

Section 3.2.

#6. Consider two subspaces  $V, W$  of  $\mathbb{R}^n$

- a) Is  $V \cap W$  necessarily a subspace of  $\mathbb{R}^n$ ?  
 b) Is  $V \cup W$  necessarily a subspace of  $\mathbb{R}^n$ ?

Solution

a) Yes. Let  $\vec{x}, \vec{y} \in V \cap W$  and  $a, b \in \mathbb{R}$ .

Since  $V \leq \mathbb{R}^n$  &  $\vec{x}, \vec{y} \in V \Rightarrow a\vec{x} + b\vec{y} \in V$

Since  $W \leq \mathbb{R}^n$  &  $\vec{x}, \vec{y} \in W \Rightarrow a\vec{x} + b\vec{y} \in W \quad \therefore \Rightarrow$

$\Rightarrow a\vec{x} + b\vec{y} \in V \cap W \Rightarrow V \cap W \leq \mathbb{R}^n$ .

b) No. Consider  $V = \text{Span}(\vec{e}_1)$  &  $W = \text{Span}(\vec{e}_2)$ . Then  $\vec{e}_1 + \vec{e}_2 \notin V \cup W$ ,  
 i.e.  $V \cup W$  is not closed under addition

#24. Find redundant column vector, write it as a lin. combination of the preceding columns. Write nontrivial relation among columns and thus find a nonzero vector in  $\ker A$ .

$$A = \begin{bmatrix} 1 & 3 & 6 \\ 1 & 2 & 5 \\ 1 & 1 & 4 \end{bmatrix}$$

Solution: Column 2 is not a multiple of the first, so two of them are linearly independent. We will try to see if there are  $a, b \in \mathbb{R}$  st

$$a \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 5 \\ 4 \end{bmatrix} \quad (\Leftrightarrow) \quad a\vec{v}_1 + b\vec{v}_2 = \vec{v}_3$$

$$\left[ \begin{array}{cc|c} 1 & 3 & 6 \\ 1 & 2 & 5 \\ 1 & 1 & 4 \end{array} \right] = \left[ \begin{array}{cc|c} 1 & 3 & 6 \\ 0 & -1 & -1 \\ 0 & -2 & -2 \end{array} \right] \sim \left[ \begin{array}{cc|c} 1 & 3 & 6 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{array} \right] \sim \left[ \begin{array}{cc|c} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{array} \right] \quad (\Leftrightarrow) \quad \begin{matrix} a=3 \\ b=1 \end{matrix}$$

$$\begin{bmatrix} 6 \\ 5 \\ 4 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} \quad (\Leftrightarrow)$$

$$(\Leftrightarrow) \quad 3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} - \begin{bmatrix} 6 \\ 5 \\ 4 \end{bmatrix} = \vec{0} \Rightarrow \begin{bmatrix} 1 & 3 & 6 \\ 1 & 2 & 5 \\ 1 & 1 & 4 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix} = \vec{0}$$

$$\Rightarrow \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix} \in \ker A.$$

#34 Consider a  $5 \times 4$  matrix

$$A = \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 & \vec{v}_4 \end{bmatrix}$$

We are told that  $\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$  is in the kernel of  $A$ . Write  $\vec{v}_4$  as a linear combination of  $\vec{v}_1, \vec{v}_2, \vec{v}_3$ .

Solution:

$$A \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \vec{0} \Leftrightarrow \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 & \vec{v}_4 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \vec{0} \Rightarrow$$

$$\Rightarrow \vec{v}_1 + 2\vec{v}_2 + 3\vec{v}_3 + 4\vec{v}_4 = \vec{0} \Leftrightarrow 4\vec{v}_4 = -\vec{v}_1 - 2\vec{v}_2 - 3\vec{v}_3 \Leftrightarrow$$

$$\Leftrightarrow \vec{v}_4 = -\frac{1}{4}\vec{v}_1 - \frac{1}{2}\vec{v}_2 - \frac{3}{4}\vec{v}_3$$

#36: Consider a linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^p$  and some linearly dependent vectors  $\vec{v}_1, \dots, \vec{v}_m \in \mathbb{R}^n$ . Are the vectors  $T(\vec{v}_1), \dots, T(\vec{v}_m)$  necessarily linearly dependent? How can you tell?

