Introduction to Linear Algebra 2270-1 Sample Final Exam Fall 2007

Instructions. The time allowed is 120 minutes. The examination consists of five problems, one for each of chapters 3, 4, 5, 6, 7, each problem with multiple parts. A chapter represents 25 minutes on the final exam. Each problem represents several textbook problems numbered (a), (b), (c), \cdots . Please solve enough parts to make 100% on each chapter. Choose the problems to be graded by check-mark X; the credits should add to 100.

Calculators, books, notes and computers are not allowed.

Answer checks are not expected or required. First drafts are expected, not complete presentations. Please submit **exactly five** separately stapled packages of problems.

Keep this page for your records.

Ch3. (Subspaces of \mathcal{R}^n and Their Dimensions)

 $\begin{bmatrix} 30\% \end{bmatrix} \text{Ch3}(a): \text{Let } A = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 2 & 1 & 1 & 0 \\ 1 & 1 & 0 & -1 \end{bmatrix}. \text{ Find bases for the image and kernel of } A.$ $\begin{bmatrix} 40\% \end{bmatrix} \text{Ch3}(b): \text{ Let } \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3 \text{ the columns of the matrix } A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}. \text{ Define } T(\mathbf{x}) = A\mathbf{x}.$ Find the matrix of T relative to the basis $\mathbf{v}_1 + \mathbf{v}_2, \mathbf{v}_2 + \mathbf{v}_3, \mathbf{v}_3 + \mathbf{v}_1.$ $\begin{bmatrix} 30\% \end{bmatrix} \text{Ch3}(d): \text{ Let } V \text{ be the vector space of all functions } f(x) \text{ defined on } 0 \le x \le 1. \text{ Let } S \text{ be the subset of } V \text{ defined by } f(1) = f(0) + \int_0^1 x f(x) dx, f(0.5) = 0. \text{ Prove that } S \text{ is a subspace of } V.$

[40% or 30%] Ch3(d): Let V be the vector space of all data packages $\mathbf{v} = \begin{pmatrix} f \\ x_0 \\ y_0 \end{pmatrix}$, where f is a

continuous function defined on $0 \le x \le 1$ and x_0 , y_0 are real values. Define + and \cdot componentwise. Let S be the subset of V defined by f(0) = f(1), $2x_0 + y_0 = 0$. Prove that S is a subspace of V.

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Ch4. (Linear Spaces)

$$\begin{bmatrix} 30\% \end{bmatrix} \text{Ch4(a): Let } \mathbf{x} = \begin{pmatrix} 1\\ 1\\ 0 \end{pmatrix}$$

Let W be the linear space of all 3×3 matrices. Let V be the set of all 3×3 matrices A such that **x** belongs to the image of A. Prove or disprove: V is a subspace of W.

[40%] Ch4(b): Let V be the linear space of all functions $f(x) = c_0 + c_1 x + c_2 x^2$. Define $T(f) = c_2 x^2$ from V to V. Find the image, kernel, rank and nullity of T.

[30%] Ch4(c): Let V be the linear space of all real 4×4 matrices M. Let T be defined on V by $T(\mathbf{M}) = \mathbf{N}$ where $\mathbf{N} = \mathbf{M}$ except for the last row, which is all zeros. Find the image and kernel of T.

 $\begin{bmatrix} [40\%] \text{ Ch4}(d): \text{ Let } A = \begin{pmatrix} 1 & 3 \\ 0 & -1 \end{pmatrix}, S = \begin{pmatrix} 1 & -2 \\ 0 & 2 \end{pmatrix} \text{ and } D = \text{diag}(1, -1). \text{ Then } AS = SD.$

Define V to be the linear space of all 2×2 matrices R satisfying AR = RD. Find a basis for V.

Ch5. (Orthogonality and Least Squares)

[30%] Ch5(a): Find the orthogonal projection of **v** onto V =**span**(**v**₁, **v**₂), given

$$\mathbf{v} = \begin{pmatrix} 9\\0\\0\\0 \end{pmatrix}, \quad \mathbf{v}_1 = \begin{pmatrix} 0\\4\\-1\\0 \end{pmatrix}, \quad \mathbf{v}_2 = \begin{pmatrix} 0\\4\\1\\0 \end{pmatrix}.$$

[10%] Ch5(b): Let A be 4 × 5. Prove or give a counterexample: dim $(\operatorname{im}(A)^{\perp}) = \operatorname{dim}(\operatorname{ker}(A^T))$. [10%] Ch5(c): Let A be $n \times m$. Prove or give a counterexample: $\operatorname{ker}(A) = \operatorname{ker}(AA^T)$.

[30%] Ch5(d): Consider the linear space V of polynomials $f(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3$ on $0 \le t \le 1$ with inner product

$$\langle f,g \rangle = \int_0^1 f(t)g(t)dt.$$

Find a basis for the subspace S of all f in V orthogonal to both t and 1 + t.

