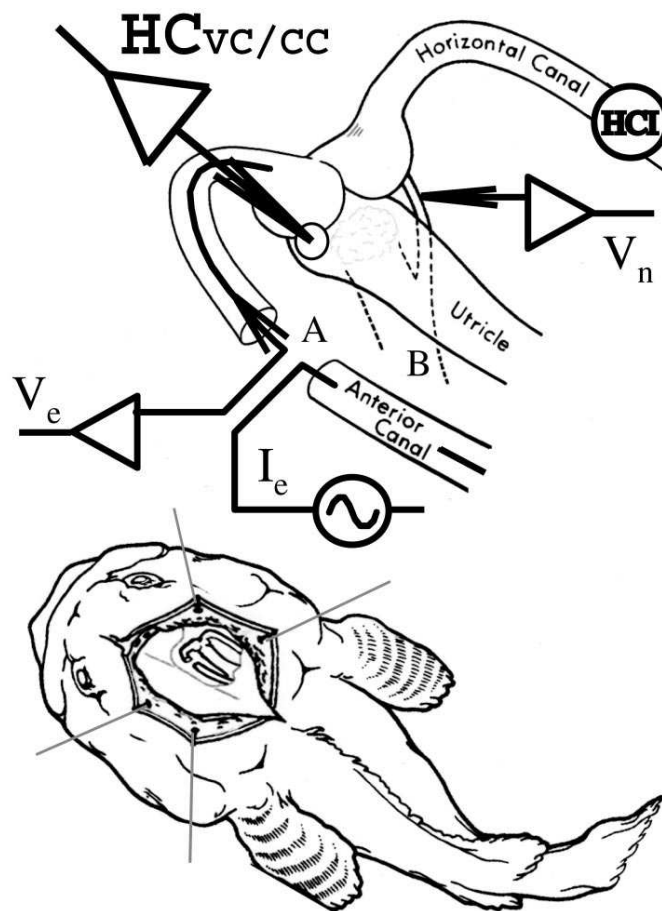


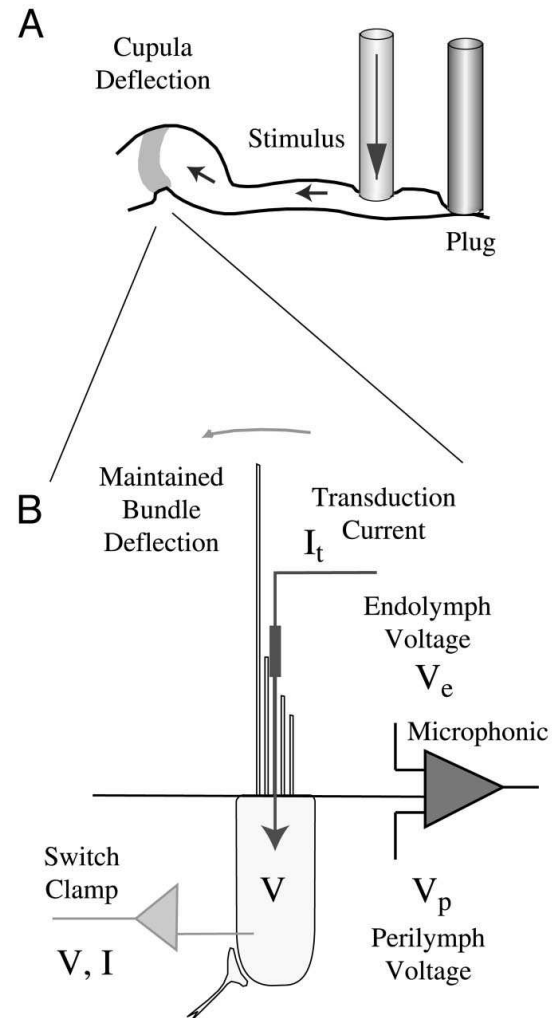


Lab Rotation Presentation

Ben Murphy

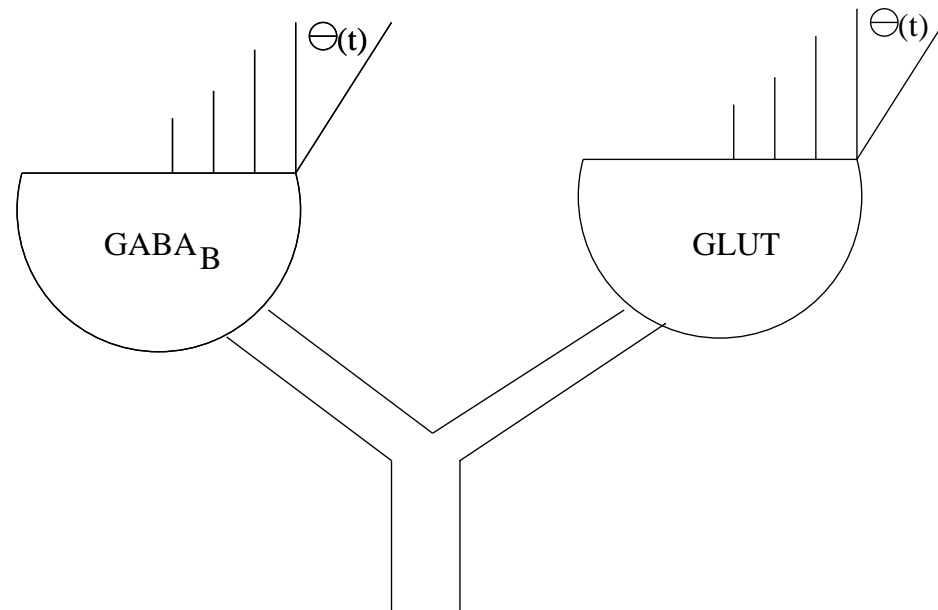


Experimental setup



Temporal encoding

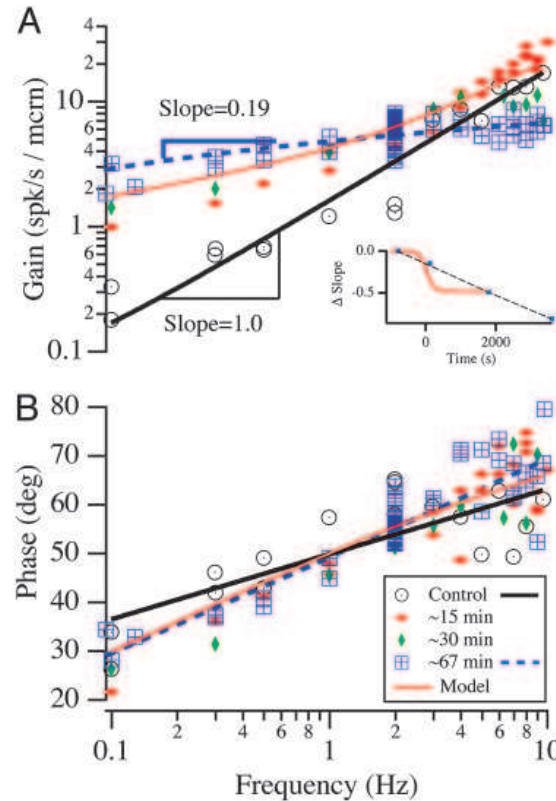
- Low frequency: Fluid displacement $D(t) \propto \ddot{\theta}(t)$
- High frequency: Real time integration via viscous forces in each canal causes $D(t) \propto \dot{\theta}(t)$
- Reflecting this there is a subset of afferents that report $\ddot{\theta}(t)$ for low f and $\dot{\theta}(t)$ for high f
- **However** a substantial number of afferents report $\ddot{\theta}(t)$ or a signal between $\ddot{\theta}(t)$ and $\dot{\theta}(t)$ even for frequencies where $D(t) \propto \dot{\theta}(t)$



- Transfer function:

$$\begin{aligned} Re^{i\omega t} &= T_E e^{i\omega t} - T_I e^{i\omega(t-\delta)} \\ &\approx T_E e^{i\omega t} (1 - ce^{-i\omega\delta}) \end{aligned}$$

Is R a Fractional Derivative?



$$R \equiv f(t) - cf(t - \tau) = bD^\alpha f \quad \text{for } c, \tau, b, \alpha \neq 0?$$