Solution:

Yes. Since  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m$  are linearly dependent we can find real numbers  $c_1, c_2, \dots, c_m$  which are not all zeros such that

$$c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_m\vec{v}_m = \vec{0}$$

$$\text{then } 0 = T(c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_m\vec{v}_m) = \\ = c_1 T(\vec{v}_1) + c_2 T(\vec{v}_2) + \dots + c_m T(\vec{v}_m)$$

and not all  $c_i$  are zero, i.e. we got a nontrivial relation among vectors  $T(\vec{v}_1), \dots, T(\vec{v}_m) \Rightarrow T(\vec{v}_1), \dots, T(\vec{v}_m)$  are lin. dependent.

#37. Consider a linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^p$  and some linearly independent vectors  $\vec{v}_1, \dots, \vec{v}_m \in \mathbb{R}^n$ . Are the vectors  $T(\vec{v}_1), \dots, T(\vec{v}_m)$  necessarily lin. indep.? How can you tell?

Solution:

No. It is possible that some nontrivial linear combination of vectors  $\vec{v}_1, \dots, \vec{v}_m$  ( $c_1\vec{v}_1 + \dots + c_m\vec{v}_m$ , some  $c_i \neq 0$ ) is in the kernel of  $T$ :

$$T(c_1\vec{v}_1 + \dots + c_m\vec{v}_m) = \vec{0}$$

$$\text{"} \\ c_1 T(\vec{v}_1) + \dots + c_m T(\vec{v}_m) = \vec{0} \quad \text{and some } c_i \neq 0 \Rightarrow$$

$\Rightarrow T(\vec{v}_1), \dots, T(\vec{v}_m)$  are not lin. independent.

#50. Consider two subspaces  $V$  and  $W$  of  $\mathbb{R}^n$ . Let  $V+W$  be the set of all vectors in  $\mathbb{R}^n$  of the form  $\vec{v} + \vec{w}$ , where  $\vec{v} \in V$  and  $\vec{w} \in W$ . Is  $V+W$  necessarily a subspace of  $\mathbb{R}^n$ ? If  $V$  and  $W$  are two distinct lines in  $\mathbb{R}^3$  what is  $V+W$ ? Draw a sketch.

Solution:

$V+W$  is always a subspace of  $\mathbb{R}^n$ . Let  $\vec{x}, \vec{y} \in V+W$  and  $a, b \in \mathbb{R}$ . We claim  $a\vec{x} + b\vec{y}$  is also in  $V+W$ .

$$\vec{x} \in V+W \rightarrow \vec{x} = \vec{v}_1 + \vec{w}_1 \quad \text{where } \vec{v}_1 \in V \text{ \& } \vec{w}_1 \in W$$

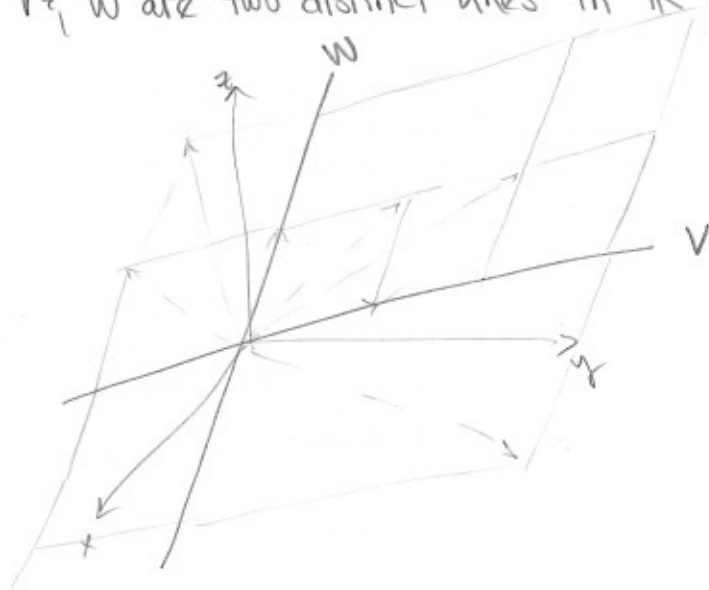
$$\vec{y} \in V+W \rightarrow \vec{y} = \vec{v}_2 + \vec{w}_2 \quad \text{where } \vec{v}_2 \in V \text{ \& } \vec{w}_2 \in W.$$

