

Differential Equations and Linear Algebra 2250-1

Midterm Exam 3, Fall 2004

Calculators, books, notes and computers are not allowed. Answer checks are not expected or required. First drafts are expected, not complete presentations.

1. (ch4) (a) [50%] Let V be the set of all vectors $\mathbf{u} = \begin{pmatrix} x \\ y \end{pmatrix}$ such that $x = 4y$. Prove that V is a subspace of \mathbb{R}^2 .

(b) [50%] Find a 3×3 system of linear equations for the constants a, b, c in the partial fractions decomposition below. Solve for a, b, c by RREF methods.

$$\frac{x^2 + x - 1}{(x-1)^2(x+2)} = \frac{a}{x-1} + \frac{b}{(x-1)^2} + \frac{c}{x+2}$$

(a) proof: Let $A = \begin{pmatrix} 1 & -4 \\ 0 & 0 \end{pmatrix}$. Then $V = \{\vec{u} : A\vec{u} = \vec{0}\}$. By superposition, V is a subspace.

(b) $x^2 + x - 1 = a(x-1)(x+2) + b(x+2) + c(x-1)^2$

$$x=1: 1 = 0 + 3b + 0$$

$$x=-2: 1 = 0 + 0 + 9c$$

$$x=0: -1 = -2a + 2b + c$$

$$\left(\begin{array}{ccc|c} 0 & 3 & 0 & 1 \\ 0 & 0 & 9 & 1 \\ -2 & 2 & 1 & -1 \end{array} \right) \cong \left(\begin{array}{ccc|c} 2 & -2 & -1 & 1 \\ 0 & 3 & 0 & 1 \\ 0 & 0 & 9 & 1 \end{array} \right)$$

$$\cong \left(\begin{array}{ccc|c} 2 & -2 & -1 & 1 \\ 0 & 1 & 0 & \frac{1}{3} \\ 0 & 0 & 1 & \frac{1}{9} \end{array} \right)$$

$$\cong \left(\begin{array}{ccc|c} 2 & 0 & 0 & 1 + \frac{2}{3} + \frac{1}{9} \\ 0 & 1 & 0 & \frac{1}{3} \\ 0 & 0 & 1 & \frac{1}{9} \end{array} \right)$$

$a = \frac{8}{9}$ $b = \frac{1}{3}$ $c = \frac{1}{9}$

check, must be x^{-1}

$$1 = a + c$$

$$1 = \frac{8}{9} + \frac{1}{9} \quad \checkmark$$

2. (ch5)

(a) [50%] Use the *recipe* for higher order constant-coefficient differential equations to write out the general solution of a fifth order linear differential equation with characteristic equation $r^5 + 2r^4 + r^3 = 0$.

(b) [50%] Given $mx''(t) + cx'(t) + kx(t) = 0$ and damped spring-mass system constants $m = 2$, $c = 4$, $k = 1$, solve the differential equation [70%] and classify the answer as over-damped, critically damped or under-damped [30%].

$$\textcircled{a} \quad r^3(r^2 + 2r + 1) = 0$$

$$r^3(r+1)^2 = 0$$

$$y = (c_1 + c_2 x + c_3 x^2) e^{0x} + (c_4 + c_5 x) e^{-x}$$

$$\textcircled{b} \quad 2x'' + 4x' + x = 0$$

$$2r^2 + 4r + 1 = 0$$

$$r = -\frac{4}{4} \pm \frac{1}{4}\sqrt{16-8}$$

$$= -1 \pm \frac{1}{4}\sqrt{8}$$

$$= -1 \pm \frac{1}{2}\sqrt{2}$$

$$x(t) = c_1 e^{-t+t/\sqrt{2}} + c_2 e^{-t-t/\sqrt{2}}$$

overdamped

3. (ch5)

(a) [50%] Determine for $y'' + y''' = x \sin x + 1 + 3x^2 + \cos x$ the final form of a trial solution for y_p according to the method of undetermined coefficients. Do not evaluate the undetermined coefficients!

(b) [50%] Apply variation of parameters to write an integral formula for a particular solution $x_p(t)$ for the equation $3x'' + 15x' + 12x = f(t)$. Don't integrate!

