


4800-16

Field
↓

Fix a group G and F

A representation of G

on a vector space V

is a morphism

$$\rho: G \rightarrow \underline{\text{Aut}(V)}.$$

$$\rho(g): V \xrightarrow{\sim} V$$

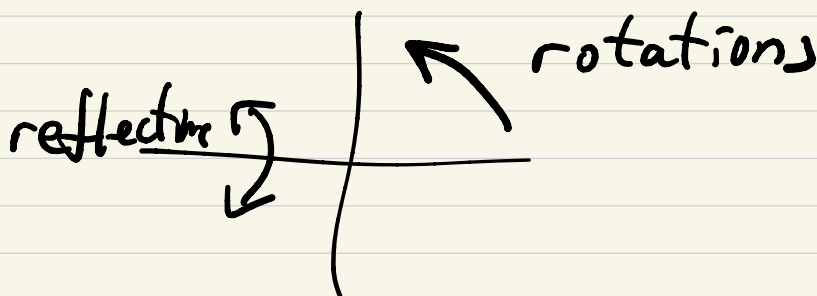
Remark: One usually writes

$$\underline{g} \cdot \underline{v} \quad \text{for} \quad \rho(g)(v)$$

\mathbb{R} -Representations of S_3

Two-dimensional (dim $V=2$)

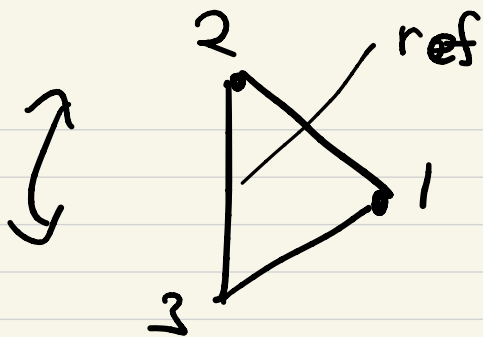
(a) Symmetries of Δ



$$\rho(123) = \text{rotation by } \frac{2\pi}{3}$$

$$= \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$$

$$\rho(132) = \text{rotation by } \frac{4\pi}{3}$$



$$\rho(23) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\rho(12) = \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{bmatrix}$$

Helpful Hint: If

G is generated by elements

g_1, \dots, g_n with relations, then to specify a representation, need

only to specify

$$\rho(s_1) = A_1$$

$$\rho(s_2) = A_2$$

⋮

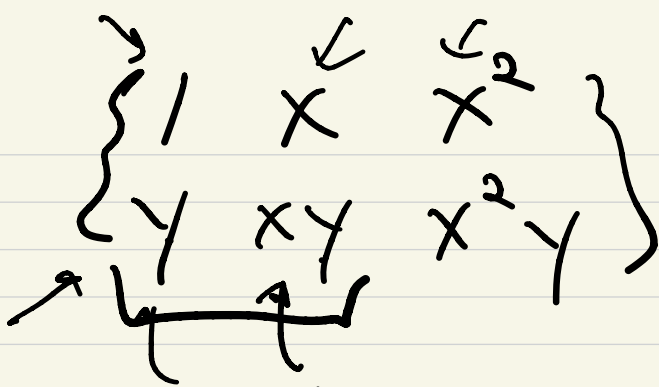
$$\rho(s_n) = A_n$$

and check the relations on A_i

Example: $S_3 \cong D_6$ is generated
by $g_1 = \underline{(1\ 2)}$ and $g_2 = \underline{(2\ 3)}$

with relations:

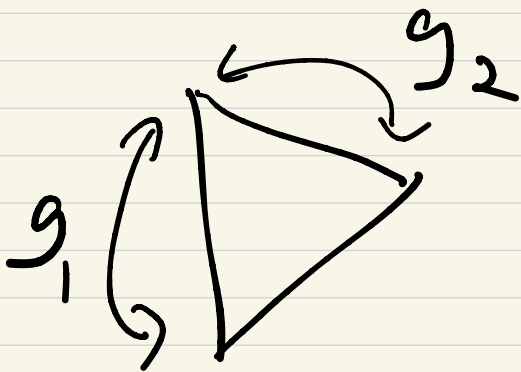
$$g_1^2 = 1, g_2^2 = 1, (g_1 g_2)^3 = 1$$



$$\underline{g_2} \quad \underline{g_1}$$

$$g_1 g_2 = x$$

$$x^3 = 1$$



$$g_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$g_2 = \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$

$$\begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$S_1 S_2 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & +\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$$

$$= \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix} \quad \begin{array}{l} \text{rotation} \\ \text{by } 4\pi/3 \end{array}$$

