

1. (ch4) Complete enough of the following to add to 100%.

(a) [100%] Let  $S$  be the vector space of all continuous functions defined on  $(-\infty, \infty)$ . Define  $V$  to be the set of all functions  $f(x)$  in  $S$  such that  $\int_0^1 f(x)xe^{-x}dx = 0$ . Prove that  $V$  is a subspace of  $S$ .

(b) [30%] Find a  $4 \times 5$  augmented matrix representing four equations for the constants  $a, b, c, d$  in the partial fractions decomposition for the fraction given below. To save time, **do not solve for  $a, b, c, d$** !

$$\frac{2x - 1}{(x - 2)^2(x^2 - 4x + 8)}$$

(b) [70%] Solve for the unknowns  $a, b, c, d$  in the system of equations below by augmented matrix RREF methods, showing all details.

$$\begin{array}{cccccc} a & + & b & - & 2c & + & 2d & = & 2 \\ & & + & b & + & 2c & + & & = & 0 \\ a & + & 2b & + & & + & 2d & = & 2 \\ a & + & 3b & + & 2c & + & 2d & = & 2 \end{array}$$

**Solution 1(a).** Use the subspace criterion: (a) Given  $f$  and  $g$  in  $V$ , write details to show  $f + g$  is in  $V$ ; (b) Given  $f$  in  $V$  and  $k$  constant, write details to show  $kf$  is in  $V$ . Let  $h(x) = xe^{-x}$ , which is a function in  $S$ . Details for (a): Given  $\int_0^1 f(x)h(x)dx = 0$  and  $\int_0^1 g(x)h(x)dx = 0$ , add the equations to obtain the equation  $\int_0^1 (f(x) + g(x))h(x)dx = 0$ . This finishes (a). Details for (b): Given  $\int_0^1 f(x)h(x)dx = 0$  and  $k$  constant, multiply the equation by  $k$  and re-arrange factors to obtain the new equation  $\int_0^1 (kf(x))h(x)dx = 0$ . This proves (b).

**Solution 1(b).** The decomposition might be

$$\frac{2x - 1}{(x - 2)^2(x^2 - 4x + 8)} = \frac{a}{x - 2} + \frac{b}{(x - 2)^2} + \frac{c(x - 2) + 2d}{x^2 - 4x + 8}$$

although there are other possibilities. Clear the fractions. Set  $x = 2$  to get one equation for the constants. Choose 3 other values for  $x$  to obtain three other equations. Display the system of equations.

**Solution 1(c).** The answer is  $\begin{pmatrix} 2 + 4t_1 - 2t_2 \\ -2t_1 \\ t_1 \\ t_2 \end{pmatrix} = \begin{pmatrix} \lambda \\ 0 \\ 0 \\ 0 \end{pmatrix} + t_1 \begin{pmatrix} 4 \\ -2 \\ 1 \\ 0 \end{pmatrix} + t_2 \begin{pmatrix} -2 \\ 0 \\ 0 \\ 1 \end{pmatrix}$ .

2. (ch5) Complete all parts.

(a) [30%] Given  $4x''(t) + 2x'(t) + x(t) = 0$ , which represents a damped spring-mass system with  $m = 4$ ,  $c = 2$ ,  $k = 1$ , **solve** the differential equation [20%] and **classify** the answer as over-damped, critically damped or under-damped [10%].

(b) [70%] Find by variation of parameters or undetermined coefficients the steady-state periodic solution for the equation  $x'' + 2x' + x = 5 \cos(2t)$ .

(a)  $4r^2 + 2r + 1 = 0$  char eq  
has roots  $-\frac{1}{4} \pm \frac{\sqrt{3}}{4}i$

[10%] under-damped

[20%] sol  $y = c_1 e^{-t/4} \cos(\sqrt{3}t/4) + c_2 e^{-t/4} \sin(\sqrt{3}t/4)$

(b)  $x = d_1 \cos 2t + d_2 \sin 2t$   
= corrected trial sol

$$-4d_1 \cos 2t - 4d_2 \sin 2t + 2(-2d_1 \sin 2t + 2d_2 \cos 2t) + d_1 \cos 2t + d_2 \sin 2t = 5 \cos(2t)$$

$$\begin{cases} -4d_1 + 4d_2 + d_1 = 5 \\ -4d_2 - 4d_1 + d_2 = 0 \end{cases} \Leftrightarrow \begin{pmatrix} -3 & 4 \\ -4 & -3 \end{pmatrix} \begin{pmatrix} d_1 \\ d_2 \end{pmatrix} = \begin{pmatrix} 5 \\ 0 \end{pmatrix}$$

Then  $\begin{pmatrix} d_1 \\ d_2 \end{pmatrix} = \begin{pmatrix} -3 & 4 \\ -4 & -3 \end{pmatrix}^{-1} \begin{pmatrix} 5 \\ 0 \end{pmatrix}$   
 $= \begin{pmatrix} -3 & 4 \\ 4 & -3 \end{pmatrix} \begin{pmatrix} 5 \\ 0 \end{pmatrix} \frac{1}{\Delta}$   
 $= \begin{pmatrix} -15/25 \\ 20/25 \end{pmatrix}$

$$\Delta = \begin{vmatrix} -3 & 4 \\ -4 & -3 \end{vmatrix} \\ = 9 + 16 \\ = 25$$

$$x = d_1 \cos 2t + d_2 \sin 2t$$

$$x_p = -\frac{3}{5} \cos 2t + \frac{4}{5} \sin 2t$$

3. (ch5) Complete all parts below.

(a) [75%] Determine for  $y'' - 4y''' = xe^{2x} + x^2(1+x) + 2\cos x$  the **corrected** trial solution for  $y_p$  according to the method of undetermined coefficients. To save time, **do not** evaluate the undetermined coefficients (that is, do undetermined coefficient steps **1** and **2**, but skip steps **3** and **4**)! Undocumented details will be considered guessing, which earns no credit.

