

Chapter IX: Invariant Sets

Let $D \subset \mathbf{R}^N$ be open and connected and let $f : D \rightarrow \mathbf{R}^N$ be locally Lipschitz continuous.

Consider the initial value problem $u' = f(u)$, $u(0) = u_0 \in D$.

Definition. An **invariant subset** $M \subset D$ is defined by the property that the solution $u(t)$ stays in M whenever $u_0 \in M$, for all $t \in I_{u_0}$, the maximal t -interval of existence.

Examples of invariant sets.

1. An equilibrium point, $f(u_0) = 0$.
2. A periodic solution, $u(0) = u(T)$.

Definition. The **flow determined by f** is the mapping $u : I_{u_0} \times D \rightarrow D$ defined by $(t, u_0) \mapsto u(t, u_0)$. The set $U = \cup_{v \in D} I_v \times \{v\}$, which is a subset of $\mathbf{R} \times \mathbf{R}^N$, is the **natural domain**.

Lemma 1. The flow determined by f has the following properties:

1. The flow $u : U \mapsto D$ is continuous.
2. $u(0, u_0) = u_0$ for all $u_0 \in D$.
3. If $u_0 \in D$, $s \in I_{u_0}$ and $t \in I_{u(s, u_0)}$, then $s + t \in I_{u_0}$ and $u(s + t, u_0) = u(t, u(s, u_0))$.

Definition. A mapping having the three properties of the lemma is called a **flow** on D . A flow may be defined without the underlying differential equation.

Orbits and Flows

If u is a flow for f and S is a subset of $I_{u_0} = (t_{u_0}^-, t_{u_0}^+)$, then $u(S, u_0)$ is the set

$$\{u(t, u_0) : t \in S\}.$$

Given $v \in U$, denote by

$\gamma(v) = u(I_v, v)$ the **orbit**,

$\gamma^+(v) = u([0, t_v^+), v)$ the **positive semiorbit**,

$\gamma^-(v) = u((t_v^-, 0], v)$ the **negative semiorbit**.

Definition. Call $v \in D$ satisfying $f(v) = 0$ a **stationary point** or **critical point** of the flow.

Lemma. If $v \in D$ is a stationary point of the flow u , then $I_v = \mathbf{R}$ and $\gamma(v) = \gamma^+(v) = \gamma^-(v) = \{v\}$.

Definition. Call $v \in D$ satisfying $u(0, v) = u(T, v)$ for some $T > 0$ a **periodic point** of period T of the flow. If in addition, $u(0, v) \neq u(t, v)$, $0 < t < T$, then T is called the **minimal period**.

Proposition 2. Let u be the flow determined by f and let $v \in D$. Then either:

1. v is a stationary point, or
2. v is a periodic point having a minimal positive period, or
3. the flow $u(\cdot, v)$ is injective.

If $\gamma^+(v)$ is relatively compact, then $t^+(v) = +\infty$. If $\gamma^-(v)$ is relatively compact, then $t^-(v) = -\infty$. If $\gamma(v)$ is relatively compact, then $I_v = \mathbf{R}$.

Proof.

The three options are mutually exclusive: a constant solution has no minimal period and an injective map cannot satisfy $u(t_1, v) = u(t_2, v)$ for $t_1 \neq t_2$. The first part of the proof assumes 1 and 2 do not hold and then 3 is proved.

The formulas for $t^-(v)$, $t^+(v)$ result from application of the extension theory for solutions of $u' = f(u)$. For example, if u remains bounded for $t \geq 0$, then the theory implies that the trajectory $(t, u(t))$ reaches the boundary at $t = \infty$.

Definition. A subset $M \subset D$ is **positively invariant** with respect to the the flow u determined by f whenever $\gamma^+(v) \subset M$, for all $v \in M$. A subset $M \subset D$ is **negatively invariant** provided $\gamma^-(v) \subset M$, for all $v \in M$. A subset $M \subset D$ is **invariant** provided it is both positively and negatively invariant.

Proposition 3. Let u be the flow determined by f and let $V \subset D$. Then there exists a smallest positively invariant subset M , $V \subset M \subset D$, and there exists a largest invariant set \tilde{M} , $\tilde{M} \subset V$. Also there exists a largest negatively invariant subset M , $V \supset M$, and there exists a smallest invariant set \tilde{M} , $\tilde{M} \supset V$. As a consequence V , contains a largest invariant subset and it is contained in a smallest invariant set.

Corollary 4.

(i) If a set M is positively invariant with respect to the flow u , then so are \overline{M} and $\text{int}(M)$.