Another representation of S_3

$$\rho(12) =$$

$$\rho(g_1) = \begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix} = A_1$$

$$\rho(g_2) =$$

$$\rho(g_2) = \begin{pmatrix} 1 & 0 \\ 1 & -1 \end{pmatrix} = A_2$$

Check: $A_1^2 = I_2 = A_2^2 \quad (A_1 A_2)^3 = I_2$

$$\begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix}^2 = \begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \checkmark$$

$$\begin{pmatrix} 1 & 0 \\ 1 & -1 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \checkmark$$

$$\begin{pmatrix} -1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix} = B$$

$$B^3 = \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix}^2 = \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix}$$
$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \checkmark$$

Example 2. \mathbb{R}^1

Two one-dim'l representations

• Trivial: $g \cdot r = r$

$$\rho(g) = 1 \quad \forall g$$

• Sgn $\sigma \cdot r = \text{sgn}(\sigma) \cdot r$

$$\text{sgn}: \mathbb{S}_2 \rightarrow \underbrace{\{\pm 1\}}_{\mathbb{Z}/2\mathbb{Z}}$$

Symmetry of \mathbb{R}

$\underline{G}\text{-Rep}_F$ category of
representations of G
on F -vector spaces

objects: $\rho: G \rightarrow \text{Aut}(V)$
 (V, ρ)

morphisms:
given $\rho_1: G \rightarrow \text{Aut}(V_1)$
 $\rho_2: G \rightarrow \text{Aut}(V_2)$,

then a morphism is a G -linear
map $f: V_1 \rightarrow V_2$; $f(g \cdot v) = g \cdot f(v)$

$$f(gv) = g \cdot f(v)$$

$$\forall g \in G, v \in V$$

$$\underline{f(\rho_1(g) \cdot v)} = \underline{\rho_2(g)} \cdot \underline{f(v)}$$

$$\rho(g): \underset{\substack{\vee \\ \vee}}{V} \longrightarrow V$$

Examples:

$\rho_1 =$ trivial rep. on \mathbb{R}^1

$\rho_2 =$ sgn rep. on \mathbb{R}^1

$$f = \text{id}: (\mathbb{R}^1, \rho_1) \rightarrow (\mathbb{R}^1, \rho_2)$$

is not G -linear.

$$f(r) = r$$

$$f(\underline{c(2)} \cdot r) = f(r) = r$$

$$c(2) \cdot f(r) = \text{sgn}(2) \cdot r = -r$$

$$(f_1 \circ f_2)(gv)$$

$$= f_1(g \cdot f_2(v))$$

$$= g(f_1 \circ f_2)(v) \quad \checkmark$$

\mathbb{R} -linear maps compose.