Then

$$a\vec{x} + b\vec{y} = a(\vec{v}_1 + \vec{w}_1) + b(\vec{v}_2 + \vec{w}_2) = \underbrace{(a\vec{v}_1 + b\vec{v}_2)}_{\in V} + \underbrace{(a\vec{w}_1 + b\vec{w}_2)}_{\in W} \in V+W.$$

since  $V$  is a subspace
since  $W$  is a subspace

If  $V$  \&  $W$  are two distinct lines in  $\mathbb{R}^3$ , then  $V+W$  is a plane



# homework set #4

## Section 3.3:

#22. Find  $\text{rref}(A)$ , basis for the image & kernel of  $A$ .

$$A = \begin{bmatrix} 2 & 4 & 8 \\ 4 & 5 & 1 \\ 7 & 9 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 4 & 8 \\ 4 & 5 & 1 \\ 7 & 9 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 4 \\ 4 & 5 & 1 \\ 7 & 9 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 4 \\ 0 & -3 & -15 \\ 0 & 5 & -25 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 5 \\ 0 & 1 & 5 \end{bmatrix} \sim$$

$$\sim \begin{bmatrix} 1 & 0 & -6 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{bmatrix} = \text{rref}(A)$$

$$\Rightarrow \vec{v}_3 = -6\vec{v}_1 + 5\vec{v}_2 \Rightarrow$$

$\Rightarrow$  Same relationship holds for column vectors of  $A$

$\Rightarrow \text{Im } A$  is spanned by 1st & 2nd column vector, in fact they form the basis of  $\text{Im } A$ .

$$\text{basis of } \text{Im } A = \left\{ \begin{bmatrix} 2 \\ 4 \\ 7 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 9 \end{bmatrix} \right\}$$

$$\text{From } \text{rref } A \quad \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \text{ker } A \text{ if } \begin{cases} x_1 - 6x_3 = 0 \\ x_2 + 5x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = 6x_3 \\ x_2 = -5x_3 \end{cases}$$

$$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6x_3 \\ -5x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 6 \\ -5 \\ 1 \end{bmatrix}$$

$$\text{basis for } \text{ker } A = \left\{ \begin{bmatrix} 6 \\ -5 \\ 1 \end{bmatrix} \right\}$$

#26: Consider the matrices

$$C = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix}, H = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}, L = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix},$$

$$T = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}, X = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}, Y = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

- a) which of the matrices have the same kernel as C  
 b) which of the matrices have the same image as C  
 c) which of these matrices has an image that is different from the images of all other matrices in the list?

a) Reminder:  $A = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3]$  is a  $3 \times 3$  matrix &  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \ker A$  iff  $x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3 = \vec{0}$

For C:  $\vec{v}_2 = \vec{v}_3$ , so we have  $x_1 \vec{v}_1 + (x_2 + x_3) \vec{v}_2 = \vec{0}$  &  $\vec{v}_1, \vec{v}_2$  are lin. independent so  $x_1 = 0$  &  $x_2 = -x_3 \Rightarrow$   
 $\Rightarrow$  basis for  $\ker C = \left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\}$

For H:  $\vec{v}_1 = \vec{v}_3 \Rightarrow (x_1 + x_3) \vec{v}_1 + x_2 \vec{v}_2 = \vec{0}$  &  $\vec{v}_1, \vec{v}_2$  are lin. independent  
 $\Rightarrow x_1 + x_3 = 0$  &  $x_2 = 0 \Rightarrow$  basis for  $\ker H = \left\{ \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$ .

L has  $\vec{v}_2 = \vec{v}_3 \Rightarrow \ker L = \ker C$

T, X & Y have  $\vec{v}_1 = \vec{v}_3 \Rightarrow \ker T = \ker X = \ker Y = \ker H$ .