(ii) A closed set M is positively invariant with respect to the flow u if and only if for every $v \in \partial M$ there exists $\epsilon > 0$ such that $u([0, \epsilon), v) \subset M$.

(iii) A set M is positively invariant if and only if $\text{comp}(M)$, the complement of M , is negatively invariant.

(iv) If a set M is invariant, then so is ∂M . If ∂M is invariant, then so are \overline{M} , $\mathbf{R} \setminus M$, and $\text{int}(M)$.

Theorem 5. Let $M \subset D$ be a closed set. Then M is positively invariant with respect to the flow u determined by f if and only if for every $v \in M$

$$\liminf_{t \rightarrow 0^+} \frac{\text{dist}(v + tf(v), M)}{t} = 0.$$

Proof of Theorem 5. Taylor's expansion $u(t, v) = v + tf(v) + o(t)$ proves the necessity. To prove sufficiency, assume the identity holds and define $w(t) = \text{dist}(u(t, v), M) = |u(t, v) - v_t|$, where $v_t \in M$ and $\lim_{t \rightarrow 0^+} v_t = v$. Using a Lipschitz constant L for f it follows that

$$w(t + s) \leq w(t) + sLw(t) + \text{dist}(v_t + tf(v_t), M),$$

hence $D_+w(t) \leq Lw(t)$. This implies $w(t) = 0$ near $t = 0$, completing the proof.

Theorem 6. Consider $\phi \in C^1(D, R)$ with $\nabla\phi(v) \neq 0$ when $\phi(v) = 0$. Let $M = \phi^{-1}(-\infty, 0]$. Then M is positively invariant with respect to the flow determined by f if and only if $\nabla\phi(v) \cdot f(v) \leq 0$ for all $v \in \partial M = \phi^{-1}(0)$.

Limit Sets

Definition. The **positive limit set** of v is the set $\Gamma^+(v)$ of all limits $w = \lim_{n \rightarrow \infty} u(t_n, v)$ where $\{t_n\}$ is a sequence with limit t_v^+ . The **negative limit set** of v is the set $\Gamma^-(v)$ of all limits $w = \lim_{n \rightarrow \infty} u(t_n, v)$ where $\{t_n\}$ is a sequence with limit t_v^- . If t_v^+ is finite, then $\Gamma^+(v) \subset \partial D$. If t_v^- is finite, then $\Gamma^-(v) \subset \partial D$.

Proposition 7.

- (i) $\overline{\gamma^+(v)} = \gamma^+(v) \cup \Gamma^+(v)$.
- (ii) $\Gamma^+(v) = \bigcap_{w \in \gamma^+(v)} \overline{\gamma^+(w)}$.
- (iii) If $\gamma^+(v)$ is bounded, then $\Gamma^+(v) \neq \emptyset$ and compact.
- (iv) If $\Gamma^+(v) \neq \emptyset$ and bounded, then $\lim_{t \rightarrow t_v^+} \text{dist}(u(t, v), \Gamma^+(v)) = 0$.
- (v) $\Gamma^+(v) \cap D$ is an invariant set.

Proof of proposition 7–(v). To show that $\Gamma^+(v) \cap D$ is an invariant set, it will be shown that solutions through points of $\Gamma^+(v)$ are defined for all time and their orbit remains in $\Gamma^+(v)$.

Let $w \in \Gamma^+(v) \cap D$. Then there exists a sequence $\{t_n\}_{n=1}^{\infty}$, $t_n \rightarrow \infty$, such that $u(t_n, v) \rightarrow w$. For each $n \geq 1$, the function $u_n(t) = u(t + t_n, v)$ is the unique solution of $u' = f(u)$, $u(0) = u(t_n, v)$, and hence the maximal interval of existence of u_n will contain the interval $[-t_n, \infty)$. Since $u(t_n, v) \rightarrow w$, there will exist a subsequence of $\{u_n(t)\}$, which we relabel as $\{u_n(t)\}$ converging to the solution, call it y , of $u' = f(u)$, $u(0) = w$. We note that given any compact interval $[a, b]$ the sequence $\{u_n(t)\}$ will be defined on $[a, b]$ for n sufficiently large and hence y will be defined on $[a, b]$. Since this interval is arbitrary it follows that y is defined on $(-\infty, \infty)$. Furthermore for any t_0

$$y(t_0) = \lim_{n \rightarrow \infty} u_n(t_0) = \lim_{n \rightarrow \infty} u(t_0 + t_n, v),$$

and hence $y(t_0) \in \Gamma^+(v)$.

Theorem 8. If $\gamma^+(v)$ is contained in a compact subset $K \subset D$, then $\Gamma^+(v) \neq \emptyset$ is a compact connected set, i.e., a continuum.