$$(V, \rho) \xrightarrow{\text{id}} (V, \rho)$$

$$\text{id}: V \rightarrow V \text{ gives}$$

Example: Suppose

(V, ρ) is a G -Rep,

and $U \subset V$ is a subspace

such that

$$g \cdot u \in U \quad \forall g \in G, u \in U.$$

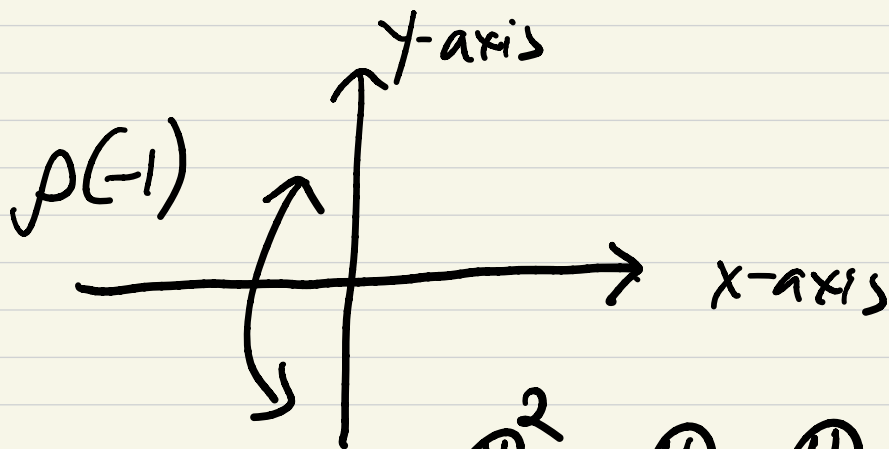
Then U is an invariant subspace of V , and

(U, ρ) is a G -Rep.

Example: $G = \{\pm 1\}$

$$\rho: G \rightarrow \text{Aut}(\mathbb{R}^2)$$

$$\left\| \begin{array}{l} \rho(1) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ \rho(-1) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \end{array} \right\|$$



$$\mathbb{R}^2 = \mathbb{R} \times \mathbb{R}$$

Two invariant subspaces:

$$\mathbb{R} \times 0 \subset \mathbb{R} \times \mathbb{R} \quad \text{x-axis}$$

$$0 \times \mathbb{R} \subset \mathbb{R} \times \mathbb{R} \quad \text{y-axis}$$

$$\left(\begin{array}{c} \mathbb{R} \times 0 \\ \downarrow \\ \mathbb{R} \end{array} \right) \quad \rho: \{\pm 1\} \rightarrow \mathbb{R} \times 0$$

trivial

is trivial.

$$\left(\begin{array}{c} 0 \times \mathbb{R} \\ \downarrow \\ \mathbb{R} \end{array} \right) \quad \left\| \begin{array}{l} \rho(1)v = v \\ \rho(-1)v = -v \end{array} \right\|$$

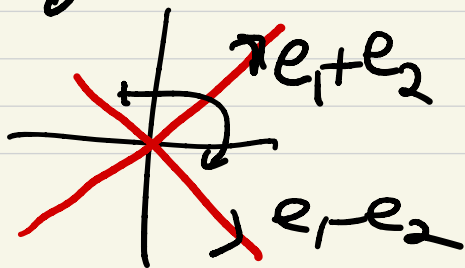
Permutation rep: of S_n

$$\rho: S_n \rightarrow \text{Aut}(\mathbb{R}^n)$$

$$\rho(\sigma): \mathbb{R}^n \rightarrow \mathbb{R}^n \quad \text{is defined by:}$$

$$\rho(\sigma)(e_i) = e_{\sigma(i)}$$

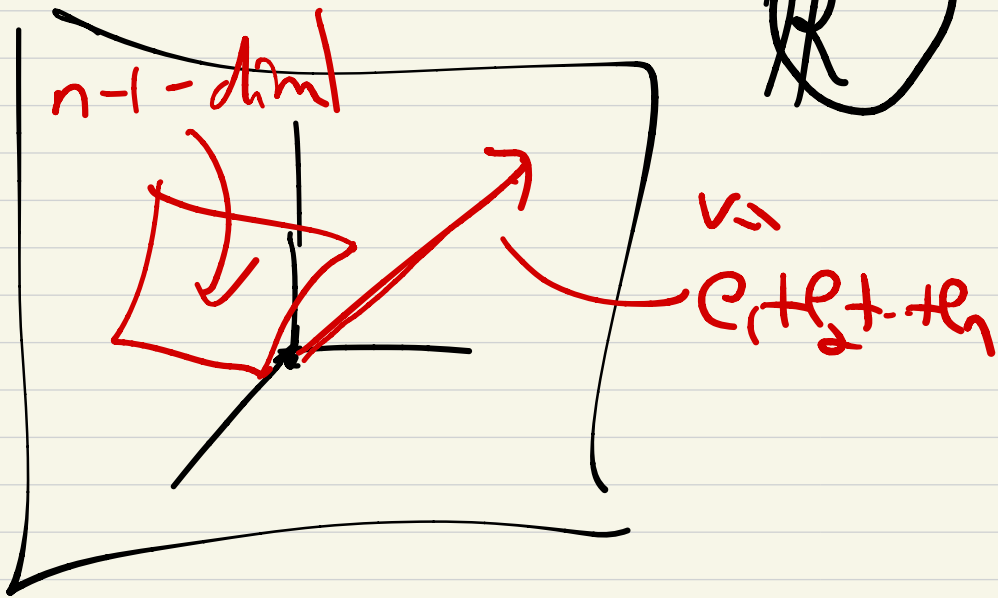
$$S_2: \left\| \begin{array}{l} \rho(1) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \\ \rho(12) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \end{array} \right\|$$