$\Rightarrow$  The only matrix with kernel equal to that of C is L.

b) We see that first two columns of C are lin. independent, hence they form a basis for  $\text{Im} C$ . So if  $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$  is in  $\text{Im} C$ , then

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = a \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} a+b \\ a \\ a+b \end{bmatrix}, \text{ for some } a, b \in \mathbb{R} \Rightarrow$$

$\Rightarrow$  We see that 1st & 3rd coordinates of  $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$  are equal

that is  $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \in \text{Im } C \Leftrightarrow y_1 = y_3.$

H: Similar considerations show that

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \in \text{Im } H \Leftrightarrow \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = a \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a \\ a+b \\ a \end{bmatrix} \Leftrightarrow y_1 = y_3$$

$$L: \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \in \text{Im } L \Leftrightarrow \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = a \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ a \\ a+b \end{bmatrix} \Leftrightarrow y_1 = y_2$$

$$T: \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \in \text{Im } T \Leftrightarrow \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + b \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} a+b \\ b \\ b \end{bmatrix} \Leftrightarrow y_2 = y_3$$

$$X: \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \in \text{Im } X \Leftrightarrow \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a \\ b \\ a \end{bmatrix} \Leftrightarrow y_1 = y_3$$

$$Y: \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \in \text{Im } Y \Leftrightarrow \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \\ b \end{bmatrix} \Leftrightarrow y_2 = y_3$$

$$\Rightarrow \text{Im } C = \text{Im } H = \text{Im } X \quad ; \quad \text{Im } T = \text{Im } Y$$

c) From b) we see that the answer is L.

31. Let  $V$  be the subspace of  $\mathbb{R}^4$  defined by the equation

$$x_1 - x_2 + 2x_3 + 4x_4 = 0$$

Find a linear transformation  $T$  from  $\mathbb{R}^3$  to  $\mathbb{R}^4$  st  $\text{Ker } T = \{0\}$  and  $\text{Im } T = V$ . Describe  $T$  by its matrix  $A$ .

Solution:  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^4 \Rightarrow A$  is a  $4 \times 3$  matrix. Its column vectors should be basis vectors of  $V$  since column vectors span the  $\text{Im } A$ . We need to find basis for  $V$ .  $\Leftrightarrow$  we need to solve  $x_1 - x_2 + 2x_3 + 4x_4 = 0$   
 $x_1 = x_2 - 2x_3 - 4x_4$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \in V \Leftrightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} x_2 - 2x_3 - 4x_4 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} =$$

$$= x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -4 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\Rightarrow A = \begin{bmatrix} 1 & -2 & -4 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

#33. A subspace  $V$  of  $\mathbb{R}^n$  is called a hyperplane if  $V$  is defined by a homogeneous equation

$$c_1x_1 + c_2x_2 + \dots + c_nx_n = 0$$

where at least one of the coefficients  $c_i$  is nonzero. What is the dimension of a hyperplane in  $\mathbb{R}^n$ ? What is a hyperplane in  $\mathbb{R}^3$  and what in  $\mathbb{R}^2$ ?

Solution:

$$c_1x_1 + c_2x_2 + \dots + c_nx_n = 0 \text{ and } c_i \neq 0$$

$$c_i x_i = -c_1 x_1 - \dots - c_{i-1} x_{i-1} - c_{i+1} x_{i+1} - \dots - c_n x_n$$

$$x_i = -\frac{c_1}{c_i} x_1 - \dots - \frac{c_{i-1}}{c_i} x_{i-1} - \frac{c_{i+1}}{c_i} x_{i+1} - \dots - \frac{c_n}{c_i} x_n$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} \in V \Leftrightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_i \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ -\frac{c_1}{c_i} x_1 - \dots - \frac{c_n}{c_i} x_n \\ \vdots \\ x_n \end{bmatrix} =$$

$$= x_1 \begin{bmatrix} 1 \\ 0 \\ -c_1/c_i \\ \vdots \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ -c_2/c_i \\ \vdots \\ 0 \end{bmatrix} + \dots + x_{i-1} \begin{bmatrix} 0 \\ 0 \\ -c_{i-1}/c_i \\ \vdots \\ 0 \end{bmatrix} + x_{i+1} \begin{bmatrix} 0 \\ 0 \\ -c_{i+1}/c_i \\ \vdots \\ 0 \end{bmatrix} + \dots + x_n \begin{bmatrix} 0 \\ 0 \\ -c_n/c_i \\ \vdots \\ 1 \end{bmatrix}$$