Proof. Proposition 7 implies $\Gamma^+(v)$ is compact. To be shown is connectedness. Suppose it is not. Then there exist nonempty disjoint compact sets M and N such that $\Gamma^+(v) = M \cup N$. Let $\delta = \inf\{|v - w| : v \in M, w \in N\} > 0$. Since $M \subset \Gamma^+(v)$ and $N \subset \Gamma^+(v)$, there exist values of t arbitrarily large such that $\text{dist}(u(t, v), M) < \frac{\delta}{2}$ and values of t arbitrarily large such that $\text{dist}(u(t, v), N) < \frac{\delta}{2}$ and hence there exists a sequence $\{t_n \rightarrow \infty\}$ such that $\text{dist}(u(t_n, v), M) = \frac{\delta}{2}$. The sequence $\{u(t_n, v)\}$ must have a convergent subsequence and hence has a limit point which is in neither M nor N , a contradiction.

LaSalle's Theorem

Let $\phi : D \rightarrow \mathbf{R}$ be a C^1 function. The notation $\phi'(v) = \nabla\phi(v) \cdot f(v)$ will be used.

Lemma 9. Assume that $\nabla\phi(v) \cdot f(v) \leq 0$, for all $v \in D$. Then for all $v \in D$, ϕ is constant on the set $\Gamma^+(v) \cap D$.

Proof. The function $\phi(u(t, v))$ is nonincreasing in t and therefore there is an inequality $\phi(u(s_n, v)) \leq \phi(u(t_k, v))$ valid for each t_k when s_n is sufficiently large. This inequality implies that $\phi(w_2) \leq \phi(w_1)$ for $w_1, w_2 \in \Gamma^+(v) \cap D$. Therefore, swapping roles of w_1 and w_2 gives $\phi(w_1) \leq \phi(w_2)$, hence $\phi(w) = \text{constant}$.

Theorem 10. Let there exist a compact set $K \subset D$ such that $\nabla\phi(v) \cdot f(v) \leq 0$, for all $v \in K$. Let $\tilde{K} = \{v \in K : \phi'(v) = 0\}$ and let M be the largest invariant set contained in \tilde{K} . Then for all $v \in D$ such that $\gamma^+(v) \subset K$

$$\lim_{t \rightarrow \infty} \text{dist}(u(t, v), M) = 0.$$

Proof. Let $v \in D$ such that $\gamma^+(v) \subset K$, then, using the previous lemma, we have that ϕ is constant on $\Gamma^+(v)$, which is an invariant set and hence contained in M .

Theorem 11 (LaSalle's Theorem). Assume that $D = \mathbf{R}^N$ and let $\nabla\phi(x) \cdot f(x) \leq 0$, for all $x \in \mathbf{R}^N$. Furthermore suppose that ϕ is bounded below and that $\phi(x) \rightarrow \infty$ as $|x| \rightarrow \infty$. Let $E = \{v : \phi'(v) = 0\}$, then

$$\lim_{t \rightarrow \infty} \text{dist}(u(t, v), M) = 0,$$

for all $v \in \mathbf{R}^N$, where M is the largest invariant set contained in E .

Two Dimensional Systems

Definition. A point $v \in D$ is a **regular point** if it is not a critical point of f , that is, $f(v) \neq 0$. A compact straight line segment $\ell \subset D$ through v is a **transversal through** v , provided ℓ contains only regular points and if for all $w \in \ell$, $f(w)$ is not parallel to the direction of ℓ .

Lemma 12. Let $v \in D$ be a regular point of f . Then there exists a transversal ℓ containing v in its relative interior. An orbit associated with f which crosses ℓ must cross always in the same direction.

Lemma 13. Let v be an interior point of some transversal ℓ . Then for every $\epsilon > 0$ there exists a circular disc D_ϵ with center at v such that for every $w \in D_\epsilon$, $u(t, w)$ will cross ℓ in time t , $|t| < \epsilon$.

Proof of Lemma 12. Let v be a regular point of f . Choose a neighborhood V of v consisting of regular points only. Let $\eta \in \mathbf{R}^2$ be any direction not parallel to $f(v)$, i.e., $\eta \times f(v) \neq 0$, (here \times is the cross product in \mathbf{R}^3). We may restrict V further such that $\eta \times f(w) \neq 0$, for all $w \in V$, and is bounded away from 0 on V . We then may take ℓ to be the intersection of the straight line through v with direction η and \bar{V} . The proof is completed by observing that $\eta \times f(w) = (0, 0, |\eta||f(w)| \sin \theta)$, where θ is the angle between η and $f(w)$.