$$\rho(12)(e_1 + e_2) = e_2 + e_1$$

$$\rho(12)(e_1 - e_2) = e_2 - e_1 = -(e_1 - e_2)$$

The permutation rep of S_n has two invariant subspaces:



$\rho(\sigma)(v) = v$. Fixed!
one-diml subspace (\mathcal{U}_1 , trivial)

$$U_{n-1} = \langle \underbrace{e_1 - e_2}, e_2 - e_3, \dots, e_{n-1} - e_n \rangle$$

$$\underline{p(\sigma)} \cdot (e_i - e_{i+1}) = e_{\sigma(i)} - e_{\sigma(i+1)}$$

$$= e_j - e_k$$

$$= (e_j - e_{j+1}) + (e_{j+1} - e_{j+2}) + \dots$$

Explicitly for \mathcal{L}_3

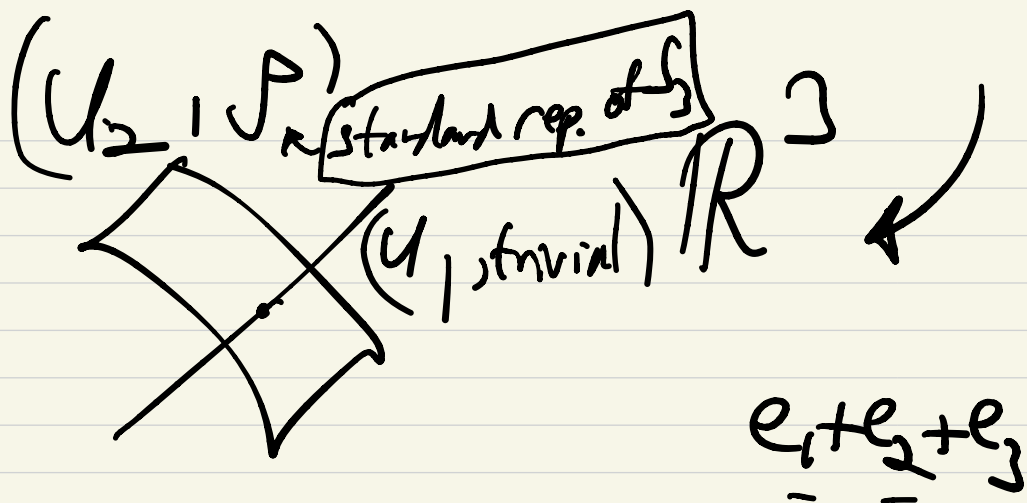
$$U_2 = \left\langle \begin{array}{c} \downarrow \downarrow \\ e_1 - e_2, \\ \uparrow \quad \nearrow \\ v_1 \quad v_2 \end{array} e_2 - e_3 \right\rangle \subseteq \mathbb{R}^3$$

$$\rho(1 \ 2)(v_1) = e_2 - e_1 = -v_1$$

$$\rho(1 \ 2)(v_2) = e_1 - e_3 = v_1 + v_2$$

$$\rho(1 \ 2) = \begin{bmatrix} -1 & 1 \\ 0 & 1 \end{bmatrix} \quad \underline{\text{matrix!}}$$

$$\rho(2 \ 3) = \begin{bmatrix} 1 & 0 \\ 1 & -1 \end{bmatrix} \quad \underline{\underline{\quad}}$$