$$\textcircled{a} \quad r^5 + r^3 = 0$$

$$r^3(r^2 + 1) = 0$$

$$y_h = c_1 + c_2 x + c_3 x^2 + c_4 \cos x + c_5 \sin x$$

$$y_1 = (d_1 + d_2 x) \cos x + (d_3 + d_4 x) \sin x$$

$$y_2 = d_5 + d_6 x + d_7 x^2$$

Fixing rule:

$$y_1 = x(d_1 + d_2 x) \cos x + x(d_3 + d_4 x) \sin x$$

$$y_2 = x^3(d_5 + d_6 x + d_7 x^2)$$

$$y = y_1 + y_2 \\ = \text{final trial sol}$$

$$\textcircled{b} \quad x'' + 5x' + 4x = \frac{f}{3}$$

$$r^2 + 5r + 4 = 0$$

$$(r+4)(r+1) = 0$$

$$x_1 = e^{-4t}$$

$$x_2 = e^{-t}$$

$$W = x_1 x_2' - x_1' x_2 = -e^{-5t} + 4e^{-5t} = 3e^{-5t}$$

$$x_p = e^{-4t} \int \frac{\bar{e}^{-t}(-f)}{9e^{-5t}} dt + e^{-t} \int \frac{\bar{e}^{-4t} f}{9e^{-5t}} dt$$

4. (ch6)

Give an example of a 3×3 matrix A with eigenvectors

$$\begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 2 \\ -5 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -3 \end{pmatrix}$$

and eigenvalues 4, 3, 7. Justify your answer.

$$P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 2 & -5 & -3 \end{pmatrix}$$

$$T = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 7 \end{pmatrix}$$

$$AP = PT \text{ defines } A.$$

$$\begin{aligned} A &= PTP^{-1} \\ &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 2 & -5 & -3 \end{pmatrix} \begin{pmatrix} 4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 7 \end{pmatrix} \begin{pmatrix} -1 & +2 & -4 \\ 0 & +3 & +5 \\ 0 & -1 & -2 \end{pmatrix}^T \cdot \frac{1}{-1} \\ &= \begin{pmatrix} 4 & 0 & 0 \\ 0 & 6 & 7 \\ 8 & -15 & -21 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -2 & 3 & 1 \\ 4 & -5 & -2 \end{pmatrix} \\ &= \begin{pmatrix} 4 & 0 & 0 \\ -12+28 & -18-35 & 6+14 \\ 8+30-84 & 45+105 & -15+42 \end{pmatrix} \\ &= \begin{pmatrix} 4 & 0 & 0 \\ 16 & -53 & -8 \\ -46 & 150 & 27 \end{pmatrix} \end{aligned}$$

- Justify: $A = PTP^{-1} \Rightarrow AP = PT \Rightarrow$ eigenpairs
are $4, \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}; 3, \begin{pmatrix} 0 \\ 2 \\ -5 \end{pmatrix}; 7, \begin{pmatrix} 0 \\ 1 \\ -3 \end{pmatrix}$

5. (ch7)

Apply the eigenanalysis method to solve the system $\mathbf{x}' = A\mathbf{x}$, given $A =$

$$\begin{bmatrix} 4 & 1 & 1 & 0 \\ 1 & 4 & 1 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & -\lambda \end{bmatrix}.$$

$$0 = \begin{vmatrix} 4-\lambda & 1 & 1 & 0 \\ 1 & 4-\lambda & 1 & 0 \\ 0 & 0 & 4-\lambda & 0 \\ 0 & 0 & 0 & -\lambda \end{vmatrix} = (-\lambda) \begin{vmatrix} 4-\lambda & 1 & 1 \\ 1 & 4-\lambda & 1 \\ 0 & 0 & 4-\lambda \end{vmatrix} = (-\lambda)(4-\lambda) \begin{vmatrix} 4-\lambda & 1 \\ 1 & 4-\lambda \end{vmatrix}$$

$$0 = (-\lambda)(4-\lambda)((4-\lambda)^2 - 1)$$

$$0 = \lambda(4-\lambda)(3-\lambda)(5-\lambda)$$

$$\boxed{\lambda = 0, 3, 4, 5}$$

$$\lambda=0: \quad \begin{bmatrix} 4 & 1 & 1 & 0 \\ 1 & 4 & 1 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \underset{\sim}{\equiv} \begin{bmatrix} 4 & 1 & 0 & 0 \\ 1 & 4 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \underset{\sim}{\equiv} \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{eigenpair } 0, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\lambda=3: \quad \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -3 \end{bmatrix} \underset{\sim}{\equiv} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \text{eigenpair } 3, \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}$$

$$\lambda=4: \quad \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -4 \end{bmatrix} \underset{\sim}{\equiv} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{eigenpair } 4, \begin{pmatrix} -1 \\ -1 \\ 0 \\ 0 \end{pmatrix}$$

$$\lambda=5: \quad \begin{bmatrix} -1 & 1 & 1 & 0 \\ 1 & -1 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} \underset{\sim}{\equiv} \begin{bmatrix} -1 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \underset{\sim}{\equiv} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \text{eigenpair } 5, \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\vec{x} = e^{0t} c_1 \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} + e^{3t} c_2 \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} + e^{4t} c_3 \begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix} + e^{5t} c_4 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$