[30%] Ch5(e): Find the Gram-Schmidt orthonormal vectors \mathbf{w}_1 , \mathbf{w}_2 , \mathbf{w}_3 for the following independent set:

$$\mathbf{v}_{1} = \begin{pmatrix} 1\\ 1\\ 0\\ 0 \end{pmatrix}, \quad \mathbf{v}_{2} = \begin{pmatrix} 0\\ -1\\ 0\\ 1 \end{pmatrix}, \quad \mathbf{v}_{3} = \begin{pmatrix} 1\\ 0\\ 0\\ -1 \end{pmatrix}.$$
[30%] Ch5(f): Find the *QR*-factorization of $A = \begin{pmatrix} 4 & 10 & 0\\ 0 & 0 & -1\\ 3 & -10 & 0 \end{pmatrix}.$

[30%] Ch5(g): Derive the normal equation in the theory of least squares.

[30%] Ch5(h): State and prove the Near Point Theorem.

Please start your solutions on this page. Staple on additional pages.

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Ch6. (Determinants)

[50%] Ch6(a): Let B be the invertible matrix given below, where ? means the value of the entry does not affect the answer to this problem. The second matrix C is the adjugate (or adjoint) of B. Find the value of $\det(2B^{-1}(B^T)^{-2})$.

$$B = \begin{pmatrix} ? & ? & ? & 0\\ 0 & -1 & 2 & 0\\ 1 & 1 & 0 & 0\\ ? & ? & ? & 3 \end{pmatrix}, \quad C = \begin{pmatrix} 6 & 6 & 12 & 0\\ -6 & -6 & 6 & 0\\ -3 & 6 & 3 & 0\\ 2 & 2 & 4 & -6 \end{pmatrix}$$

[25%] Ch6(b): Assume $A = \operatorname{aug}(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$ is 3×3 and $B = \operatorname{aug}(\mathbf{v}_1 + \mathbf{v}_3, \mathbf{v}_3 - \mathbf{v}_2, 2\mathbf{v}_2 - \mathbf{v}_3)$. Suppose $det(A + B) + (det(A))^2 = 0$. Find all possible values of det(A).

[25%] Ch6(c): Assume given 3×3 matrices A, B. Suppose $E_5 E_4 B = E_3 E_2 E_1 A$ and E_1, E_2, E_3 , E_4, E_5 are elementary matrices representing respectively a combination, a multiply by 3, a swap and a multiply by 7. Assume det(A) = 5. Find $det(5A^2B)$.

[25%] Ch6(d): Find the area of the parallelogram formed by \mathbf{v}_1 , \mathbf{v}_2 , given

$$\mathbf{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \mathbf{v}_2 = \begin{pmatrix} -1 \\ 2 \end{pmatrix}.$$

[25%] Ch6(e): Evaluate det(A) by any hybrid method.

$$A = \begin{pmatrix} 1 & 1 & 2 & 0 \\ -1 & -1 & 1 & 0 \\ -1 & 2 & 1 & 0 \\ 1 & 1 & 2 & -3 \end{pmatrix}$$

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Ch7. (Eigenvalues and Eigenvectors)

[30%] Ch7(a): Find the eigenvalues of the matrix $A = \begin{pmatrix} 4 & -2 & 1 & 12 \\ 2 & 4 & -3 & 15 \\ 0 & 0 & 3 & 7 \\ 0 & 0 & -1 & -5 \end{pmatrix}$. To save time, **do**

not find eigenvectors!

 $\begin{bmatrix} 30\% \end{bmatrix} \text{Ch7(b): Given } A = \begin{pmatrix} 1 & 1 & -1 \\ 0 & 3 & 1 \\ 0 & 1 & 3 \end{pmatrix}, \text{ assume there exists an invertible matrix } P \text{ and a diagonal matrix } D \text{ such that } AP = PD. \text{ Circle all possible columns of } P \text{ from the list below.}$

$$\left(\begin{array}{c}2\\1\\1\end{array}\right),\quad \left(\begin{array}{c}1\\0\\0\end{array}\right),\quad \left(\begin{array}{c}0\\-1\\-1\end{array}\right).$$

[40%] Ch7(c): Consider the 3×3 matrix

$$A = \left(\begin{array}{rrr} 4 & 2 & -2 \\ 0 & 3 & 1 \\ 0 & 1 & 3 \end{array}\right).$$

Already computed are eigenpairs

$$\left(2, \left(\begin{array}{c}2\\-1\\1\end{array}\right)\right), \quad \left(4, \left(\begin{array}{c}1\\0\\0\end{array}\right)\right).$$

- (1) [25%] Find the remaining eigenpairs of A.
- (2) [5%] Display an invertible matrix P and a diagonal matrix D such that AP = PD.

(3) [10%] Display explicitly Fourier's model for A.

[40%] Ch7(d): Consider a discrete dynamical system $\mathbf{x}(n+1) = A\mathbf{x}(n)$. Given A and $\mathbf{x}(0)$ below, find exact formulas for the vectors $\mathbf{x}(n)$ and $\lim_{n\to\infty} \mathbf{x}(n)$.

$$A = \frac{1}{10} \begin{pmatrix} 7 & 1 \\ -2 & 10 \end{pmatrix}, \quad \mathbf{x}(0) = \begin{pmatrix} 40 \\ 50 \end{pmatrix}.$$