$(U_1 = \mathbb{R}^1, \text{trivial})$

Def: A representation

(V, ρ) is irreducible if

the only invariant subspaces of

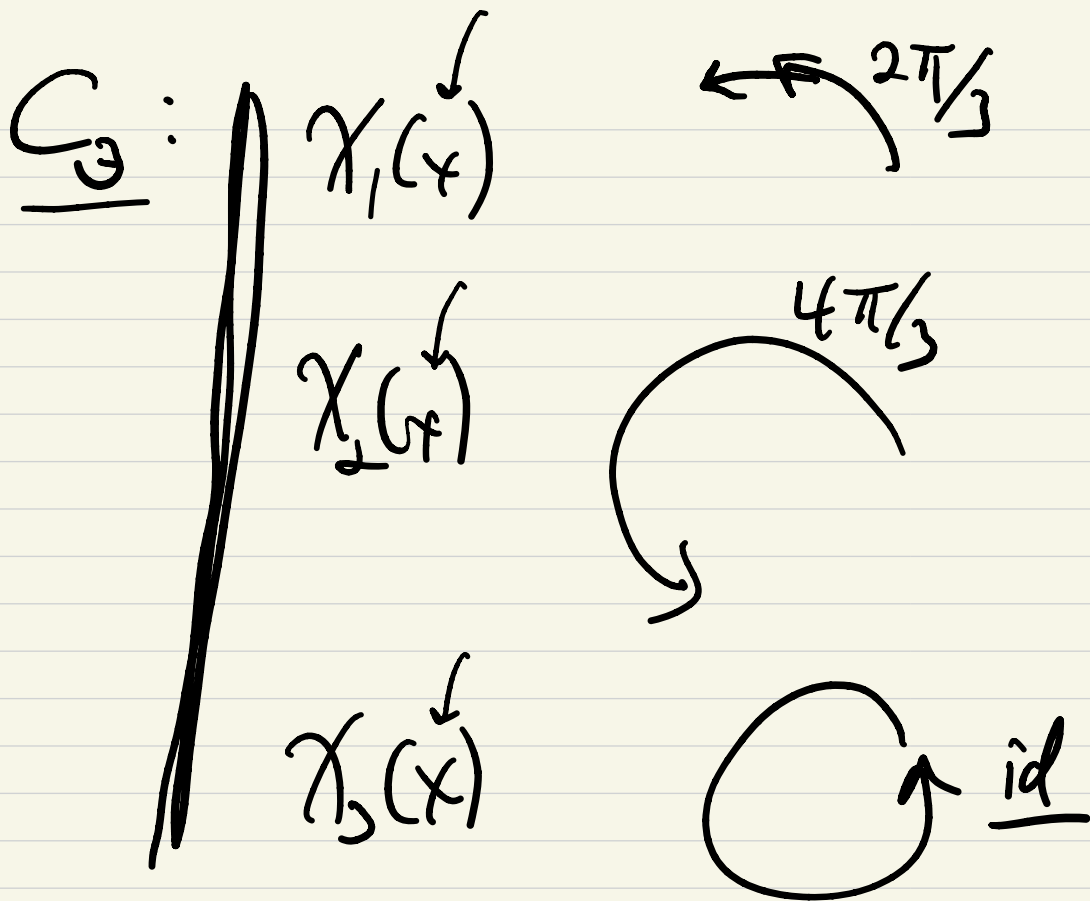
V are $\langle 0 \rangle, V$.

Example:

- All one-dim'l reps. of a group. are irreducible.
- One-dim'l complex reps
- $\chi: G \rightarrow \mathbb{C}^* = \text{Aut}(\mathbb{C}^1)$ are called characters.

Eg. Let $C_n = \{1, x, \dots, x^{n-1}\}$ cyclic gp.

Then $\chi_m: C_n \rightarrow \mathbb{C}^*$ are the characters $\chi_m(x) = \zeta^m$; $\zeta = e^{2\pi i/n}$.



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$$\chi_1(x) = 3, \chi_1(x^2) = 3^2 \dots$$

$$\chi_2(x) = 3^2, \chi_2(x^2) = 3^4, \dots$$