot IA = BA$,
for all 3×3 matrices \rightarrow $\dim V = 9$

Section 4.2.

- #7 Is $T: M_{2,2} \rightarrow M_{2,2}$ defined by $T(M) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} M$ a linear transf? Is it an isomorphism?

Solution

$$T(M+N) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} (M+N) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} M + \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} N = T(M) + T(N)$$

$$T(kM) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} kM = k \cdot \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} M = k \cdot T(M)$$

$\Rightarrow T$ is linear.

T is an isomorphism if $T(M) = N$ has a unique solution $\forall N \in M_{2,2}$.

$T(M) = N \Leftrightarrow \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} M = N$ has unique solution if

$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}^{-1}$ exists, because then $M = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}^{-1} \cdot N$ is the unique

solution.

$$\left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 3 & 4 & 0 & 1 \end{array} \right] \sim \left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 0 & -2 & -3 & 1 \end{array} \right] \sim \left[\begin{array}{cc|cc} 1 & 0 & -2 & 1 \\ 0 & -2 & -3 & 1 \end{array} \right] \sim \left[\begin{array}{cc|cc} 1 & 0 & -2 & 1 \\ 0 & 1 & 3/2 & -1/2 \end{array} \right]$$

$\Rightarrow T$ is an isomorphism.

≡

12. Same Q for $T: \mathbb{R} \rightarrow M_{2,2}$, $T(c) = c \cdot \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}$

Solution

$k \in \mathbb{R}$ $T(kc) = kc \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = k \cdot T(c)$

$c_1, c_2 \in \mathbb{R}$ $T(c_1 + c_2) = (c_1 + c_2) \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = c_1 \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} + c_2 \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = T(c_1) + T(c_2)$

$\Rightarrow T$ is linear, but it can't be an isomorphism:

$\dim \text{Im} T = 1$, while $\dim M_{2,2} = 4$.

24: $T: P_2 \rightarrow P_2$, $T(f(t)) = f'(t) \cdot f(t)$

Solution:

$f, g \in P_2$

$$\begin{aligned} T((f+g)(t)) &= (f+g)'(t) \cdot (f+g)(t) = \\ &= (f'(t) + g'(t)) \cdot (f(t) + g(t)) = \\ &= f'(t) \cdot f(t) + f'(t) \cdot g(t) + g'(t) \cdot f(t) + g'(t) \cdot g(t) \\ &\neq f''(t) f(t) + g''(t) g(t) = T(f(t)) + T(g(t)) \end{aligned}$$

$\Rightarrow T$ is not linear.

≡

$$\# 30. T: P_2 \rightarrow P_2$$

$$T(f(t)) = t \cdot (f'(t))$$

Solution:

$$f, g \in P_2$$

$$\begin{aligned} T((f+g)(t)) &= t \cdot (f+g)'(t) = t \cdot (f'(t) + g'(t)) = \\ &= t f'(t) + t g'(t) = T(f(t)) + T(g(t)) \end{aligned}$$

$$k \in \mathbb{R}, f \in P_2$$

$$T((kf)(t)) = t \cdot (kf)'(t) = k \cdot t f'(t) = k T(f(t))$$

$\Rightarrow T$ is linear, but it is not an isomorphism, because $f(t) = c$, $c \neq 0$, is not in the image of T .

$$\# 36. T: P \rightarrow V$$

P space of all polynomials,
 V space of all infinite sequences

$$T(f(t)) = (f(0), f(1), f(2), f(3), \dots)$$

Solution:

$$f, g \in P$$

$$\begin{aligned} T((f+g)(t)) &= ((f+g)(0), (f+g)(1), \dots) = \\ &= (f(0)+g(0), f(1)+g(1), \dots) = \\ &= (f(0), f(1), \dots) + (g(0), g(1), \dots) = T(f(t)) + T(g(t)) \end{aligned}$$

$$f \in P, k \in \mathbb{R}$$

$$\begin{aligned} T((kf)(t)) &= ((kf)(0), (kf)(1), \dots) = (k f(0), k f(1), \dots) = \\ &= k (f(0), f(1), \dots) = k \cdot T(f(t)) \end{aligned}$$

$\Rightarrow T$ is linear

Consider, the sequence $(7, 0, 0, 0, \dots) \in V$ whose first component is 7, and all others are 0. If

$$T(f(t)) = (7, 0, 0, \dots), \text{ then } f(n) = 0, \forall n > 1, \text{ so}$$

f has infinitely many zeros, which can be true only if f is a zero polynomial, but in that case $f(0) = 0 \neq 7$, so

$$(7, 0, 0, 0, \dots) \notin \text{Im } T \Rightarrow V \neq \text{Im } T \Rightarrow T \text{ is not an isomorphism}$$