Proof of Lemma 13. Let $v \in \text{int}(\ell)$ and let $\ell = \{z : z = v + s\eta, s_0 \leq s \leq s_1\}$. Let B be a disc centered at v containing only regular points of f . Let $L(t, w) = au^1(t, w) + bu^2(t, w) + c$, where $u(t, w)$ is the solution with initial condition w and $au^1 + bu^2 + c = 0$ is the equation of the straight line containing ℓ . Then $L(0, v) = 0$, and $\frac{\partial L}{\partial t}(0, v) = (a, b) \cdot f(v) \neq 0$. We hence may apply the implicit function theorem to complete the proof.

Lemma 14. Let ℓ be a transversal and let $\Gamma = \{w = u(t, v) : a \leq t \leq b\}$ be a closed arc of an orbit u associated with f which has the property that $u(t_1, v) \neq u(t_2, v)$, $a \leq t_1 < t_2 \leq b$. Then if Γ intersects ℓ it does so at a finite number of points whose order on Γ is the same as the order on ℓ . If the orbit is periodic it intersects ℓ at most once.

The proof relies on the Jordan curve theorem:

Theorem (Jordan). If J is a curve in R^2 given by a continuous function $g : [0, 1] \rightarrow R^2$ such that $g(0) = g(1)$ and $g(t) \neq g(s)$ for $0 < t < s < 1$, then the complement of J is the union of a unbounded open connected set $\text{Ext}(J)$ and a bounded open connected set $\text{Int}(J)$ such that J is the boundary of each set.

Lemma 15. Let $\gamma^+(v)$ be a semiorbit which does not intersect itself and let $w \in \Gamma^+(v)$ be a regular point of f . Then any transversal containing w in its interior contains no other points of $\Gamma^+(v)$ in its interior.

Lemma 16. Let $\gamma^+(v)$ be a semiorbit which does not intersect itself and which is contained in a compact set $K \subset D$ and let all points in $\Gamma^+(v)$ be regular points of f . Then $\Gamma^+(v)$ contains a periodic orbit.

Proof. Let $w \in \Gamma^+(v)$. It follows from Proposition 7 that $\Gamma^+(v)$ is an invariant set and hence that $\gamma^+(w) \subset \Gamma^+(v)$, and thus also $\Gamma^+(w) \subset \Gamma^+(v)$. Let $z \in \Gamma^+(w)$, and let ℓ be a transversal containing z in its relative interior. It follows that the semiorbit $\gamma^+(w)$ must intersect ℓ and by the above for an infinite number of values of t . On the other hand, the previous lemma implies that all these points of intersection must be the same.

Theorem 17 (Poincaré–Bendixson). Let $\gamma^+(v)$ be a semiorbit which does not intersect itself and which is contained in a compact set $K \subset D$ and let all points in $\Gamma^+(v)$ be regular points of f . Then $\Gamma^+(v)$ is the orbit of a periodic solution u_T with smallest positive period T .

Proof. It follows from Lemma 16 that every point in $\Gamma^+(v)$ is a point on some periodic orbit of a minimal positive period. On the other hand, it also follows from earlier results that $\Gamma^+(v)$ is a compact connected set. Hence, if for some $w \in \Gamma^+(v)$, $\gamma(w) \neq \Gamma^+(v)$, then $\Gamma^+(v) \setminus \gamma(w)$ must be a relatively open set with $A = \overline{\Gamma^+(v) \setminus \gamma(w)} \cap \gamma(w) \neq \emptyset$. One now easily obtains a contradiction by examining transversals through points of A . One hence concludes that in fact under the hypotheses of Lemma 16, the limit set $\Gamma^+(v)$ is a periodic orbit.

Theorem 18. Let Γ be a periodic orbit of $u' = f(u)$ which together with its interior is contained in a compact set $K \subset D$. Then there exists at least one singular point of f in the interior of D .

Proof. Let $\Omega = \text{interior}\Gamma$. Then f is continuous on $\overline{\Omega}$ and does not vanish on $\Gamma = \partial\Omega$. Let us assume that f has no stationary points in Ω . Then for each $w \in \Omega$, $\Gamma^+(w)$ is a periodic orbit. We partially order the collection $\{\Gamma_\alpha\}_{\alpha \in I}$, where I is an index set, of all periodic orbits which are contained in $\overline{\Omega}$, by saying that

$$\Gamma_\alpha \leq \Gamma_\beta \Leftrightarrow \text{interior}\Gamma_\alpha \subset \text{interior}\Gamma_\beta.$$

One now employs the Hausdorff minimum principle together with LaSalle's Theorem to arrive at a contradiction.