$\vec{a}_1 \quad \vec{a}_2 \quad \dots \quad \vec{a}_{i-1} \quad \vec{a}_{i+1} \quad \dots \quad \vec{a}_n$

All these vectors  $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_{i-1}, \vec{a}_{i+1}, \dots, \vec{a}_n$  are lin. independent, they span  $V$  and there are  $n-1$  of them

$$\Rightarrow \dim V = n-1$$

Hyperplanes in  $\mathbb{R}^3$  are all planes through the origin.  
Hyperplanes in  $\mathbb{R}^2$  are all lines through the origin.

- #38. a) Consider a lin. transf.  $T: \mathbb{R}^5 \rightarrow \mathbb{R}^3$ . What are the possible values of  $\dim(\ker T)$   
b) Consider a lin. transf.  $T: \mathbb{R}^4 \rightarrow \mathbb{R}^7$ . What are the possible values of  $\dim(\text{Im } T)$ ?

Solution:

we know: If  $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$  is a lin. transf. then

$$\dim(\ker T) + \dim(\text{Im } T) = m$$

$$\begin{cases} \ker T \subseteq \mathbb{R}^m \\ \text{Im } T \subseteq \mathbb{R}^n \end{cases}$$

$$\begin{cases} \text{a) } \dim(\ker T) + \dim(\text{Im } T) = 5 \\ \ker T \subseteq \mathbb{R}^5 \Rightarrow 0 \leq \dim(\ker T) \leq 5 \\ \text{Im } T \subseteq \mathbb{R}^3 \Rightarrow 0 \leq \dim(\text{Im } T) \leq 3 \end{cases} \Rightarrow$$

$$\Rightarrow 5 = \dim \ker T + \dim \text{Im } T \leq \dim \ker T + 3 \Rightarrow$$

$$\Rightarrow \dim \ker T \geq 2.$$

$$\begin{cases} \text{b) } \dim(\ker T) + \dim(\text{Im } T) = 4 \\ \ker T \subseteq \mathbb{R}^4 \Rightarrow 0 \leq \dim \ker T \leq 4 \end{cases} \Rightarrow$$

$$\Rightarrow 4 = \dim \ker T + \dim \text{Im } T \geq 0 + \dim \text{Im } T \Rightarrow$$

$$\dim \text{Im } T \leq 4$$

$$4 = \dim \ker T + \dim \text{Im } T \leq 4 + \dim \text{Im } T \Rightarrow \dim \text{Im } T \geq 0$$

$$\Rightarrow 0 \leq \dim \text{Im } T \leq 4.$$



#47: Consider two subspaces  $V, W$  of  $\mathbb{R}^n$ . Show that  
 $\dim(V) + \dim(W) = \dim(V+W) + \dim(V \cap W)$ .

Solution:

$V \cap W$  is a subspace, so let  $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k$  be its basis.  
Since  $\vec{u}_1, \dots, \vec{u}_k$  are lin. independent vectors in  $V$  we can find  
vectors  $\vec{v}_1, \dots, \vec{v}_\ell$  st  $\{\vec{u}_1, \dots, \vec{u}_k, \vec{v}_1, \dots, \vec{v}_\ell\}$  is a basis for  $V$ .

Similarly, we can find  $\vec{w}_1, \dots, \vec{w}_r$  st  $\{\vec{u}_1, \dots, \vec{u}_k, \vec{w}_1, \dots, \vec{w}_r\}$  is a  
basis for  $W$ .