#40/ $T: C^\infty \rightarrow C^\infty$, $T(f) = f'' + 2f' + f$

T is linear

$$T(f+g) = (f+g)'' + 2(f+g)' + f+g = f'' + g'' + 2f' + 2g' + f + g = T(f) + T(g)$$

$$\begin{aligned} T(kf) &= (kf)'' + 2(kf)' + (kf) = T(f) \\ &= kf'' + 2kf' + kf = kT(f) \end{aligned}$$

Let's try to see if there is anything in the kernel of T.

$$f(x) = e^{kx}; \quad f'(x) = k \cdot e^{kx}; \quad f''(x) = k^2 e^{kx}$$

$$T(e^{kx}) = k^2 e^{kx} + 2k e^{kx} + e^{kx} = (k^2 + 2k + 1) e^{kx} = 0, \quad \forall x \Leftrightarrow$$

$$k^2 + 2k + 1 = (k+1)^2 = 0 \quad (\Rightarrow) \quad k = -1$$

$\Rightarrow f(x) = e^{-x} \in \ker T \Rightarrow T$ is not an isomorphism.

#56/ Find Image, rank, kernel & nullity of T from #30.

Solution

$$T: P_2 \rightarrow P_2, \quad \dim P_2 = 3 \quad \text{basis} = (1, t, t^2).$$

$$T(f(t)) = t \cdot f'(t)$$

$$f \in \ker T \Leftrightarrow T(f(t)) = 0 \Leftrightarrow t \cdot f'(t) = 0 \Leftrightarrow f'(t) = 0 \Leftrightarrow f(t) = a,$$

$$a \in \mathbb{R} \Rightarrow f(t) = a \cdot 1 \Rightarrow \ker T = \text{span}(1) \Rightarrow \text{nullity}(T) = 1$$

$$f(t) = a + bt + ct^2 \Rightarrow f'(t) = b + 2ct \Rightarrow t \cdot f'(t) = bt + 2ct^2 = b \cdot t + c \cdot 2t^2$$

$\Rightarrow \text{Im} T$ is spanned by $\{t, 2t^2\}$ (which is a basis)

$$\Rightarrow \text{rank}(T) = 2.$$

#64/ Define an isomorphism from P_2 to $M_{2,2}$, if you can.

Can't be done; $\dim P_2 = 3$ & $\dim M_{2,2} = 4$.

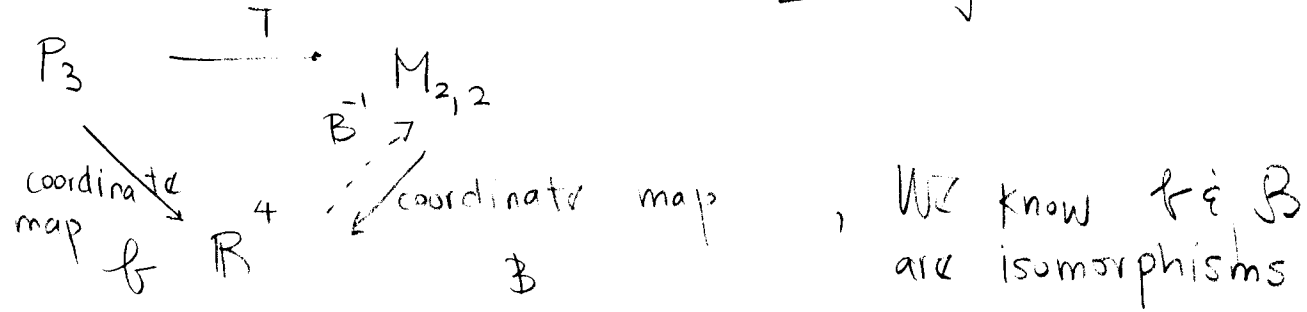
Except that wasn't a problem. Turn to the last page!

Define an isomorphism from \mathbb{P}_3 to $M_{2,2}$.

$$T: \mathbb{P}_3 \rightarrow M_{2,2}$$

$$T(a+bt+ct^2+dt^3) = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

Consider



Then $f = B \circ T$, but B is invertible, so

$T = B^{-1} \circ f$ is a composition of two isomorphisms is an isomorphism.