(b) [10%] Using the *recipe* for second order constant-coefficient differential equations, write out a **basis** for the solution space of the equation  $y'' + 4y' - y = 0$ .

(c) [15%] Using the *recipe* for higher order constant-coefficient differential equations, write out the general solution when the characteristic equation is  $(r-1)^2(r^2-1)^2(r^2+4)^2 = 0$ .

$$\textcircled{a} \quad y = y_1 + y_2 + y_3$$

$$y_1 = (d_1 + d_2 x) e^{2x}$$

$$y_2 = d_3 + d_4 x + d_5 x^2 + d_6 x^3$$

$$y_3 = d_7 \cos x + d_8 \sin x$$

$$r^5 - 4r^3 = 0$$

$$r^3(r-2)(r+2) = 0$$

Fixup required for roots  $r=0$  (mult=3) and  $r=2$  (mult=1)

Multiply  $y_1$  by  $x$  and  $y_2$  by  $x^3$ .

$$y = x(d_1 + d_2 x) e^{2x} + x^3(d_3 + d_4 x + d_5 x^2 + d_6 x^3) + d_7 \cos x + d_8 \sin x$$

$$\textcircled{b} \quad r^2 + 4r - 1 = 0$$

$$r = \frac{-4 \pm \sqrt{16+4}}{2}$$

$$= -2 \pm \sqrt{5}$$

$$\text{Basis} = \left\{ e^{-2t + \sqrt{5}t}, e^{-2t - \sqrt{5}t} \right\}$$

$$\textcircled{c} \quad (r-1)^4(r+1)^2(r^2+4)^2 = 0$$

$$y = u_1 e^x + u_2 e^{-x} + u_3 \cos 2x + u_4 \sin 2x$$

$$u_1 = c_1 + c_2 x + c_3 x^2 + c_4 x^3$$

$$u_2 = c_5 + c_6 x$$

$$u_3 = c_7 + c_8 x$$

$$u_4 = c_9 + c_{10} x$$

4. (ch6) Complete all of the items below.

(a) [30%] Find the eigenvalues of the matrix  $A = \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & -3 \\ 0 & 0 & 3 & 1 \end{bmatrix}$ . To save time, **do not** find eigenvectors!

(b) [70%] Given  $A = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 5 & 1 \\ 0 & 1 & 5 \end{bmatrix}$ , then there exists an invertible matrix  $P$  and a diagonal matrix  $D$  such that  $AP = PD$ . Find one possible column of  $P$ .

$$\begin{aligned} \textcircled{a} \det(A - \lambda I) &= \begin{vmatrix} 1-\lambda & 1 & -1 & 0 \\ 0 & 1-\lambda & -2 & 1 \\ 0 & 0 & 1-\lambda & -3 \\ 0 & 0 & 3 & 1-\lambda \end{vmatrix} \\ &= (1-\lambda)^2 \begin{vmatrix} 1-\lambda & -3 \\ 3 & 1-\lambda \end{vmatrix} \\ &= (1-\lambda)^2 ((1-\lambda)^2 + 9) \end{aligned}$$

$$\boxed{\text{Eigenvalues} = 1, 1, 1 \pm 3i}$$

\textcircled{b}  $\lambda = 1$  is an eigenvalue. Find an eigenpair  $(\lambda, \vec{v})$ .

$$\begin{aligned} \left( \begin{array}{ccc|c} 0 & 1 & -1 & 0 \\ 0 & 4 & 1 & 0 \\ 0 & 1 & 4 & 0 \end{array} \right) &\xrightarrow{R_2 - 4R_1} \left( \begin{array}{ccc|c} 0 & 1 & -1 & 0 \\ 0 & 0 & -5 & 0 \\ 0 & 0 & 5 & 0 \end{array} \right) \\ &\xrightarrow{R_3 + R_2} \left( \begin{array}{ccc|c} 0 & 1 & -1 & 0 \\ 0 & 0 & -5 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \end{aligned}$$

$$\boxed{\vec{v} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}}$$

$$\begin{aligned} \text{also } &\left( 4, \begin{pmatrix} -2/3 \\ -1 \\ 1 \end{pmatrix} \right) \\ \text{and } &\left( 6, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right) \end{aligned}$$

5. (ch6) Complete all parts below.

Consider a given  $3 \times 3$  matrix  $A$  having three eigenpairs

$$6, \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}; \quad 4, \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}; \quad 1, \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix}.$$

(a) [50%] Display the general solution  $\mathbf{x}(t)$  of the system  $\mathbf{x}' = A\mathbf{x}$  in vector form.

(b) [20%] Write a matrix algebra formula for the matrix  $A$  of (a) above. To save time, do not evaluate anything.

(c) [30%] Describe precisely Fourier's simplification method for the equation  $\mathbf{y} = A\mathbf{x}$ , using the matrix  $A$  of (a) above.

$$\textcircled{a} \quad \vec{x}(t) = c_1 \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} e^{6t} + c_2 \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} e^{4t} + c_3 \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} e^t$$

$$\textcircled{b} \quad AP = PD \quad D = \begin{pmatrix} 6 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad P = \begin{pmatrix} 1 & -1 & 1 \\ 2 & 1 & -2 \\ 0 & 1 & 0 \end{pmatrix},$$

$$\boxed{A = PDP^{-1}}$$

$$\textcircled{c} \quad \vec{x} = x_1 \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} + x_3 \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix}$$

$$\begin{aligned} \Rightarrow \vec{y} &= A\vec{x} \\ &= 6x_1 \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} + 4x_2 \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} + x_3 \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} \end{aligned}$$