We would then have

$$\begin{aligned} \dim(V \cap W) &= k \\ \dim V &= k + \ell \\ \dim W &= k + r \end{aligned}$$

If we show that  $\{\vec{u}_1, \dots, \vec{u}_k, \vec{v}_1, \dots, \vec{v}_\ell, \vec{w}_1, \dots, \vec{w}_r\}$  is a basis for  $V+W$   
then  $\dim(V+W) = k + \ell + r$ , and we would have

$$\begin{aligned} \dim V + \dim W &= k + \ell + k + r = k + (\ell + k + r) = \\ &= \dim(V \cap W) + \dim(V+W). \end{aligned}$$

So we need to show that  $\{\vec{u}_1, \dots, \vec{u}_k, \vec{v}_1, \dots, \vec{v}_\ell, \vec{w}_1, \dots, \vec{w}_r\}$  is a basis  
for  $V+W$ , i.e. that this set of vectors span  $V+W$  and the vectors  
are lin. independent.

1) span. Let  $\vec{x} \in V+W$ . Then  $\vec{x} = \vec{v} + \vec{w}$  for some  $\vec{v} \in V, \vec{w} \in W$ .

$$\vec{v} \in V \Rightarrow \vec{v} = a_1 \vec{u}_1 + \dots + a_k \vec{u}_k + a_{k+1} \vec{v}_1 + \dots + a_{k+\ell} \vec{v}_\ell, \text{ for some } a_i$$

$$\vec{w} \in W \Rightarrow \vec{w} = b_1 \vec{u}_1 + \dots + b_k \vec{u}_k + b_{k+1} \vec{w}_1 + \dots + b_{k+r} \vec{w}_r, \text{ for some } b_i$$

$$\begin{aligned} \Rightarrow \vec{x} &= a_1 \vec{u}_1 + \dots + a_k \vec{u}_k + a_{k+1} \vec{v}_1 + \dots + a_{k+\ell} \vec{v}_\ell + b_1 \vec{u}_1 + \dots + b_{k+r} \vec{w}_r = \\ &= (a_1 + b_1) \vec{u}_1 + \dots + (a_k + b_k) \vec{u}_k + a_{k+1} \vec{v}_1 + \dots + a_{k+\ell} \vec{v}_\ell + b_{k+1} \vec{w}_1 + \dots + b_{k+r} \vec{w}_r \end{aligned}$$

$$\Rightarrow \vec{u}_1, \dots, \vec{u}_k, \vec{v}_1, \dots, \vec{v}_\ell, \vec{w}_1, \dots, \vec{w}_r \text{ span } V+W$$

2) lin. independence: Suppose

$$a_1 \vec{u}_1 + \dots + a_k \vec{u}_k + b_1 \vec{v}_1 + \dots + b_\ell \vec{v}_\ell + c_1 \vec{w}_1 + \dots + c_r \vec{w}_r = \vec{0} \quad (*)$$

$$\Rightarrow \underbrace{a_1 \vec{u}_1 + \dots + a_k \vec{u}_k + b_1 \vec{v}_1 + \dots + b_\ell \vec{v}_\ell}_{\in V} = \underbrace{-c_1 \vec{w}_1 - \dots - c_r \vec{w}_r}_{\in W}$$

So, we have a vector that lies both in  $V$  &  $W$ , i.e. it lies in  $V \cap W$

||

$$a_1 \vec{u}_1 + \dots + a_k \vec{u}_k + b_1 \vec{v}_1 + \dots + b_\ell \vec{v}_\ell \in V \cap W$$

Since  $\{\vec{u}_1, \dots, \vec{u}_k\}$  is a basis for  $V \cap W$ , this vector's representation in terms of the basis is unique, which implies that

$$b_1 = b_2 = \dots = b_\ell = 0$$

Putting this into equation (\*) we get

$$a_1 \vec{u}_1 + \dots + a_k \vec{u}_k + c_1 \vec{w}_1 + \dots + c_r \vec{w}_r = \vec{0}$$

but  $\{\vec{u}_1, \dots, \vec{u}_k, \vec{w}_1, \dots, \vec{w}_r\}$  is a basis for  $W$ , hence

$$a_1 = \dots = a_k = c_1 = \dots = c_r = 0$$