Design projects

M 5740 Math Modeling Fall 2017

November 29, 2017

1 Transformer of vibrations

A simple model of a device (a metamaterial) that transforms the external periodic force $F_e = A \cos(\omega t)$ into electricity is shown in the Figure. It consists of the external massless and rigid plates (two rods), the inclined massless rigid joints that transform vertical vibrations into a horizontal motion x(t) of the central rigid rod with the mass m, a spring with constant $C (F_{spring} = -Cx)$, and the dissipative element (or an electrical generator) with resistance force F is $F = -\gamma \dot{x}(t)$.

Model the motion of the rod. Derive the differential equation for x and solve it. Find optimal value of m and angle α that maximize the average dissipated energy

$$D = \frac{\omega}{2\pi} \int_0^{\frac{2\pi}{\omega}} \dot{x}^2(t) \, dt$$

2 Metamaterials: Negative Poisson's ratio materials

Investigate the mode of deformation of the two structures and compute their Poisson ratio ν in dependence of the angle θ .

http://silver.neep.wisc.edu/ lakes/Poisson.html

http://en.wikipedia.org/wiki/Auxetics

Find other models of Auxetics and discuss their common properties.

Suggest a 3d model of auxetic material. What are natural boundaries for the Poisson ratio?

A natural continuation of the auxetics:

Theory

GW.Milton and A.Cherkaev. Which Elasticity Tensors are Realizable? J. Eng. Mater. Technol 117(4), 483-493 (Oct 01, 1995) Realization

M.Kadic, T.Bckmann, N.Stenger, M.Thiel, M.Wegener. On the feasibility of pentamode mechanical metamaterials. https://arxiv.org/abs/1203.1481