$$\text{Where } \widehat{D^\alpha f(t)} = (is)^\alpha \hat{f}(s)$$

$$D^{-\alpha} f(t) = \frac{1}{\Gamma(\alpha)} \int_l^t (t-s)^{\alpha-1} f(s) ds$$

$$D^{\alpha} f(t) = D^m D^{-(m-\alpha)} f(t)$$

$$\begin{aligned} (is)^{\alpha} \hat{f}(s) &= \widehat{D^{\alpha} f(t)} = (\widehat{f(t) - cf(t-\tau)}) \\ &= (1 - ce^{is\tau}) \hat{f}(s) \end{aligned}$$

Therefore

$$\forall s \neq 0 \text{ s.t. } \hat{f}(s) \neq 0, \infty$$
$$1 - ce^{is\tau} = b(is)^\alpha$$

Taylor expanding about $a \neq 0$ gives:

$$b(ia)^\alpha = 1 - ce^{(ia\tau)} \quad O(1) \quad (1)$$

$$\alpha b(ia)^\alpha = -iac\tau e^{(ia\tau)} \quad O(s - a) \quad (2)$$

$$\alpha(\alpha - 1)b(ia)^\alpha = a^2 c\tau^2 e^{(ia\tau)} \quad O((s - a)^2) \quad (3)$$

(2) and (3) \Rightarrow

$$ba^{\alpha-2}\alpha(\alpha-1)/c\tau^2 = \cos(a\tau + \alpha\pi/2) = 0$$

$$\alpha ba^{\alpha-1}/c = \sin(a\tau + \alpha\pi/2) = 0$$

$\Rightarrow \Leftarrow$

as all parameters are assumed nonzero and $\alpha \neq 1$.
Therefore R is not a fractional derivative.